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Chapter 5. Examples of nvJPEG.................................................................................... 26
The nvJPEG 0.2.0 library provides high-performance, GPU accelerated JPEG decoding functionality for image formats commonly used in deep learning and hyperscale multimedia applications. The library offers single and batched JPEG decoding capabilities which efficiently utilize the available GPU resources for optimum performance; and the flexibility for users to manage the memory allocation needed for decoding.

The nvJPEG library enables the following functions: use the JPEG image data stream as input; retrieve the width and height of the image from the data stream, and use this retrieved information to manage the GPU memory allocation and the decoding. A dedicated API is provided for retrieving the image information from the raw JPEG image data stream.

Tip Throughout this document, the terms “CPU” and “Host” are used synonymously. Similarly, the terms “GPU” and “Device” are synonymous.

The nvJPEG library supports the following:

**JPEG options:**
- Baseline and Progressive JPEG decoding
- 8 bits per pixel
- Huffman bitstream decoding
- 3 color channels (YCbCr) or 1 color channel (Grayscale)
- 8- and 16-bit quantization tables
- The following chroma subsampling for the 3 color channels Y, Cb, Cr (Y, U, V):
  - 4:4:4
  - 4:2:2
  - 4:2:0
  - 4:4:0
  - 4:1:1 and
  - 4:1:0

**Features:**
- Hybrid decoding using both the CPU (i.e., host) and the GPU (i.e., device).
- Input to the library is in the host memory, and the output is in the GPU memory.
- Single image and batched image decoding.
- Single phase and multiple phases decoding.
- Color space conversion.
- User-provided memory manager for the device and pinned host memory allocations.
Chapter 2.
USING THE NVJPEG LIBRARY

The nvJPEG library provides functions for both the decoding of a single image, and batched decoding of multiple images.

2.1. Single Image Decoding

For single-image decoding you provide the data size and a pointer to the file data, and the decoded image is placed in the output buffer.

To use the nvJPEG library, start by calling the helper functions for initialization.

1. Create nvJPEG library handle with one of the helper functions
   \texttt{nvjpegCreateSimple()} or \texttt{nvjpegCreateEx()}.
2. Create JPEG state with the helper function \texttt{nvjpegJpegStateCreate()}. See \texttt{nvJPEG Type Declarations} and \texttt{nvjpegJpegStateCreate()}.

Below is the list of helper functions available in the nvJPEG library:

- \texttt{nvjpegStatus_t nvjpegGetProperty(libraryPropertyType type, int *value)};
- [DEPRECATED] \texttt{nvjpegStatus_t nvjpegCreate(nvjpegBackend_t backend, nvjpegHandle_t *handle, nvjpeg_dev_allocator allocator)};
- \texttt{nvjpegStatus_t nvjpegCreateSimple(nvjpegHandle_t *handle)};
- \texttt{nvjpegStatus_t nvjpegCreateEx(nvjpegBackend_t backend, nvjpegDevAllocator_t *dev_allocator, nvjpegPinnedAllocator_t *pinned_allocator, unsigned int flags, nvjpegHandle_t *handle)};
- \texttt{nvjpegStatus_t nvjpegDestroy(nvjpegHandle_t handle)};
- \texttt{nvjpegStatus_t nvjpegJpegStateCreate(nvjpegHandle_t handle, nvjpegJpegState_t *jpeg_handle)};
- \texttt{nvjpegStatus_t nvjpegJpegStateDestroy(nvjpegJpegState handle)};
- Other helper functions such as \texttt{nvjpegSet*()} and \texttt{nvjpegGet*()} can be used to configure the library functionality on per-handle basis. Refer to the helper API reference for more details.
3. Retrieve the width and height information from the JPEG-encoded image by using the `nvjpegGetImageInfo()` function. See also `nvjpegGetImageInfo()`.

