

NVIDIA®

Next Generation Games with Direct3D 10

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Motivation



Direct3D 10 is Microsoft's next graphics API
 Driving the feature set of next generation GPUs

Many new features

New programmability, generality

New driver model

Improved performance

Cleaned up API

Improved state handling. Almost no caps bits!





Short review of DX10 pipeline and features

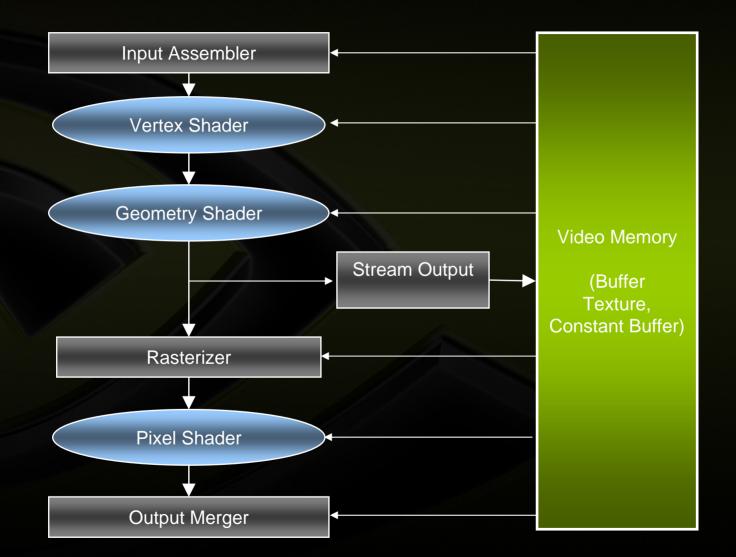
Effect Case Studies

- Curves
- Silhouette detection
- Metaballs

Conclusions

Direct3D 10 Pipeline





Direct3D 10 Features Overview



Common shader core
 Integer operations in shaders

Geometry shader

Stream out

Texture arrays

Generalized resources

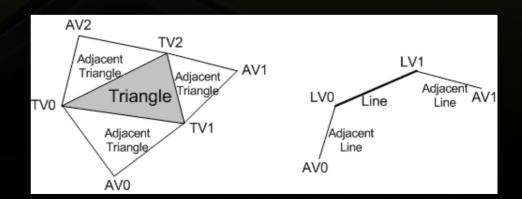
Improved instancing support

Geometry Shader



Brand new programmable stage

- Allows GPU to create (or destroy) geometry
- Run after vertex shader, before setup
- Input: point, line or triangle
 - Also new primitive types with adjacency information
- Output: points, line strips or triangle strips
 - Can output multiple primitives
- Allow us to offload work from CPU



Geometry Shader Applications



Shadow volume generation

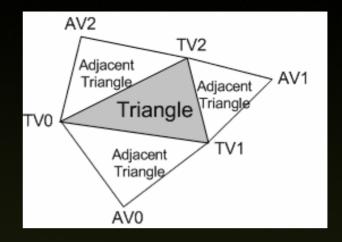
- Fur / fin generation
- Render to cubemap
- GPGPU

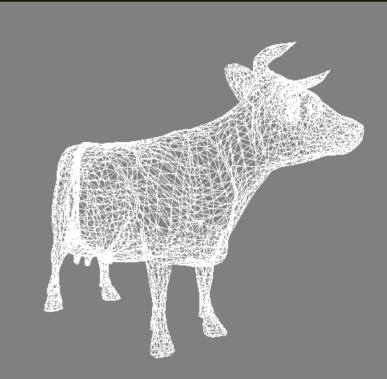
enables variable number of outputs from shader

Silhouette Detection

 Calculate geometric normal of centre triangle and adjacent triangles
 Calculate dot products between normals and view direction
 If centre triangle is

facing towards viewer and adjacent triangle is facing away, edge must be on silhouette

