

Accelerating AV Productization with AI

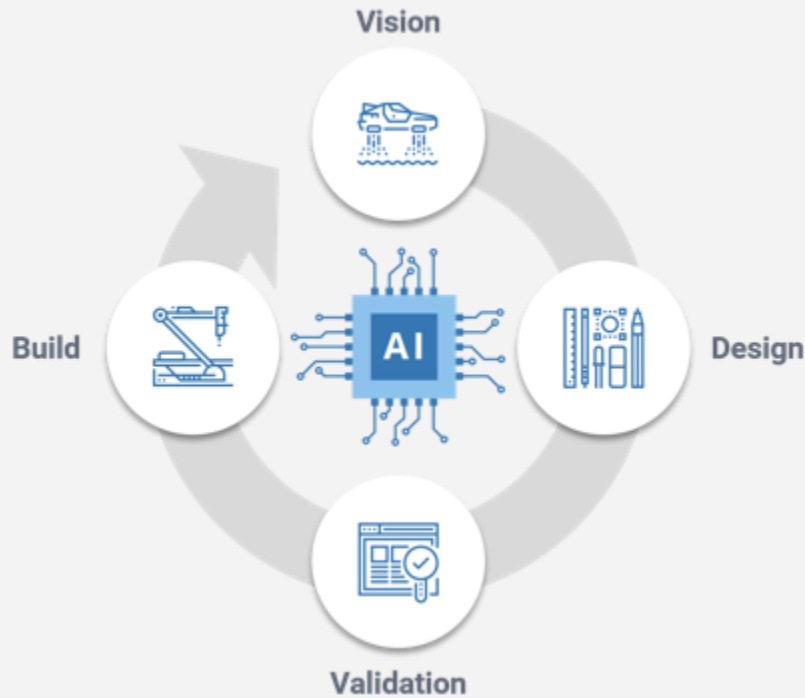
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Agenda

- Vision
- Challenges
 - AI Solutions in Design
 - AI Solutions in Validation
- Solution Convergence

