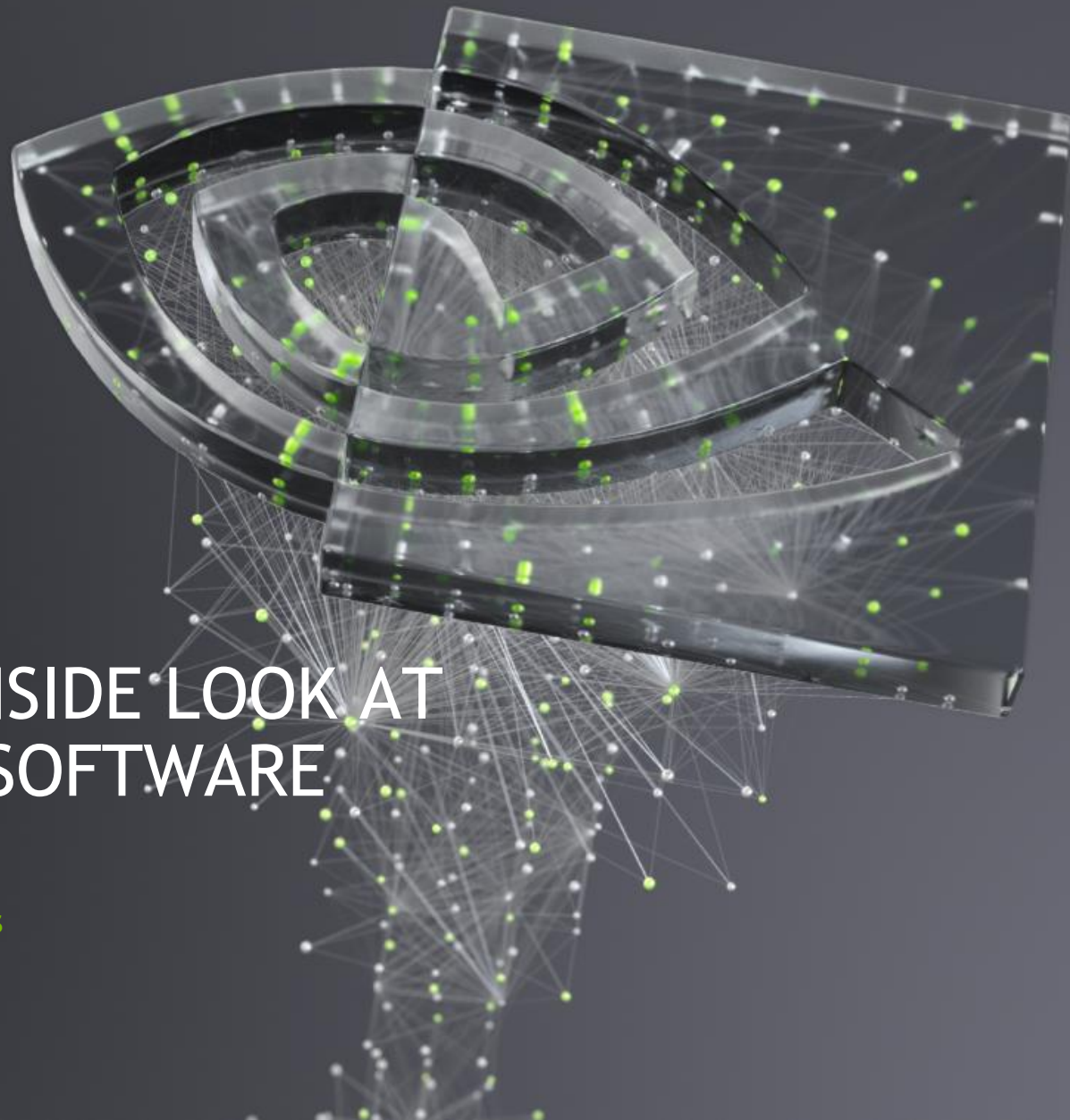




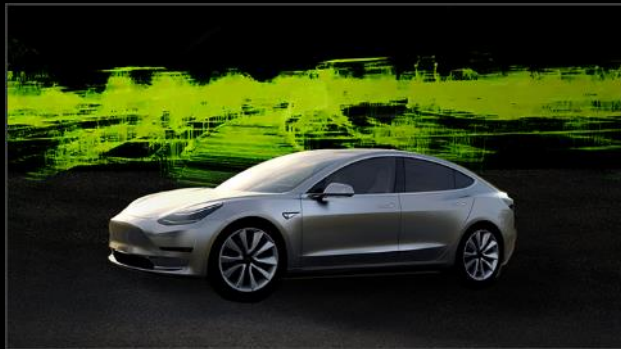
# NVIDIA DRIVE LABS: AN INSIDE LOOK AT AUTONOMOUS VEHICLES SOFTWARE

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April 1, 2020



# \$10T TRANSPORTATION INDUSTRY



1B Cars on the Road



20M Rides per Day