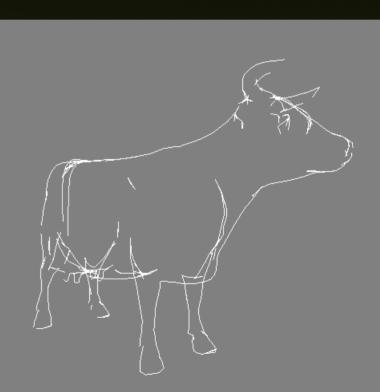




Silouhette Detection



Can be used for cartoon shading
 Same basic technique used for stencil shadow volumes extrusion

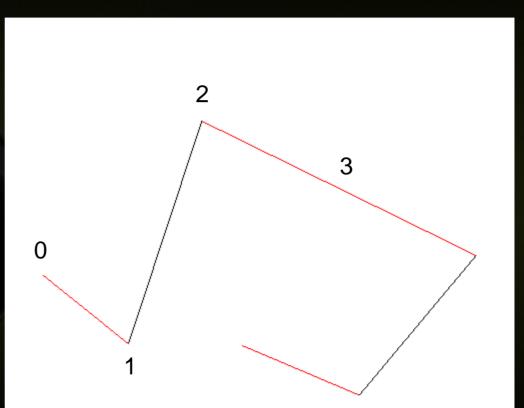


Bezier Curve Tesselation





- Line with adjacency
- 4 control vertices



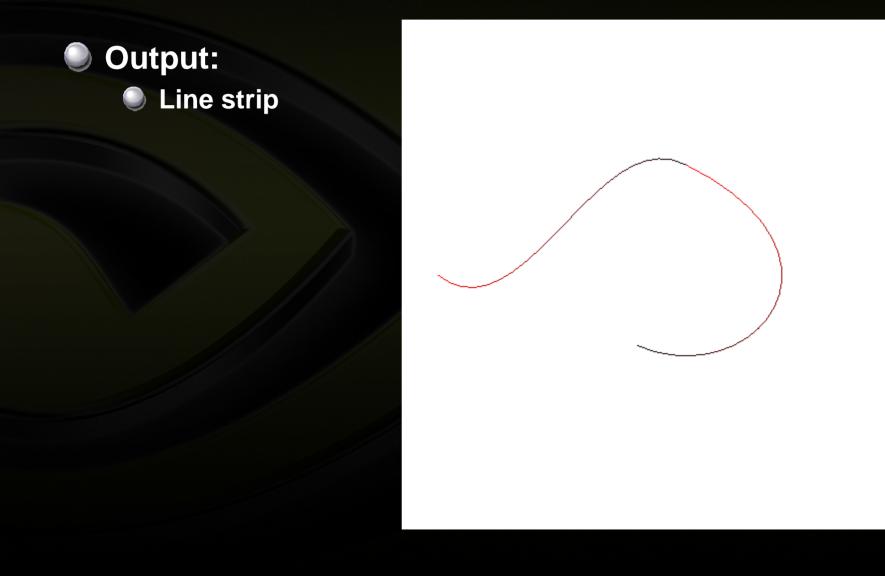
Bezier Curve HLSL Code



```
[maxvertexcount(10)]
void bezier GS(lineadj float4 v[4],
               inout LineStream<float4> stream,
               uniform int segments = 10)
{
    float4x4 bezierBasis = {
       \{1, -3, 3, -1\},\
       \{0, 3, -6, 3\},\
       \{0, 0, 3, -3\},\
       \{0, 0, 0, 1\}
   };
    for(int i=0; i<segments; i++) {</pre>
        float t = i / (float) (segments-1);
        float4 tvec = float4(1, t, t*t, t*t*t);
       float4 b = mul(bezierBasis, tvec);
       float4 p = v[0]*b.x + v[1]*b.y + v[2]*b.z + v[3]*b.w;
       stream.Append(p : SV POSITION)
   CubeMapStream.RestartStrip();
}
```

Bezier Curve Tesselation





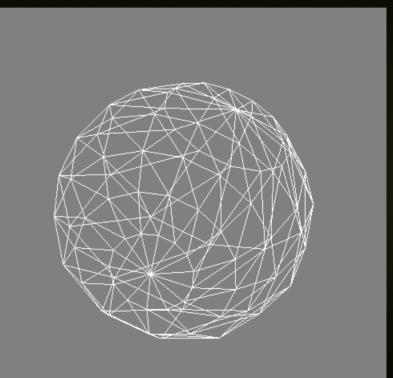
Fur Generation



Grow fur from triangles

1st pass

- Generate lines with adjacency from triangles
- Use barycentric coords
- Direction based on tangent vectors
- Use noise texture to perturb directions
- 2nd pass
 - Generate curves from lines