AI-driven Design and Validation Solutions



Vision



Design Challenges

Challenge: Mission Driven Engineering

Mission left to the **User**



Traditional Vehicles



People



Delivery



Taxi Driver

Mission engineered within the **System**

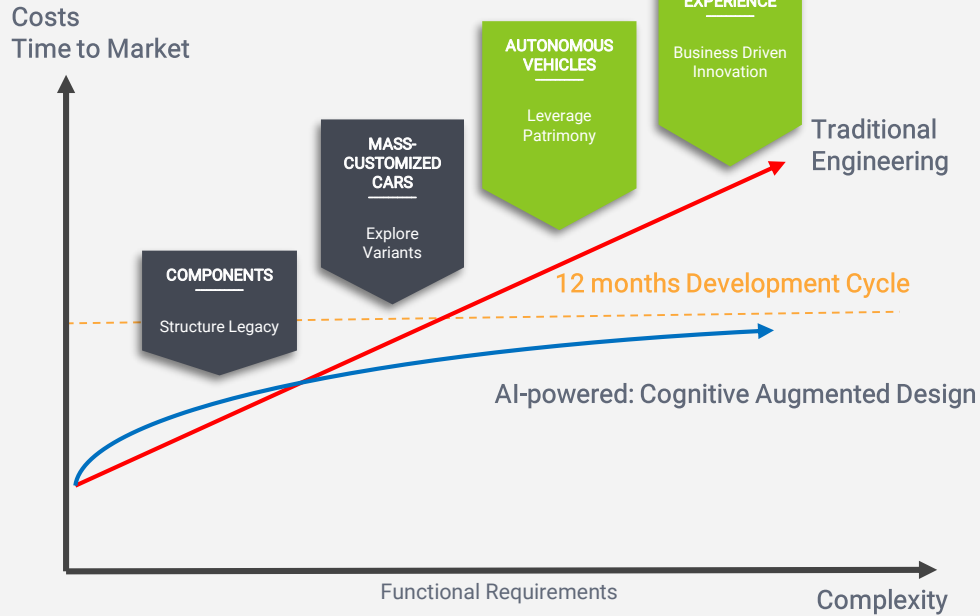


3x more System Requirements

