

# DYNAMIC DIFFUSE GLOBAL ILLUMINATION

WITH RAY-TRACED IRRADIANCE FIELDS

Morgan McGuire | April 2019





#### DIRECT + DIFFUSE GI

DIRECT + DIFFUSE GI + VOLUMETRIC

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**Diffuse GI:** Glossy GI: Throughput:

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1.0 ms/frame 1.1 ms/frame 1.5 Grays/s

#### DIRECT + DIFFUSE GI + VOLUMETRIC + GLOSSY GI + MATERIALS

GeForce RTX 2080 Ti @ 1080p

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BEFORE: NO GLOBAL ILLUMINATION

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- SALIN

**BEFORE: CLASSIC PROBES** 

EX CX D

#### AFTER: NEW DYNAMIC DIFFUSE GI

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END CAD

MOVING CAMERA, GEOMETRY, AND LIGHTS ...

Shit CA

# Dynamic Diffuse Global Illumination with Ray Traced Irradiance Fields **OVERVIEW**

1 ms/frame dynamic diffuse global illumination on *everything* (static, dynamic, transparent, volumetric, forward, deferred)

Runs everywhere, best quality on RTX. Constant performance, varying indirect light latency across platforms.

Uses existing engine data paths, no bake time, minimizes leaks and noise. Good artist workflow.

Fresh out of the lab after six years of R&D with academic collaborators [Mara 2012, Crassin 2013, Evangelakos 2015, Donow 2016, McGuire 2017, Wang 2019, Majercik 2019]

Working with partners on game integration and art team feedback now.

No patents on the algorithm. No SDK or licensing.

### AGENDA

- 1. Global Illumination Overview
- 2. Glossy GI Best Practices
- 3. The Diffuse GI challenge
- 4. New Dynamic Diffuse Gl
- 5. Engine Integration
- 6. Examples & Demo

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straight from the emitter



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straight from the light emitter



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#### **Global illumination:**

bounces off at least one other surface



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Direct illumination:

straight from the light source

#### Global illumination:

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#### Visibility:

unobstructed line of sight primary surface: visibility to camera direct shadow: visibility to emitter G.I. "visibility": any two points



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straight from the light source

#### Global illumination:

bounces off at least one other surface

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unobstructed line of sight primary surface: visibility to camera direct shadow: visibility to emitter G.I. "visibility": any two points

### **GLOSSY REFLECTION**



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(e.g., specular, microfacet, GGX, etc.)

- reflects off the surface
- only visible near mirror angle

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- scatters just below the surface
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#### Today: Dynamic Diffuse Global Illumination with correct Visibility



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# GLOSSY GI STATE OF THE ART

#### State of the Art GLOSSY G









### **GLOSSY GI**







**1. Ray Trace** Trace and shade perfect mirror rays at full resolution X, ½ resolution Y

**2. Blur** Bilateral filter into MIPs, respecting edges

**3. Sample** Sample in screen-space based on primary roughness and total reflection distance

1.1 ms/frame in our simple demo, including BVH update

### **GLOSSY GI IMPLEMENTATION**

Heavy lifting is all in your existing forward or deferred shader, which runs on ray hits. Uses shadow maps, regular materials, etc. so no special shading code for the base implementation.

We use half resolution only *vertically* because that gives a good performance to quality tradeoff on high-end hardware. Most reflections are on floors, and they'll be blurred vertically in screen space anyway.

Stretch to full resolution and bilateral blur into MIP-maps. Gaussian kernel, normal & depth weighting. Expand out into untraced areas so that trilinear fetches don't hit black. MIP generation is about 0.1 ms of total time.

When rendering the camera view, compute MIP level to gather from smoothness, distance to primary surface + distance to reflected surface. Produces proper distance fading.

To improve quality: address flicker. final-frame TAA can help and hurt. Use everything you know about filtering and flickering *inside* the glossy shader: MIP bias, bump to roughness, TAA/FXAA on the glossy trace, LOD.

Can optimize down to about 0.5 ms/frame (see Battlefield V): Combine with screen-space ray tracing and environment maps, use geometric and material level of detail, apply checkerboarding plus upsampling, DLSS.