Fur Generation



Light using anisotropic lighting model



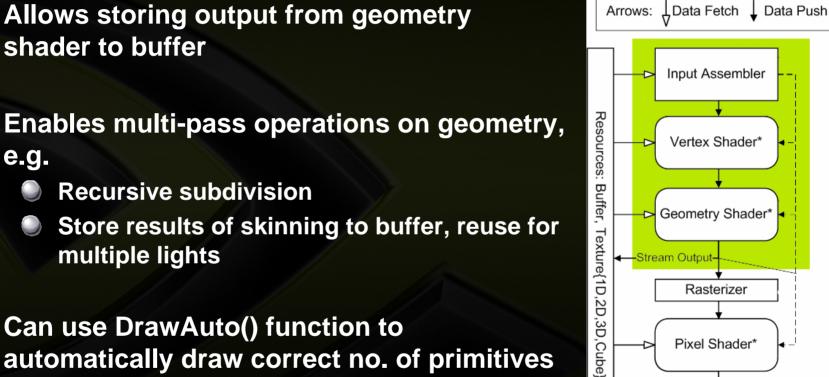
Stream Out

shader to buffer



Pixel Shader*

Output Merger





e.g.

Can use DrawAuto() function to automatically draw correct no. of primitives

No CPU intervention required

Recursive subdivision

multiple lights

Geometry Shader Tips

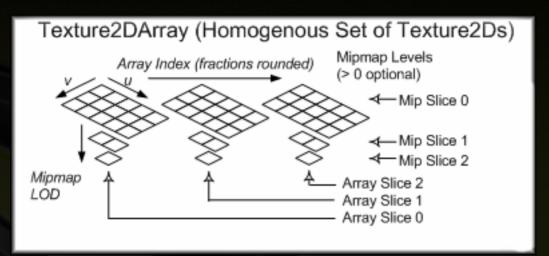


GS is not designed for large-scale tessellation

- Output limited to 1024 float values
- Try to minimize output size
- Output order is guaranteed
- Prefer multi-pass algorithms using stream-out to single pass with large output
- Do as much as possible in vertex shader
 - Run once per vertex, rather than per primitive vertex
- No quad input type
 - can use lines with adjacency instead (4 vertices)

Texture Arrays





- Array of 1D or 2D textures
- Indexable from shader
- Slices must be same size and format
- Arrays of cubemaps not supported (until DX10.1)
- Removes need for texture atlases
 - Useful for instancing, terrain texturing

Terrain using Texture Arrays





Rendering to Texture Arrays



Can select destination slice from GS

- Write to one of more layers
- Contrast to MRT
 - writes to all render targets
- Can be used for single-pass render-to-cubemap
 - Read input triangle
 - Output to 6 cube map faces, transformed by correct face matrix
 - Simple culling may help

DirectX 10 HDR



Two new floating point HDR formats

- R9G9B9E5_SHAREDEXP
 - 9 bit mantissa, shared 5 bit exponent
 - Very similar to Radiance RGBE format (R8G8B8E8)
 - Cannot be used for render targets (would be lossy)
 - Good for storing emissive textures (sky boxes etc.)
- R11G11B10_FLOAT
 - Each component has own 5 bit exponent (like fp16 numbers)
 - RGB components have 6, 6, 5 bits of mantissa each (vs. 10 bit mantissa for fp16)
 - No sign bit, all values must be positive
 - Can be used for render targets
- No sign bits, all values must be positive

Case Study: GS Metaballs





What are Isosurfaces?