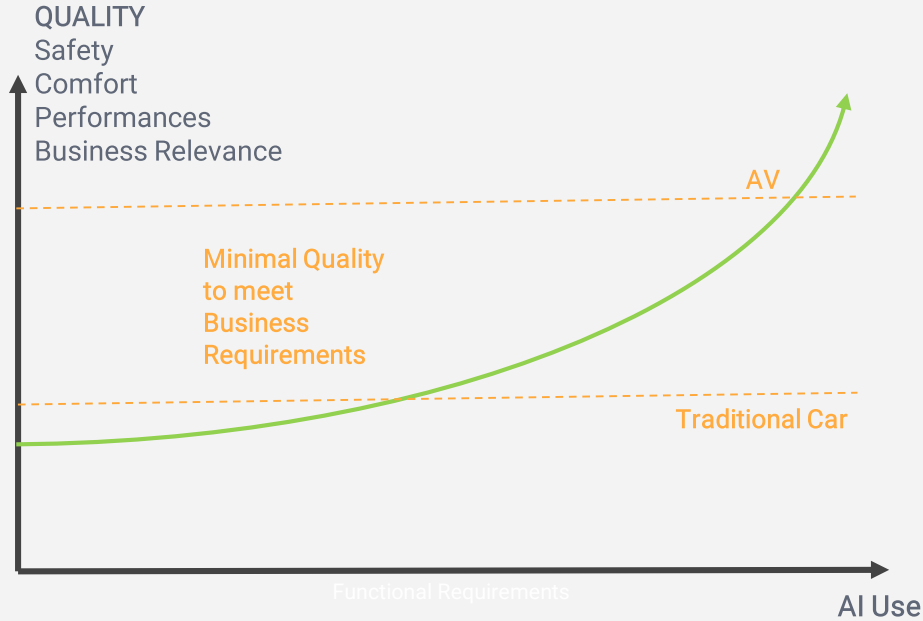
Autonomous Systems



Costs vs Complexity – AI is making it possible



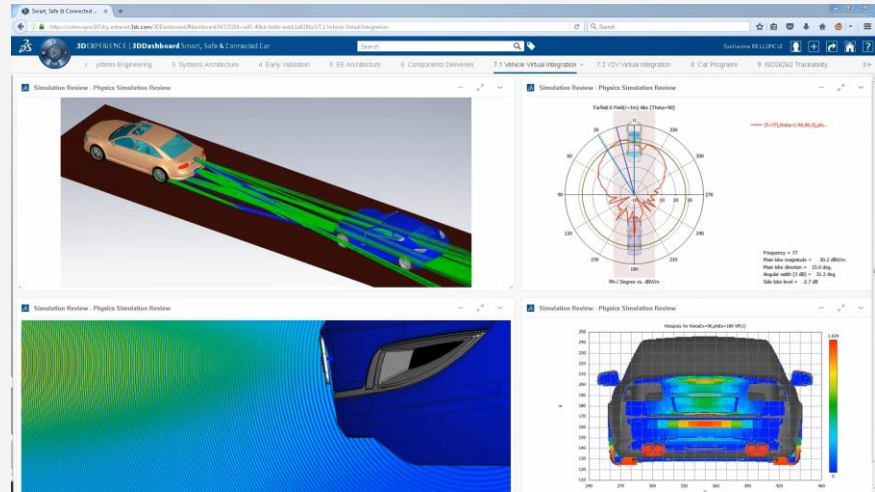
AI is bringing Quality



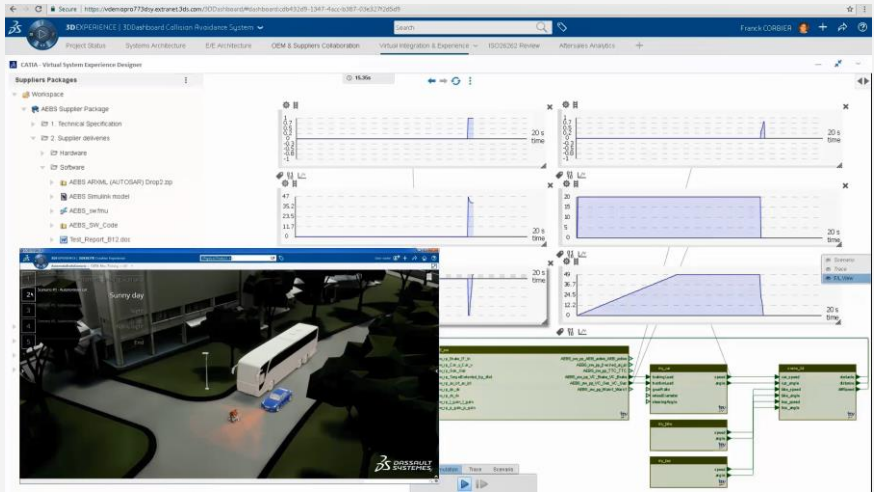
More than 100.000 Design Variants to explore to find the Optimal Tradeoff