# DIFFUSE GI STATE OF THE ART

# Real-Time Diffuse GI STATE OF THE ART

Baked light maps

Light propagation volumes

Sparse voxel cone tracing

**Denoised ray tracing** 

Baked irradiance probes

#### **IRRADIANCE PROBES**









Image Credits: Geomerics and Ninja Theory, https://unity3d.com/learn/tutorials/topics/graphics/probe-lighting, https://docs.unrealengine.com/en-us/Engine/Rendering/LightingAndShadows/IndirectLightingCache, https://unity3d.com/learn/tutorials/topics/graphics/probe-lighting
### **LIGHT & SHADOW LEAKS**







#### **LIGHT & SHADOW LEAKS**





[Iwanicky 2013]







Image Sources: https://forums.unrealengine.com/development-discussion/content-creation/18712-need-help-how-to-fix-the-light-under-walls, https://answers.unrealengine.com/questions/336484/light-leaking-problem-solid-geometry.html, https://www.worldofleveldesign.com/categories/udk/udk-lightmaps-03-how-to-fix-light-shadow-lightmap-bleeds-and-seams.php

### **NEW: DYNAMIC DIFFUSE GI** WITH RAY-TRACED IRRADIANCE FIELDS

### **UPGRADING PROBES WITH VISIBILITY**

**Classic Probes:** Fast to sample, noise-free, work with characters and transparents, parameterization-free, already in your engine.

Upgrade:

Leaks: Store visibility information to prevent light and shadow leaking.

Dynamic: Asynchronous GPU ray trace directly into low resolution probes, gather blending

Workflow: Art cost is in avoiding leaks and bake time. Real-time + no leaks fixes worflow.



### **PROBE PLACEMENT**

#### Grid

Optionally optimize around static geo [Chajdas 2011, Donow 2016, Wang et al. 2019, Unity] Artists may override placement

#### Cascades

 $32 \times 4 \times 32 = 4$  k probes around the camera that update frequently.

Coarse cascades in space and time to scale out to big scenes.



[Kaplanyan and Dachsbacher 2010]



[Asirvatham and Hoppe 2005]

### **DATA STRUCTURE**

6x6-texel probe

#### R11G11B10F Irradiance





RG16F Depth: (radius, radius<sup>2</sup>)

#### 16x16-texel probe

32x32-probe scene layer

5 MB GPU RAM for 8k Probes

### **DYNAMIC DIFFUSE GI**

Independent of framerate and screen resolution







#### 1. Ray Trace

Trace and shade packed rays from active probes. (Pack into the bottom of the Glossy GI ray pass) **2. Blend** Blend irradiance and depth into probes. Duplicate probe border texels for fast bilinear. **3. Sample** Volumetric sample based on 3D position, visibility, and normal.

Uses previous iteration for shading: infinite bounce GI.

### **ACCURATE & NOISE FREE**





#### **ACCURATE & NOISE FREE**

#### Path Tracing



#### Dynamic Diffuse GI



#### REALISTIC

Direct Illumination Only



+ Dynamic Diffuse GI



### REALISTIC

Direct Illumination Only

+ Dynamic Diffuse GI



### REALISTIC

#### Direct Illumination Only

#### + Dynamic Diffuse GI



#### **DYNAMIC LIGHTING**

#### Afternoon

Evening













### DYNAMIC GEOMETRY

### **DYNAMIC GEOMETRY**















Before: Classic Probes







### After: Dynamic Diffuse GI



#### Light leak

#### Correct

#### Before: Classic Probes



#### After: Dynamic Diffuse GI



#### Light leak



### LIMITATIONS

Self-shadow bias must be tuned to geometry thickness

Light crossfades in time under dramatic changes

Blurrier than light maps (use screen-space AO for contact shadows)

## **ENGINE INTEGRATION**







# Encoding Visibility RADIAL GAUSSIAN DEPTH



#### Encoding Visibility

### **RADIAL GAUSSIAN DEPTH**



### Encoding Visibility RADIAL GAUSSIAN DEPTH

#### Mean:

 $\mu = \sum r / n$ 

#### **Standard Deviation:**

 $\sigma = \operatorname{sqrt}(\sum (r - \mu)^2 / n)$ = sqrt((\sum r^2) / n - \mu^2)

Each probe texel stores ( $\sum r, \sum r^2$ )

Irradiance blurs over a cosine-weighted hemisphere in a gather pass.

Blur depth over a *power*-cosine to capture variation but retain some sharpness.