300M Trucks — 1.2T Miles per Year



500K Buses in Operation

# AI IS THE SOLUTION TO SELF-DRIVING



Perception



Reasoning



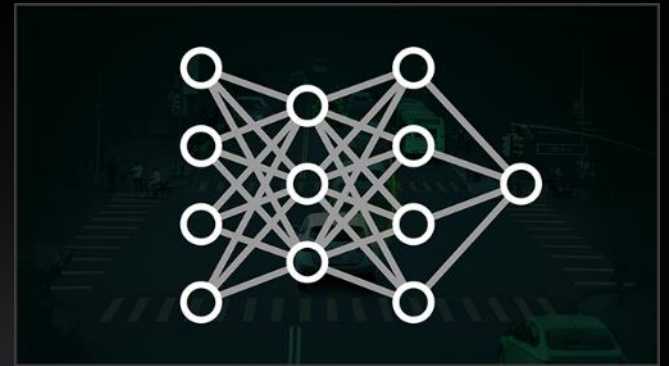
Driving



HD Map



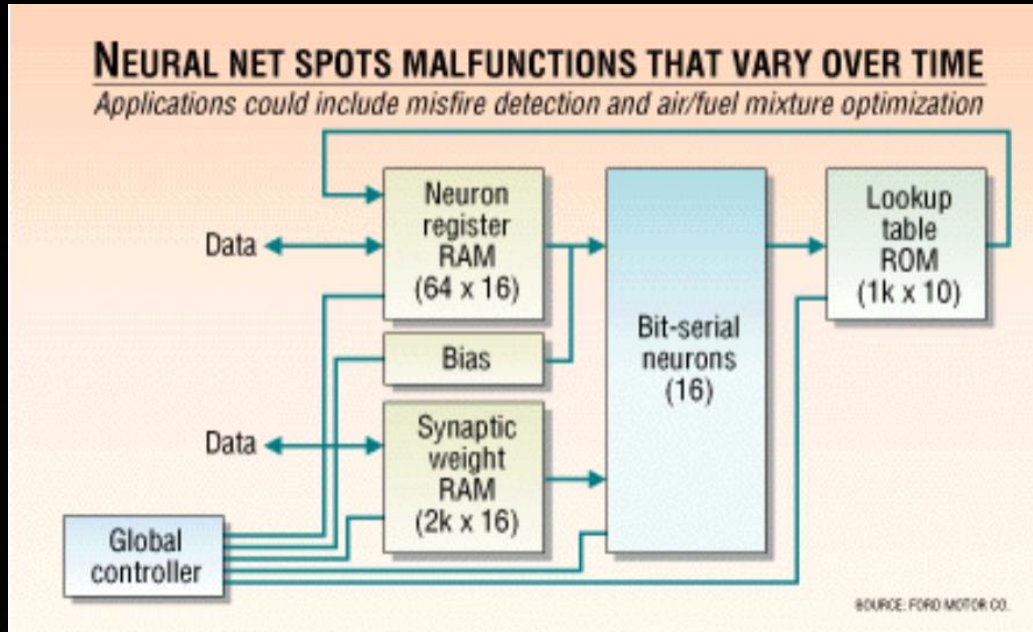
Mapping



AI Computing

# NEURAL NETWORKS IN AUTOMOTIVE

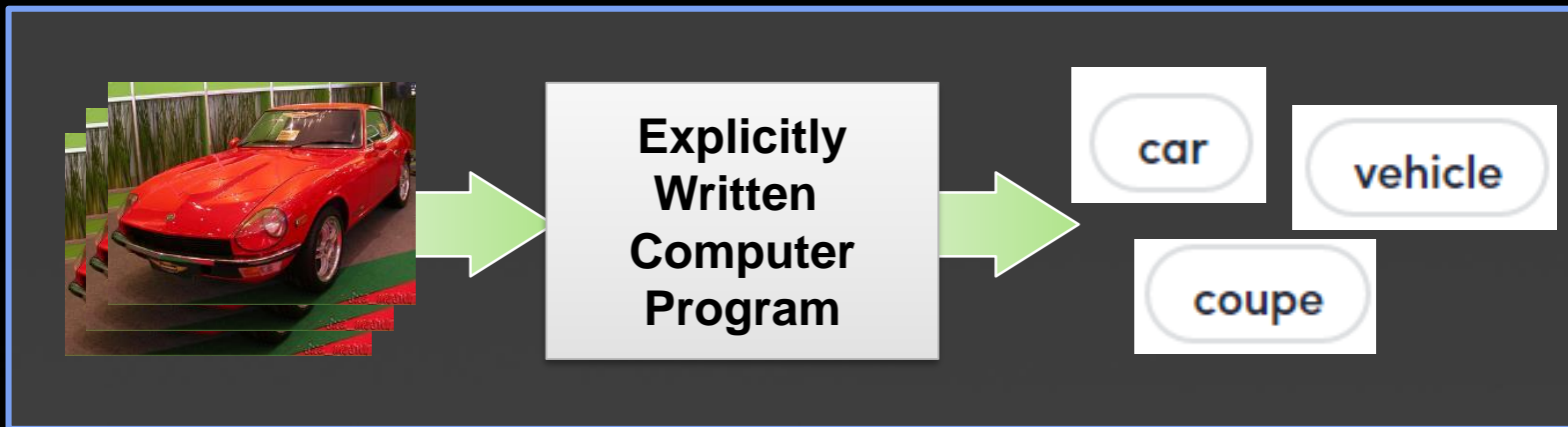