Challenge 2: Physically Exact

Multidiscipline, Multiphysics, Multiscale



Sensors optimization



Consistent System Experience Validation

AI Solutions for Design

Learning from Patrimony

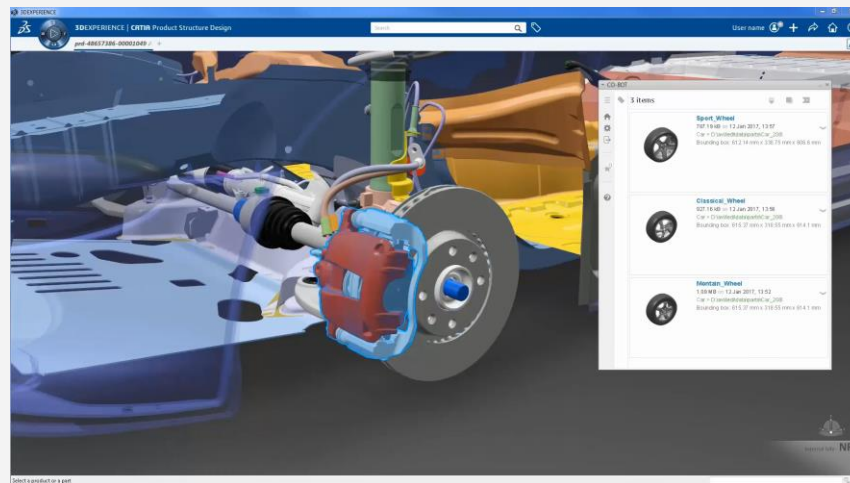


3DEXPERIENCE

Function Driven
Generative Design

Context Sensitive
Automated Assembly

Parameters space
Exploration



Model Based System
Engineering

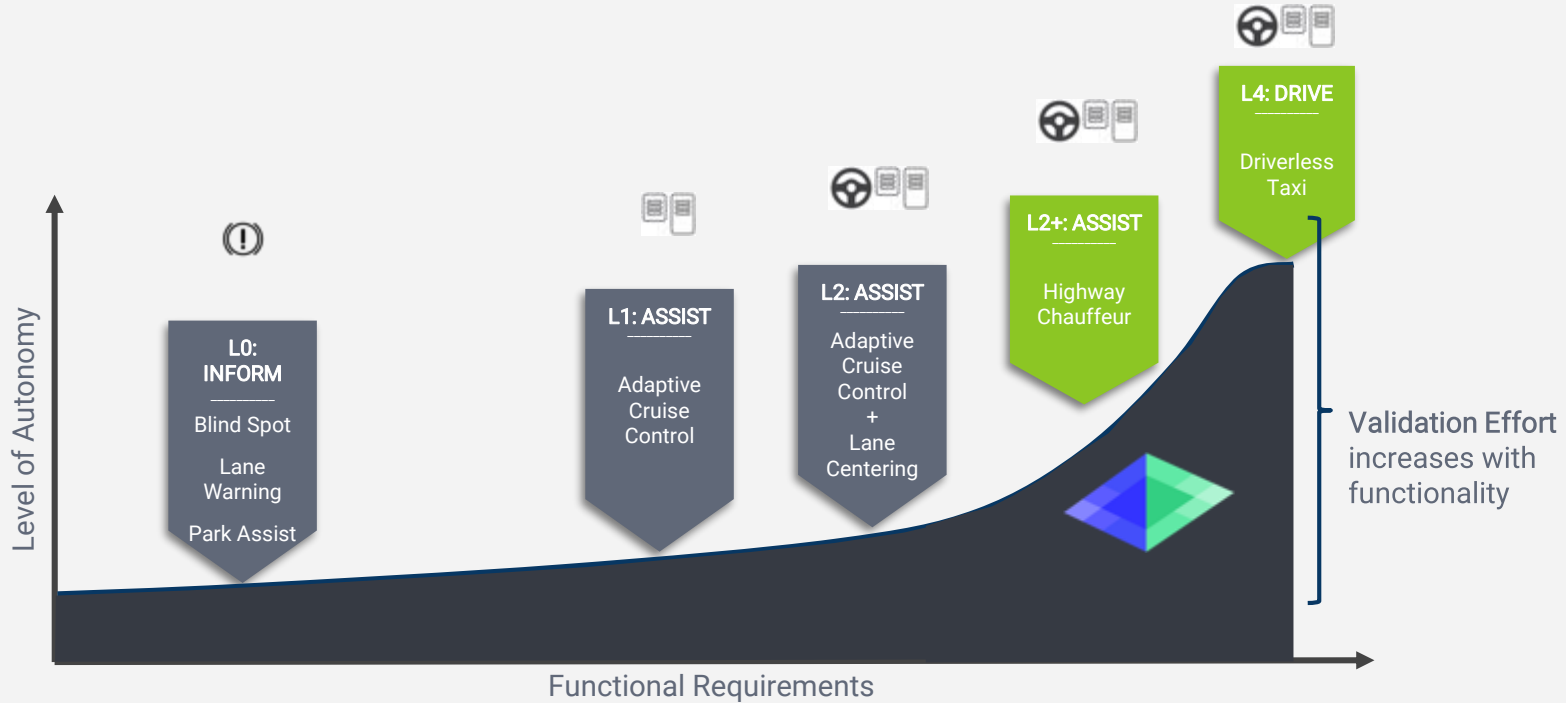
Performance
Tradeoff

Validation Challenges

AV Tech Has Had Some **Unplanned Setbacks**



Challenge #1: Scale



Challenge #1: Scale - Need Vs. Actual

The Need: 11B*

Actually driven: 16M (0.15%)

*Rand corporation

Challenge #2: Realism

REAL LIFE

Realism

100%

Scalable



VS.