// float3 n = shading normal, X = shading point



// float3 n = shading normal, X = shading point, P = probe location



// float3 n = shading normal, X = shading point, P = probe location

```
float4 irradiance = float4(0);
for (each of 8 probes around X) {
    float3 dir = P - X;
    float r = length(dir);
    dir *= 1.0 / r;
```

// smooth backface
float weight = (dot(dir, n) + 1) \* 0.5;



// float3 n = shading normal, X = shading point, P = probe location

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```

```
// adjacency
```

weight \*= trilinear(P, X);



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float4 irradiance = float4(0);
for (each of 8 probes around X) {
      float3 dir = P - X;
      float r = length(dir);
      dir * = 1.0 / r;
     // smooth backface
      float weight = (dot(dir, n) + 1) * 0.5;
     // adjacency
      weight *= trilinear(P, X);
      // visibility (Chebyshev)
      float2 temp = texelFetch(depthTex, probeCoord).rg;
      float mean = temp.r, mean2 = temp.g;
      if (r > mean) {
        float variance = abs(square(mean) - mean2);
        weight *= variance / (variance + square(r – mean));
```



// float3 n = shading normal, X = shading point, P = probe location

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float4 irradiance = float4(0);
for (each of 8 probes around X) {
      float3 dir = P - X;
      float r = length(dir);
      dir * = 1.0 / r:
     // smooth backface
      float weight = (dot(dir, n) + 1) * 0.5;
     // adjacency
     weight *= trilinear(P, X);
     // visibility (Chebyshev)
      float2 temp = texelFetch(depthTex, probeCoord).rg;
     float mean = temp.r, mean2 = temp.g;
      if (r > mean) {
        float variance = abs(square(mean) - mean2);
        weight *= variance / (variance + square(r - mean));
      irradiance += sqrt(texelFetch(colorTex, probeCoord) * weight;
```


# **READING IRRADIANCE**

```
// float3 n = shading normal, X = shading point, P = probe location
// threshold = low-perception threshold (around 0.2)
X += bias * (n - viewVector)
float4 irradiance = float4(0);
float4 irradianceNoCheb = float4(0);
for (each of 8 probes around X) {
```

```
// smooth backface
float weight = square( (dot(dir, n) + 1) * 0.5 ) + 0.2;
```

```
// adjacency
weight *= trilinear(P, X) + 0.001;
```

```
// visibility (Chebyshev)
```

```
if (weight < threshold)
weight *= square(weight) / square(threshold);</pre>
```

```
return lerp(square(irradianceNoCheb.rgb * (1.0 / irradianceNoCheb.a)),
square(irradiance.rgb * (1.0 / irradiance.a)),
saturate(irradiance.a));
```



# **PROBE PACKING**



Pack XZ squares, layer in Y

Including border texels for fast bilinear:

Depth: 16x16 RG16F = 1024 bytesIrradiance: 6x6 R11G11B10F = 144 bytes= **1168** bytes/probe



















# **MORE GI OPTIMIZATIONS**

Scale down to lower-end hardware by reduce number of probes updated each frame or decreasing ray count and increasing hysteresis. Similar to what Enlighten did for their probes

Use fewer probes vertically for typical environments. Most illumination changes are due to walls. If you have two probes per room vertically that may be fine.

Order diffuse probe rays to capture coherence.

Pack diffuse probe rays and glossy into a single ray shader. Having more work in a single pass allows the scheduler to fill the machine and do more optimizations. This will get even faster over time with driver updates.

Compute ray derivatives for mip bias to reduce flicker and increase cache coherence. Force higher roughness on indirect bounces.

Clamp maximum radiance on indirect shading so that tiny reflections into light sources won't become fireflies.

Use fewer rays for diffuse in bright situations. Dim/high contrast is the case where rays get different results and you need more to avoid low-frequency flicker.

Use simplified shaders on indirect rays: no shadow map filtering, simpler BRDF model, no volumetrics.

Blurred mirror reflections are more stable than blurred stochastic reflections.

## The Ultimate Optimization **STREAMING GI**





Dynamic Diffuse GI

Avoids leaks to decrease artist workload while increasing visual quality

1 ms/frame, 4.5 MB per cascade
Scales down to XboxOne by reducing update frequency
Scales up to 4k, 240 Hz, and VR

Dynamic lights and geometry, forward, deferred, transparent, volumetric

# **MORE INFORMATION**

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After the conference:

Blog Post: https://morgan3d.github.io/articles/2019-04-01-ddgi

Technical Paper: Dynamic Diffuse Global Illumination with Ray-Traced Irradiance Fields, Zander Majercik (NVIDIA), Jean-Philippe Guertin (University of Montreal), Derek Nowrouzezahrai (McGill University), and Morgan McGuire (NVIDIA), JCGT 2019

Thanks to Dylan Lacewell, Mike Mara, Dan Evangelakos, Sam Donow, and Corey Taylor for their work on the implementation infrastructure.



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