Consider a function f(x, y, z)

- Defines a scalar field in 3D-space
- Can come from procedural function, or 3D simulation

Isosurface S is a set of points for which f(x, y, z) = const

Can be thought of as an *implicit* function relating x, y and z

Sometimes called *implicit* surfaces

Metaballs



A particularly interesting case Use implicit equation of the form

$$\sum_{i=1}^{N} \frac{r_i^2}{\|\mathbf{x} - \mathbf{p}_i\|^2} = 1$$

Gradient can be computed directly

$$\mathbf{grad}(f) = -\sum_{i=1}^{N} \frac{2 \cdot r_i^2}{\left\|\mathbf{x} - \mathbf{p}_i\right\|^4} \cdot (\mathbf{x} - \mathbf{p}_i)$$



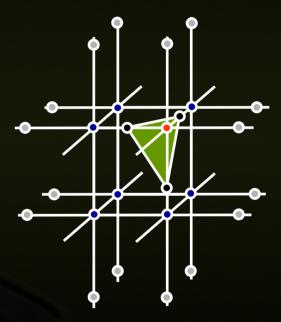
Soft/blobby objects that blend into each other Perfect for modelling fluids, explosions in games

The Marching Cubes Algorithm



A well-known method for scalar field polygonization
 Sample f(x, y, z) on a cubic lattice
 For each cubic cell:
 Estimate where isosurface intersects cell edges by linear interpolation

Tessellate depending on values of f() at cell vertices



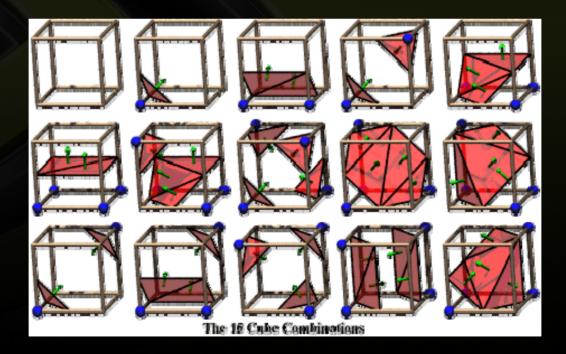
The marching cubes algorithm



Each vertex can be either "inside" or "outside"

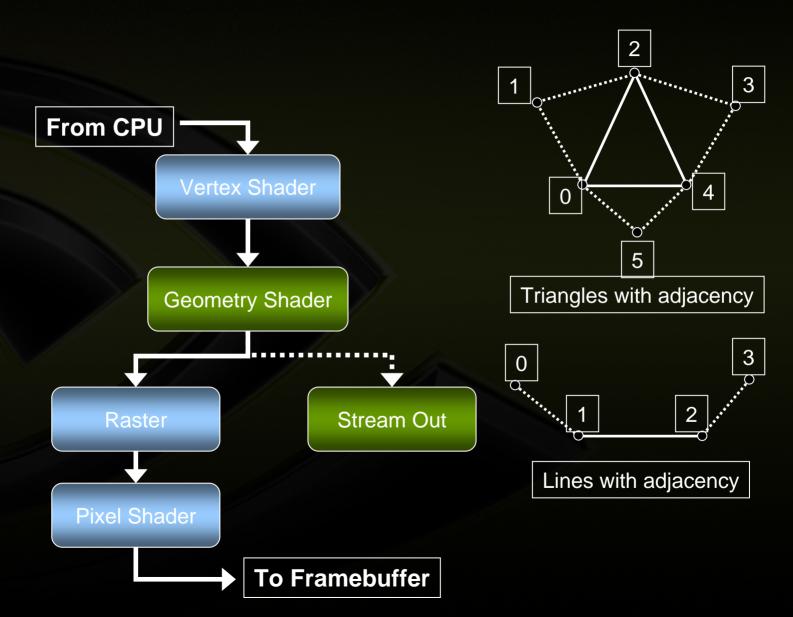
For each cube cell there are 256 ways for isosurface to intersect it

Can be simplified down to 15 unique cases



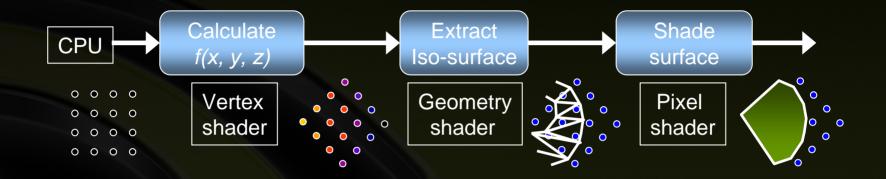
Geometry shaders in DX10





Implementation - Basic Idea





App feeds a GPU with a grid of vertices

VS transforms grid vertices and computes f(x, y, z), feeds to GS

GS processes each cell in turn and emits triangles

A problem...