Below is the signature of `nvjpegGetImageInfo()` function:

```c
nvjpegStatus_t nvjpegGetImageInfo(
    nvjpegHandle_t              handle,
    const unsigned char         *data,
    size_t                      length,
    int                         *nComponents,
    nvjpegChromaSubsampling_t   *subsampling,
    int                         *widths,
    int                         *heights);
```

For each image to be decoded, pass the JPEG data pointer and data length to the above function. The `nvjpegGetImageInfo()` function is thread safe.

4. One of the outputs of the above `nvjpegGetImageInfo()` function is `nvjpegChromaSubsampling_t`. This parameter is an enum type, and its enumerator list is composed of the chroma subsampling property retrieved from the JPEG image. See `nvJPEG Chroma Subsampling`.

5. Use the `nvjpegDecode()` function in the nvJPEG library to decode this single JPEG image. See the signature of this function below:

```c
nvjpegStatus_t nvjpegDecode(
    nvjpegHandle_t          handle,
    nvjpegJpegState_t       jpeg_handle,
    const unsigned char     *data,
    size_t                  length,
    nvjpegOutputFormat_t    output_format,
    nvjpegImage_t           *destination,
    cudaStream_t            stream);
```

In the above `nvjpegDecode()` function, the parameters `nvjpegOutputFormat_t`, `nvjpegImage_t`, and `cudaStream_t` can be used to set the output behavior of the `nvjpegDecode()` function. You provide the `cudaStream_t` parameter to indicate the stream to which your asynchronous tasks are submitted.

6. The `nvjpegOutputFormat_t` parameter:

The `nvjpegOutputFormat_t` parameter can be set to one of the `output_format` settings below:

<table>
<thead>
<tr>
<th>output_format</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>NVJPEG_OUTPUT_UNCHANGED</td>
<td>Return the decoded image planar format.</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_RGB</td>
<td>Convert to planar RGB.</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_BGR</td>
<td>Convert to planar BGR.</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_RGBI</td>
<td>Convert to interleaved RGB.</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_BGRI</td>
<td>Convert to interleaved BGR.</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_Y</td>
<td>Return the Y component only.</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_YUV</td>
<td>Return in the YUV planar format.</td>
</tr>
</tbody>
</table>
For example, if the output_format is set to `NVJPEG_OUTPUT_Y` or `NVJPEG_OUTPUT_RGB`, or `NVJPEG_OUTPUT_BGRI` then the output is written only to channel[0], and the other channels are not touched.

Alternately, in the case of planar output, the data is written to the corresponding channels of the `nvjpegImage_t` destination structure.

Finally, in the case of grayscale JPEG and RGB output, the luminance is used to create the grayscale RGB.

7. As mentioned above, an important benefit of the `nvjpegGetImageInfo()` function is the ability to utilize the image information retrieved from the input JPEG image to allocate proper GPU memory for your decoding operation.

The `nvjpegGetImageInfo()` function returns the `widths`, `heights` and `nComponents` parameters.

```c
nvjpegStatus_t nvjpegGetImageInfo(
    const nvjpegHandle_t handle,
    const unsigned char *data,
    size_t length,
    int *nComponents,
    int *widths,
    int *heights,
    int *subsampling
);
```

You can use the retrieved parameters, `widths`, `heights` and `nComponents`, to calculate the required size for the output buffers, either for a single decoded JPEG, or for every decoded JPEG in a batch.