SIMULATION

Realism

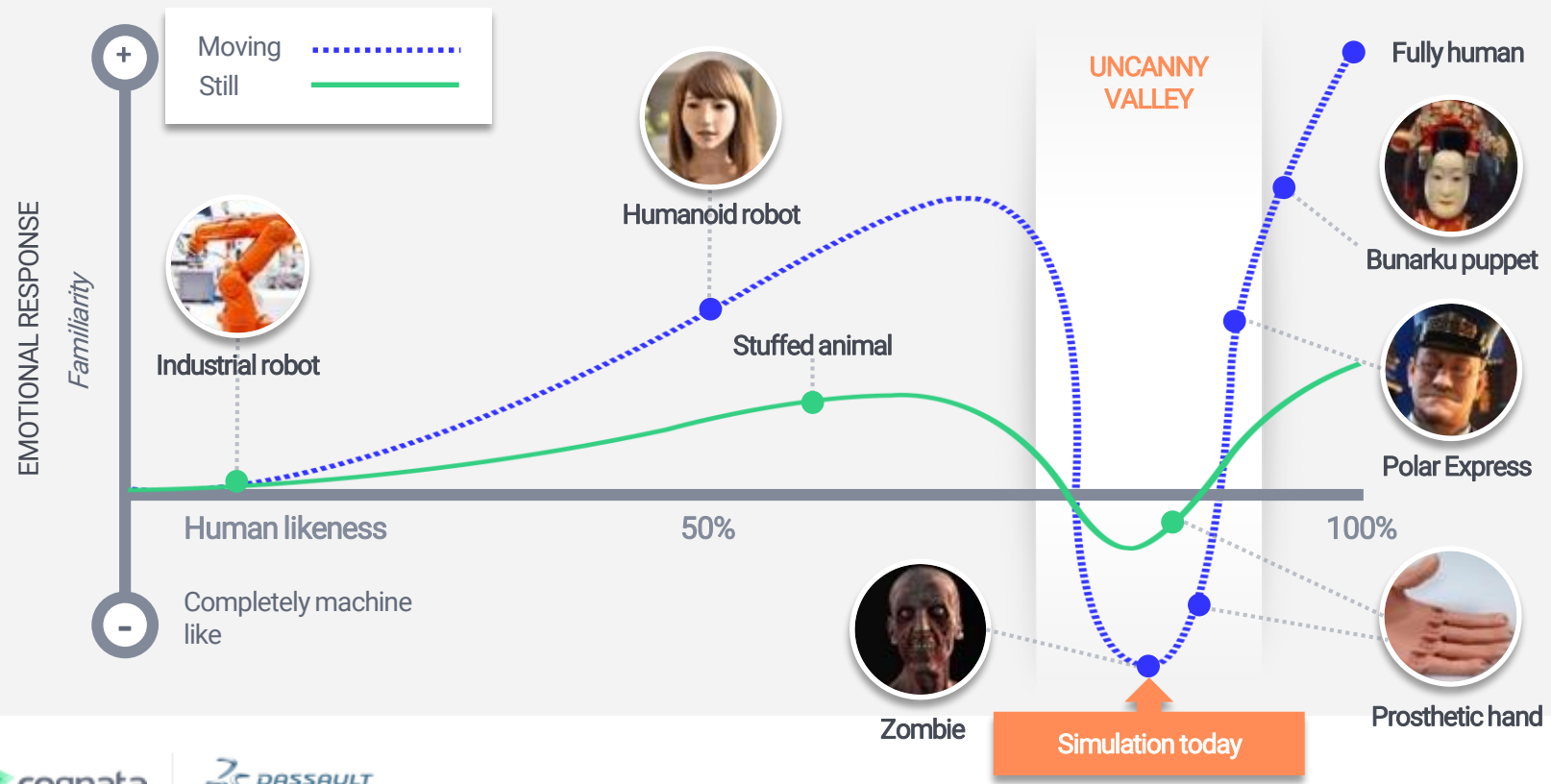
??%

Scalable

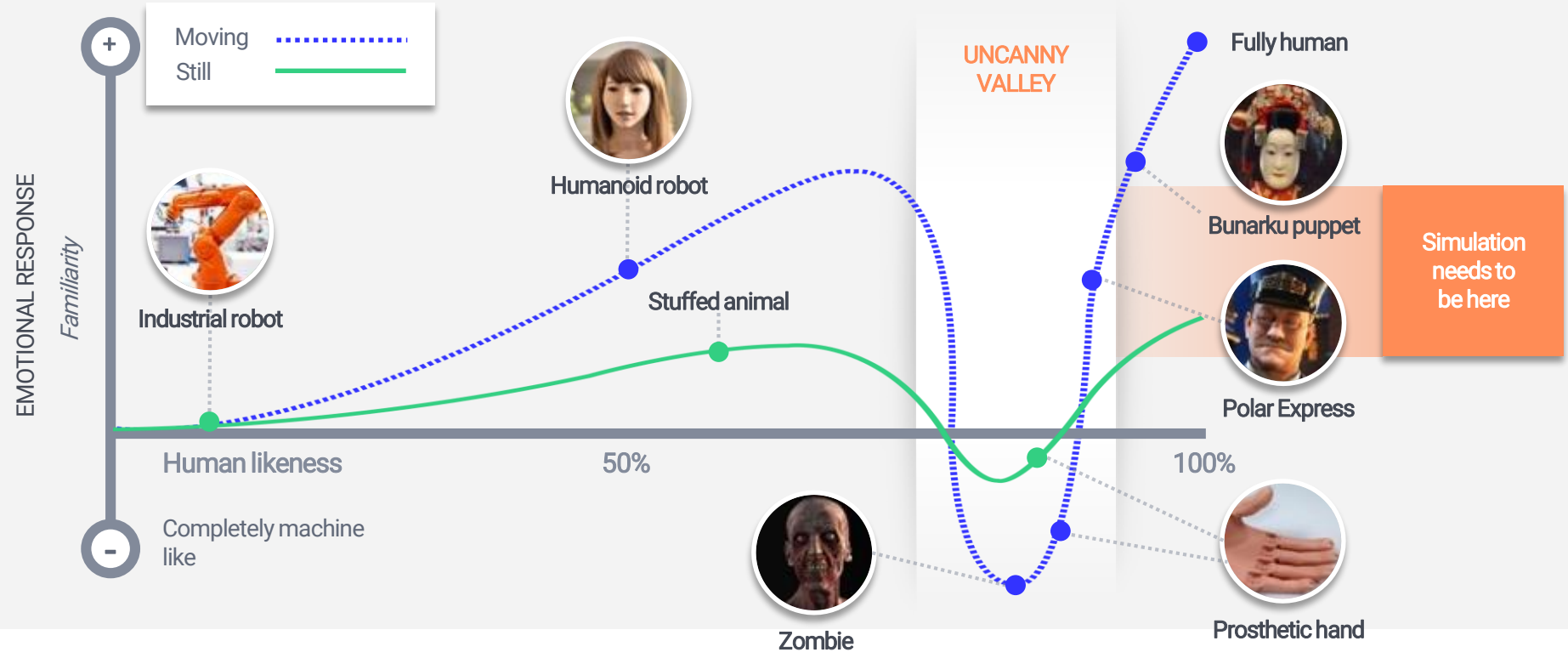


We need a realistic simulation
for a meaningful coverage

Realism - Uncanny Valley (Masahiro Mori, 1978)



Realism - Uncanny Valley



The animation **solution**

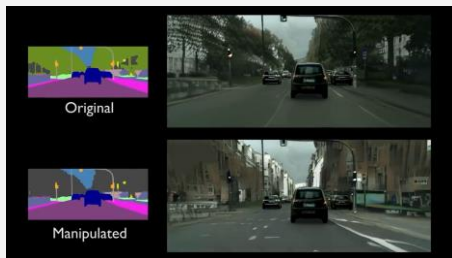
“An animator cannot capture all of reality . Instead he picks 3 or 4 distinct elements and exaggerate them.”

- Walt Disney

The image shows the classic signature logo of Walt Disney, written in a cursive, handwritten style.