Topology of GS input is restricted Points Lines Triangles with optional adjacency info Our "primitive" is a cubic cell Need to input 8 vertices to a GS A maximum we can input is 6 (with trianglead)

Solution



- First, note that actual input topology is irrelevant for GS
 - E.g. lineadj can be treated as quad input
- Work at tetrahedra level
 - Tetrahedron is 4 vertices perfect fit for lineadj!
- We'll subdivide each cell into tetrahedra

Marching Tetrahedra (MT)



Tetrahedra are easier to handle in GS

- No ambiguities in isosurface reconstuction
- Always output either 1 or 2 triangles



Generating a sampling grid



There's a variety of ways to subdivide

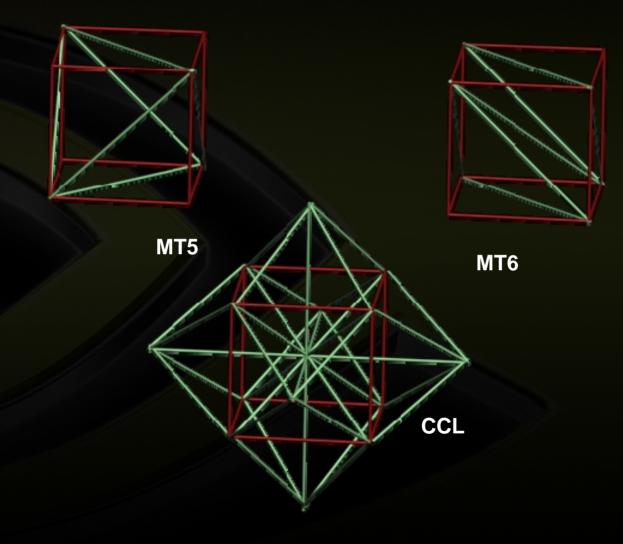
- Along main diagonal into 6 tetrahedra MT6
- Tessellate into 5 tetrahedra MT5
- Body-centered tessellation CCL

Can also generate tetrahedral grid directly

- AKA simplex grid
- Doesn't fit well within rectilinear volume







Sampling grids comparison



	Generation Complexity	Sampling effectiveness	Regularity
MT5	Med	Med	Low
MT6	Low	Med	Low
CCL	High	High	Med
Simplex	Low	Med	High

VS/GS Input/output



```
// Grid vertex
struct SampleData
{
    float4 Pos : SV_POSITION;
    float3 N : NORMAL;
    float Field : TEXCOORD0;
    uint IsInside : TEXCOORD1;
};
// Surface vertex
struct SurfaceVertex
{
    float4 Pos : SV_POSITION;
    float3 N : NORMAL;
};
```

// Sample position
// Scalar field gradient
// Scalar field value
// "Inside" flag

// Surface vertex position
// Surface normal

Vertex Shader



```
// Metaball function
// Returns metaball function value in .w
// and its gradient in .xyz
float4 Metaball(float3 Pos, float3 Center, float RadiusSq)
{
    float4 o;
    float3 Dist = Pos - Center;
    float InvDistSq = 1 / dot(Dist, Dist);
    o.xyz = -2 * RadiusSq * InvDistSq * InvDistSq * Dist;
    o.w = RadiusSq * InvDistSq;
    return o;
}
```

Vertex Shader



```
#define MAX_METABALLS
                              32
SampleData VS_SampleField(float3 Pos : POSITION,
     uniform float4x4 WorldViewProj,
     uniform float3x3 WorldViewProjIT,
     uniform uint NumMetaballs, uniform float4 Metaballs[MAX METABALLS])
     SampleData o;
     float4 Field = 0;
     for (uint i = 0; i<NumMetaballs; i++)</pre>
          Field += Metaball(Pos, Metaballs[i].xyz, Metaballs[i].w);
     o.Pos = mul(float4(Pos, 1), WorldViewProj);
     o.N = mul(Field.xyz, WorldViewProjIT);
     o.Field = Field.w;
     o.IsInside = Field.w > 1 ? 1 : 0;
     return o;
}
```