To optimally set the `destination` parameter for the `nvjpegDecode()` function, use the following guidelines:

<table>
<thead>
<tr>
<th>For the output_format:</th>
<th>destination.pitch[0] should be at least: width[0]</th>
<th>destination.channel[0] should be at least of size: destination.pitch[0]*height[0]</th>
</tr>
</thead>
<tbody>
<tr>
<td>NVJPEG_OUTPUT_Y</td>
<td>destination.pitch[c] should be at least:</td>
<td>destination.channel[c] should be at least of size:</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_YUV</td>
<td>width[c] for c = 0, 1, 2</td>
<td>destination.pitch[c]*height[c] for c = 0, 1, 2</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_RGB and</td>
<td>width[0] for c = 0, 1, 2</td>
<td>destination.pitch[0]*height[0] for c = 0, 1, 2</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_BGR</td>
<td>width[0]*3</td>
<td></td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_RGBI and</td>
<td>width[c] for c = [0, nComponents - 1]</td>
<td>destination.pitch[c]*height[c] for c = [0, nComponents - 1]</td>
</tr>
<tr>
<td>NVJPEG_OUTPUT_BGRI</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

8. Ensure that the `nvjpegImage_t` structure (or structures, in the case of batched decode) is filled with the pointers and pitches of allocated buffers. The `nvjpegImage_t` structure that holds the output pointers is defined as follows:

```c
typedef struct {
    unsigned char * channel[NVJPEG_MAX_COMPONENT];
    unsigned int pitch[NVJPEG_MAX_COMPONENT];
} nvjpegImage_t;
```
NVJPEG_MAX_COMPONENT is the maximum number of color components the nvJPEG library supports in the current release. For generic images, this is the maximum number of encoded channels that the library is able to decompress.

9. Finally, when you call the `nvjpegDecode()` function with the parameters as described above, the `nvjpegDecode()` function fills the output buffers with the decoded data.

### 2.2. Decode by Phases

Alternately, you can decode a single image in multiple phases. This gives you flexibility in controlling the flow, and optimizing the decoding process.

To decode an image in multiple phases, follow these steps:

1. Just as when you are decoding in a single phase, create the JPEG state with the helper function `nvjpegJpegStateCreate()`.
2. Next, call the functions in the sequence below (see Decode API -- Multiple Phases.)
   - `nvjpegDecodePhaseOne()`
   - `nvjpegDecodePhaseTwo()`
   - `nvjpegDecodePhaseThree()`
3. At the conclusion of the third phase, the `nvjpegDecodePhaseThree()` function writes the decoded output at the memory location pointed to by its `*destination` parameter.

### 2.3. Batched Image Decoding

For the batched image decoding you provide pointers to multiple file data in the memory, and also provide the buffer sizes for each file data. The nvJPEG library will decode these multiple images, and will place the decoded data in the output buffers that you specified in the parameters.

### 2.4. Single Phase

For batched image decoding in single phase, follow these steps:

1. Call `nvjpegDecodeBatchedInitialize()` function to initialize the batched decoder. Specify the batch size in the `batch_size` parameter. See `nvjpegDecodeBatchedInitialize()`.
2. Next, call `nvjpegDecodeBatched()` for each new batch. Make sure to pass the parameters that are correct to the specific batch of images. If the size of the batch changes, or if the batch decoding fails, then call the `nvjpegDecodeBatchedInitialize()` function again.
2.5. Multiple Phases

To decode a batch of images in multiple phases, follow these steps:

1. Create the JPEG state with the helper function `nvjpegJpegStateCreate()`.
2. Call the `nvjpegDecodeBatchedInitialize()` function to initialize the batched decoder. Specify the batch size in the `batch_size` parameter, and specify the `max_cpu_threads` parameter to set the maximum number of CPU threads that work on single batch.
3. Batched processing is done by calling the functions for the specific phases in sequence:
   - In the first phase, call `nvjpegDecodePhaseOne()` for each image in the batch, according to the index of the image in the batch. Note that this could be done using multiple threads. If multiple threads are used then the thread index in the range [0, max_cpu_threads-1] should be provided to the `nvjpegDecodeBatchedPhaseOne()` function. Before proceeding to the next phase, ensure that the `nvjpegDecodePhaseOne()` calls for every image have finished.
   - Next, call `nvjpegDecodePhaseTwo()`.
   - Finally, call `nvjpegDecodePhaseThree()`.
4. If you have another batch of images of the same size to process, then repeat from 3.
Chapter 3.
NVJPEG TYPE DECLARATIONS