AI based methods for Realism

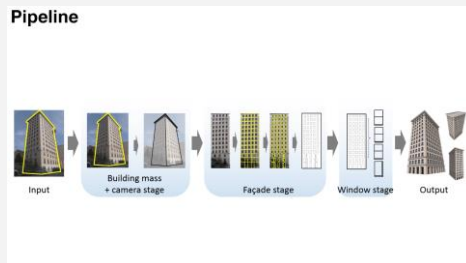
Nvidia & MIT - Video (Labels) to Video Synthesis – Wang et. al. 2018



END TO END

Realistic, not consistent

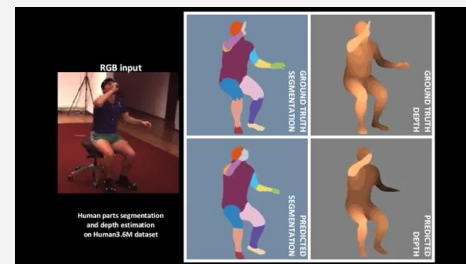
Procedural Modeling of a Building from a Single Image – Nishida et al, 2018



LAYERED APPROACH

Consistent, Not scalable (Manual)

Learning from Synthetic Humans – Varol et. al 2017



LAYERED APPROACH

Consistent, Not scalable (Variations)

Challenge #2: Realism conclusions

REAL LIFE

VS.

SIMULATION

- DNN transfer functions \approx Realism
- Isolated layers brings better results than End to End
- *Data sources should be wide (crowd sourced)*

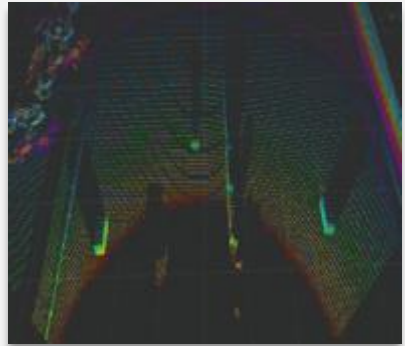
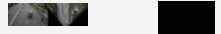
Cognata - 4 Technology layers



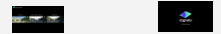
STATIC



DYNAMIC



SENSING



CLOUD & ANALYTICS



A Combined Solution

Design and Validation Converge



The screenshot displays two web browser windows. The left window is the 3DEXPERIENCE dashboard, showing a navigation menu with categories like '3DEXPERIENCE Marketplace', '3DEXPERIENCE Roles & Apps', and 'Dassault Systèmes Communities'. The main content area shows a 'Systems Traceability' diagram with nodes for 'Vehicle Requirements', 'CCRB Scenarios', 'Systems Architecture', and 'ICAM-RADAR-LIDAR-GPS'. The right window is the Cognata dashboard, featuring a 'Dashboard' with a 'Simulation results' table and a 'Details' view for a specific simulation scenario.

Name	Created	Sim
[Scenario:Sc1a78bed7e4460be06b579f] - Up Lombard St. - ODRB - Yellow electric car - MORNING - CLEAR - clear - morning	1/2/19, 11:50 AM	1
[Scenario:Sc1a78bed7e4460be06b579f] - Up Lombard St. - ODRB - Yellow electric car - MORNING - CLEAR - clear - morning	12/21/18, 3:06 PM	1
[Scenario:Sc1a6cd507e4460be06b429] Highway - ODRB - Black SUV - NIGHT - FOG - fog - evening	12/21/18, 2:10 PM	1
[Scenario:Sc1a6cd507e4460be06b439] Highway - ODRB - Black SUV -	12/21/18,	