Geometry Shader

}



```
// Estimate where isosurface intersects grid edge
SurfaceVertex CalcIntersection(SampleData v0, SampleData v1)
{
    SurfaceVertex o;
    float t = (1.0 - v0.Field) / (v1.Field - v0.Field);
    o.Pos = lerp(v0.Pos, v1.Pos, t);
    o.N = lerp(v0.N, v1.N, t);
    return o;
```

Geometry Shader



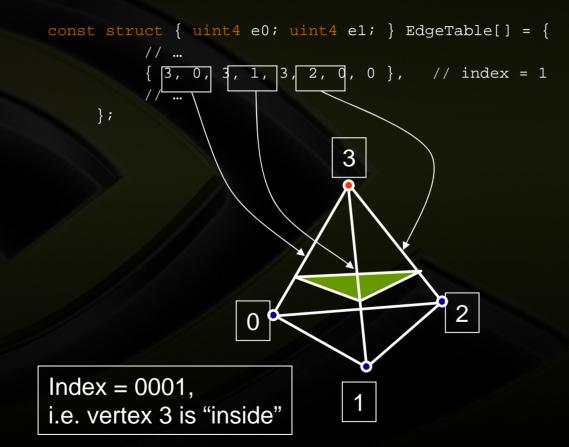
const struct { uint4 e0; uint4 e1; } EdgeTable[] = {

{	Ο,	Ο,	Ο,	Ο,	Ο,	0,	Ο,	1	},	//	all vertices out
{	3,	Ο,	3,	1,	3,	2,	Ο,	0	},	//	0001
{	2,	1,	2,	Ο,	2,	3,	Ο,	0	},	//	0010
{	2,	Ο,	3,	Ο,	2,	1,	3,	1	},	//	0011 - 2 triangles
{	1,	2,	1,	3,	1,	Ο,	Ο,	0	},	//	0100
{	1,	Ο,	1,	2,	3,	Ο,	3,	2	},	//	0101 - 2 triangles
{	1,	Ο,	2,	Ο,	1,	3,	2,	3	},	//	0110 - 2 triangles
{	3,	Ο,	1,	Ο,	2,	Ο,	0,	0	},	//	0111
{	Ο,	2,	Ο,	1,	Ο,	3,	Ο,	0	},	11	1000
{	Ο,	1,	3,	1,	0,	2,	3,	2	},	11	1001 - 2 triangles
{	Ο,	1,	Ο,	3,	2,	1,	2,	3	},	11	1010 - 2 triangles
{	3,	1,	2,	1,	0,	1,	Ο,	0	},	//	1011
{	Ο,	2,	1,	2,	0,	3,	1,	3	},	//	1100 - 2 triangles
{	1,	2,	3,	2,	Ο,	2,	Ο,	0	},	//	1101
{	Ο,	3,	2,	3,	1,	3,	Ο,	0	}	//	1110

};

Edge table construction





Geometry Shader



```
// ... continued
// don't bother if all vertices out or all vertices in
if (index > 0 && index < 15)
{
    uint4 e0 = EdgeTable[index].e0;
    uint4 e1 = EdgeTable[index].e1;
    // Emit a triangle
    Stream.Append(CalcIntersection(In[e0.x], In[e0.y]));
    Stream.Append(CalcIntersection(In[e0.z], In[e0.w]));
    Stream.Append(CalcIntersection(In[e1.x], In[e1.y]));
    Stream.Append(CalcIntersection(In[e1.x], In[e1.y]));
    // Emit additional triangle, if necessary
    if (e1.z != 0)
```

Stream.Append(CalcIntersection(In[e1.z], In[e1.w]));

Respect your vertex cache!