## Neural Networks are Not New in Automotive



- From the early 1990s
- Applied to:
  - Misfire detection
  - Air/fuel mixture optimization
  - Dynamic suspension control
- Ford licensed neural network IP from JPL in 1998 for powertrain

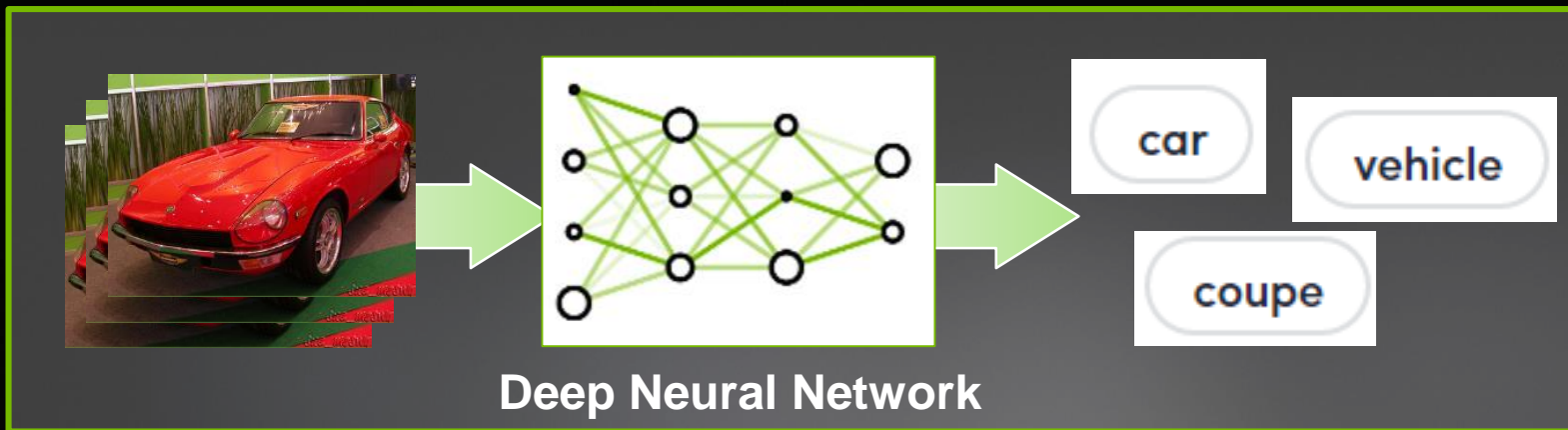
# HOW DOES A DNN WORK?