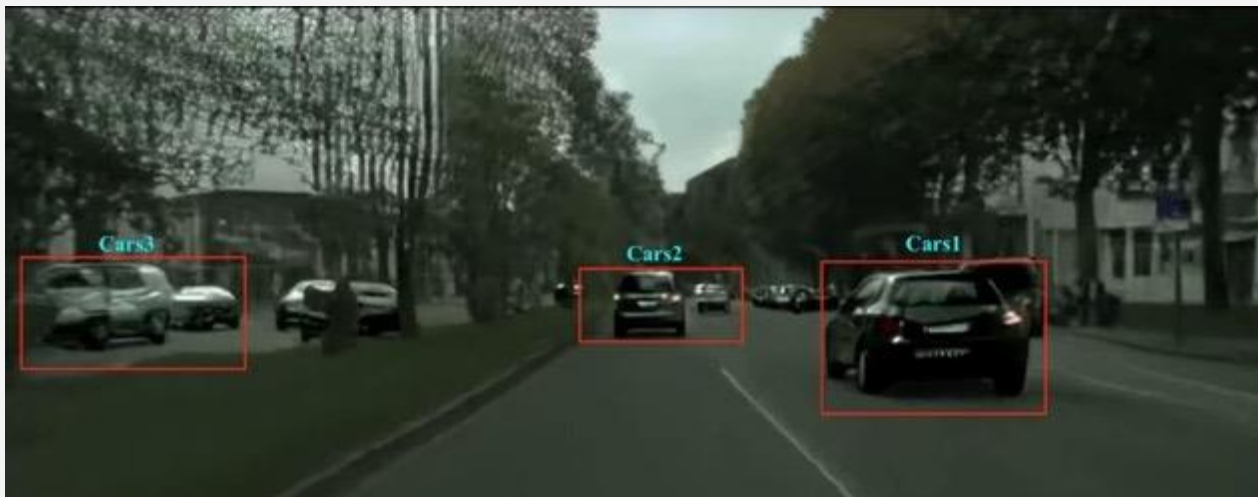
Better Together

- Tests and designs together
- Validation base directly from requirements
- Smart coverage

- Autonomous vehicles brings
 - New designs and use cases
 - Large scale validation challenge
- AI is a key to get Autonomous vehicles in a safe and cost effective way
- A platform solution to manage, design and validate is the needed solution

Thank You!

End to end limitations



The Problem: Not consistent, overfeat

Buildings reconstruction conclusions

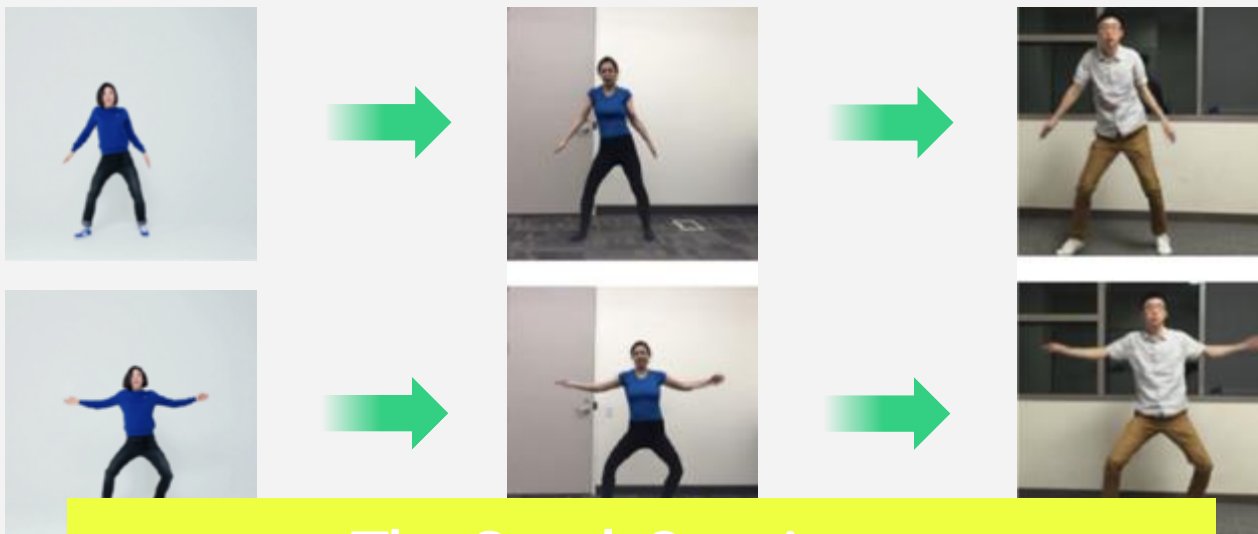


The Good: Consistent, Procedural

The Bad: Not practical

Learning pose - Conclusions

This the most advanced way of learning moving objects.



The Good: Consistent

The Bad: Not scalable