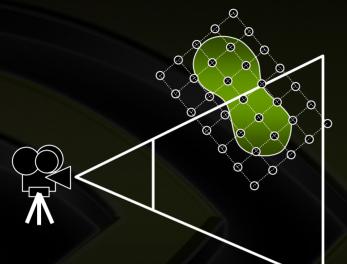


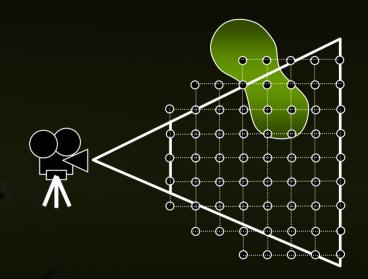
f(x, y, z) can be arbitrary complex
 E.g., many metaballs influencing a vertex
 Need to be careful about walk order
 Worst case is 4x more work than necessary!
 Straightforward linear work is not particularly cache friendly either

Alternatively, can pre-transform with StreamOut

Tessellation space







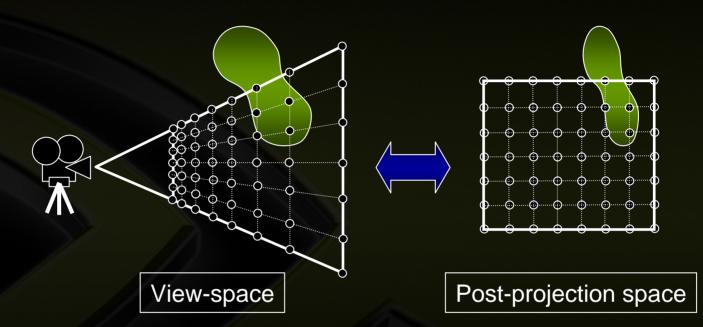
Object space

Works if you can calculate BB around your metaballs

View space

Better, but sampling rate is distributed inadequately



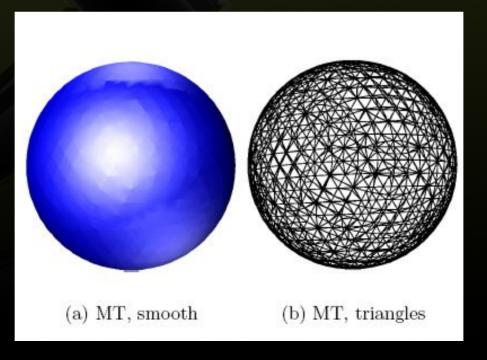


- Post-projective space
 - Probably the best option
 - We also get LOD for free!

Problems with current approach



Generated mesh is over-tessellated
 General problem with MT algorithms
 Many triangles end up irregular and skinny
 Good sampling grid helps a bit



Possible enhancements



Regularized Marching Tetrahedra (RMT)

- Vertex clustering prior to polygonization
 - Generated triangles are more regular
- For details refer to [2]
- Need to run a pre-pass at vertex level, looking at immediate neighbors
 - For CCL, each vertex has 14 neighbors
 - GS input is too limited for this ⊗

Conclusion



- Direct3D 10 is a major discontinuity in graphics hardware functionality
- Enables new effects and better performance
- Start redesigning your game engine now





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Buffer Resources



Input assembler accepts

- Vertex buffer
- Index buffer
- Buffer resource

Buffer resource can only be rendered to
 And limited to 8k elements at a time

Multiple passes can get you a R2VB

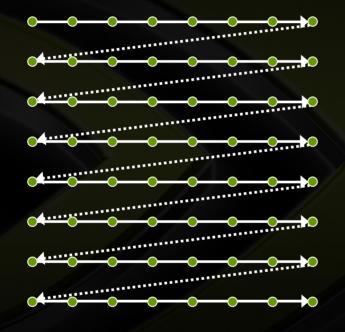
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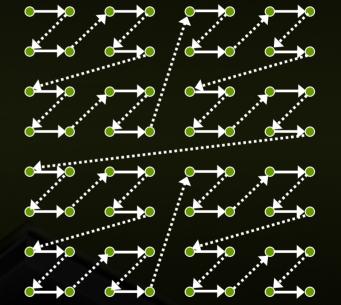


Can use space-filling fractal curves
 Hilbert curve
 Swizzled walk
 We'll use swizzled walk
 To compute swizzled offset, just interleave x, y and z bits

Linear walk vs swizzled walk







Swizzled walk