Learning from Examples



## Traditional Approach

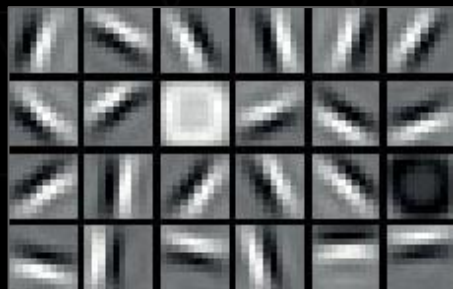
- Time consuming
- Error prone
- Not scalable to new problems



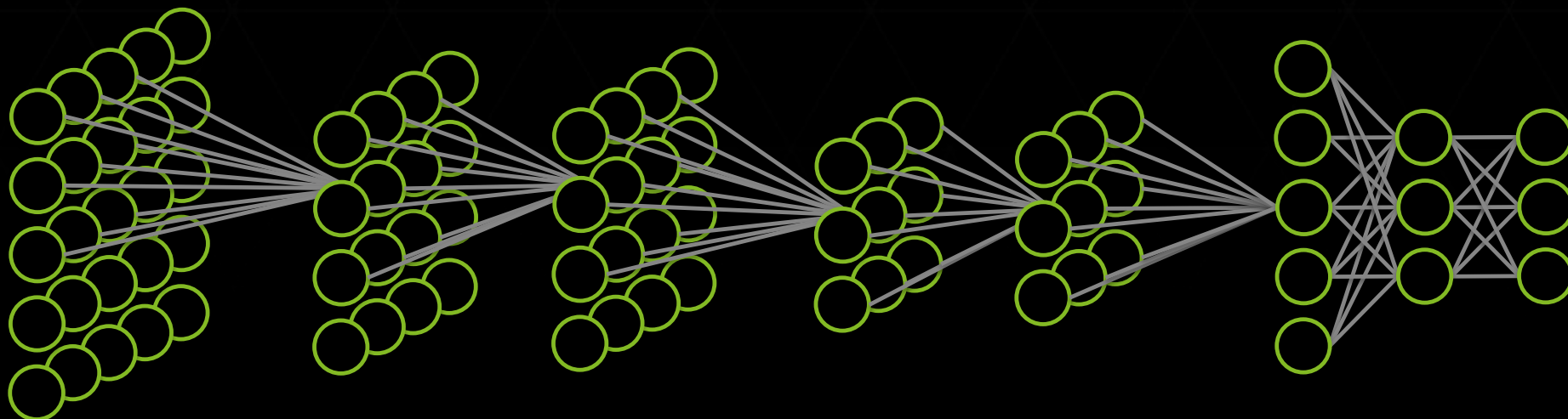
## Deep Learning Approach

- Learn from data
- Easily extended
- Speedup with GPUs

# HOW A DEEP NEURAL NETWORK SEES



Image



"Audi A7"

# AV CHALLENGES & PAIN POINTS

50-Car Fleet Driving 6 Hours/Day Generates 1.6PB Each Day



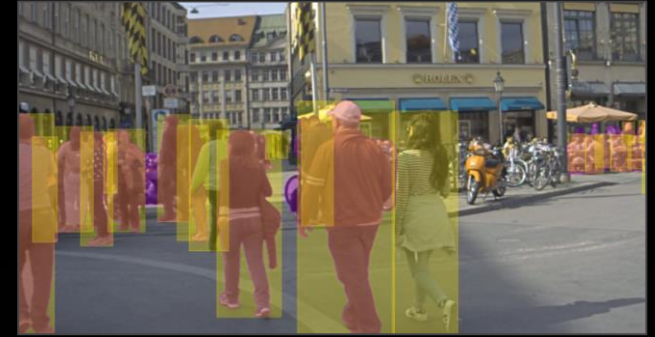
## Ingestion

1.6PB/day needs to be transported, encoded, and stored.



## Curation

Billions of frames.  
Find the 10% that are useful.



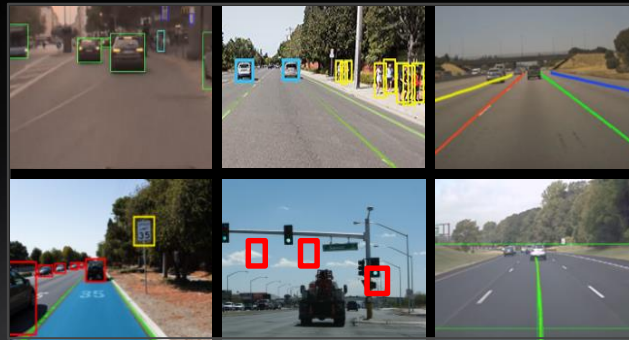
## Labeling

Manage 1,000+ workers with 50+ projects.  
Ensure quality every frame.



## Training

20+ models. 100s Engineers,  
Optimize models w/ 50+ parallel experiments.



## Replay

Test against 1,000s hours of sensor data.  
Repeat daily.



## Simulation

Drive millions of miles.  
Find the most critical scenarios to test.

# BUILDING AI IS HARD

Every neural net needs to handle 1,000s of conditions and geolocations.



Vehicles



Pedestrians



Bicycles



Animals



Hazards



Day



Twilight



Night



Lamps



Backlit



Clear



Cloudy



Rain



Fog



Snow



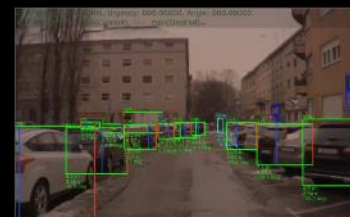
Perception



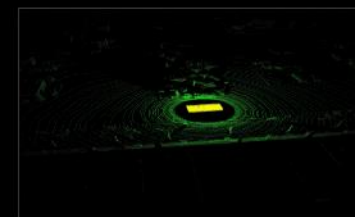
Free Space Perception



Distance Perception



Weather



LIDAR Perception



Camera-based Mapping



Camera Localization to HD Map



LIDAR Localization to HD Map



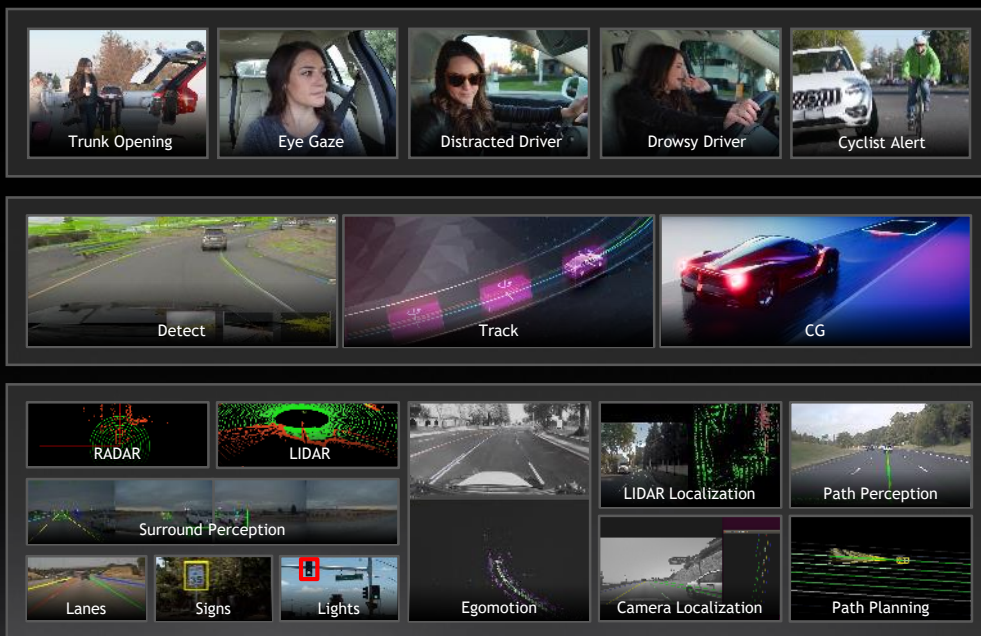
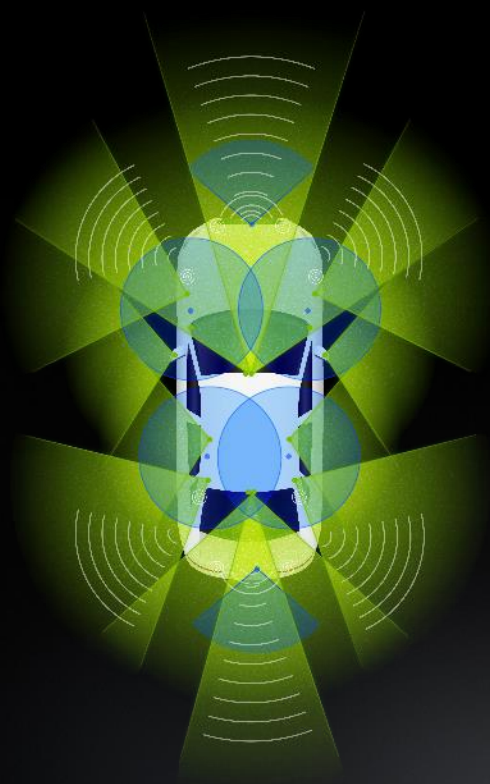
Path Perception



Scene Perception

# FUTURE CAR IS SOFTWARE-DEFINED

Powerful and Efficient AI, CV, AR, HPC | Rich Software Development Platform  
Functional Safety | Open Platform



Assistive

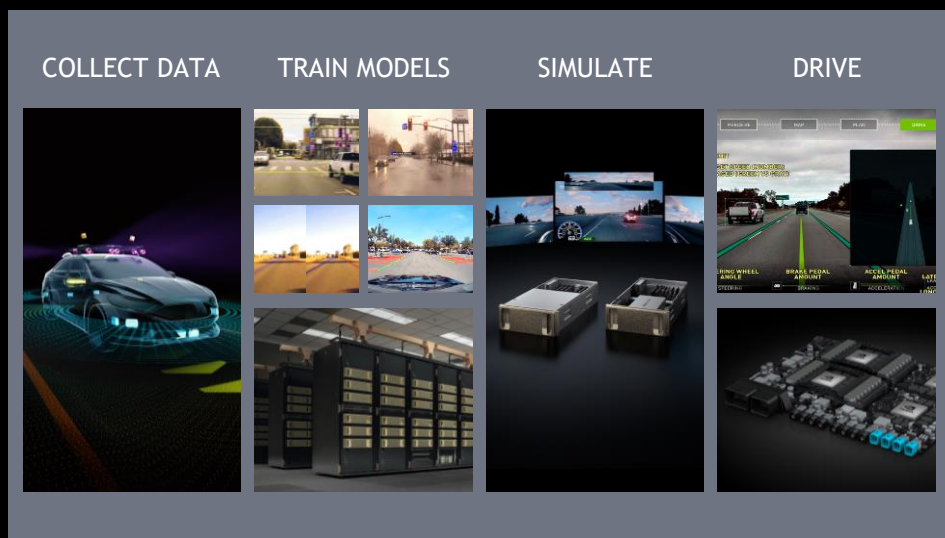
Augmented

Autonomous

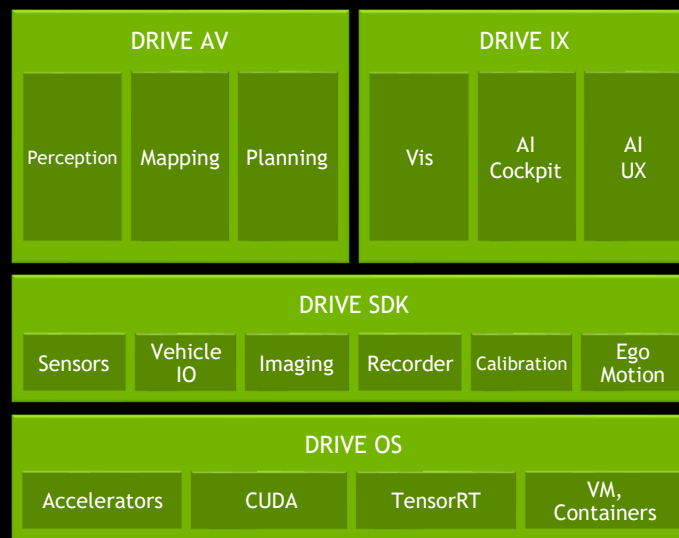


Safe

# NVIDIA DRIVE — SOFTWARE-DEFINED AV PLATFORM



End-to-End Infrastructure



Open Software Platform



Pre-Trained Models

# ADDITIONAL RESOURCES

NVIDIA Drive Labs website:

<https://www.nvidia.com/en-us/self-driving-cars/drive-labs/>

NVIDIA Drive Labs Youtube playlist:

<https://www.youtube.com/watch?v=T7w-ZCVVUgM&list=PLZHnYvH1qtOYkEIUMqYiHDMrGTPnqRhSr>

NVIDIA AI Podcast episode:

<https://soundcloud.com/theaipodcast/nvidias-neda-cvijetic-explains-the-science-behind-self-driving-cars-ep-108>