3.1. nvJPEG Device Memory Allocator Interface

typedef int (*tDevMalloc)(void**, size_t);
typedef int (*tDevFree)(void*);
typedef struct
{
    tDevMalloc dev_malloc;
    tDevFree dev_free;
} nvjpegDevAllocator_t;

Users can tell the library to use their own device memory allocator. The function prototypes for the memory allocation and memory freeing functions are similar to the cudaMalloc() and cudaFree() functions. They should return 0 in case of success, and non-zero otherwise. A pointer to the nvjpegDevAllocator_t structure, with properly filled fields, should be provided to the nvjpegCreate() function. NULL is accepted, in which case the default memory allocation functions cudaMalloc() and cudaFree() is used.

When the nvjpegDevAllocator_t *allocator parameter in the nvjpegCreate() or nvjpegCreateEx() function is set as a pointer to the above nvjpegDevAllocator_t structure, then this structure is used for allocating and releasing the device memory. The function prototypes for the memory allocation and memory freeing functions are similar to the cudaMalloc() and cudaFree() functions. They should return 0 in case of success, and non-zero otherwise.

However, if the nvjpegDevAllocator_t *allocator parameter in the nvjpegCreate() or nvjpegCreateEx() function is set to NULL, then the default memory allocation functions cudaMalloc() and cudaFree() will be used. When using nvjpegCreateSimple() function to create library handle the default device memory allocator will be used.
3.2. nvJPEG Host Pinned Memory Allocator Interface

typedef int (*tPinnedMalloc)(void**, size_t, unsigned int flags);
typedef int (*tPinnedFree)(void*);
typedef struct
{
    tPinnedMalloc pinned_malloc;
t    tPinnedFree pinned_free;
} nvjpegPinnedAllocator_t;

When the `nvjpegPinnedAllocator_t *allocator` parameter in the `nvjpegCreateEx()` function is set as a pointer to the above `nvjpegPinnedAllocator_t` structure, then this structure will be used for allocating and releasing host pinned memory for copying data to/from device. The function prototypes for the memory allocation and memory freeing functions are similar to the `cudaHostAlloc()` and `cudaFreeHost()` functions. They will return 0 in case of success, and non-zero otherwise.

However, if the `nvjpegPinnedAllocator_t *allocator` parameter in the `nvjpegCreateEx()` function is set to NULL, then the default memory allocation functions `cudaHostAlloc()` and `cudaFreeHost()` will be used. When using `nvjpegCreate()` or `nvjpegCreateSimple()` function to create library handle, the default host pinned memory allocator will be used.

3.3. nvJPEG Opaque Library Handle Struct

struct nvjpegHandle;
typedef struct nvjpegHandle* nvjpegHandle_t;

The library handle is used in any consecutive nvJPEG library calls, and should be initialized first.

The library handle is thread safe, and can be used by multiple threads simultaneously.

3.4. nvJPEG Opaque JPEG Decoding State Handle

struct nvjpegJpegState;
typedef struct nvjpegJpegState* nvjpegJpegState_t;

The `nvjpegJpegState` structure stores the temporary JPEG information. It should be initialized before any usage. This JPEG state handle can be reused after being used in another decoding. The same JPEG handle should be used across the decoding phases for the same image or batch. Multiple threads are allowed to share the JPEG state handle only when processing same batch during first phase (`nvjpegDecodePhaseOne`).
3.5. nvJPEG Output Pointer Struct

```
typedef struct
{
    unsigned char * channel[NVJPEG_MAX_COMPONENT];
    unsigned int pitch[NVJPEG_MAX_COMPONENT];
} nvjpegImage_t;
```

The `nvjpegImage_t` struct holds the pointers to the output buffers, and holds the corresponding strides of those buffers for the image decoding.

See Single Image Decoding on how to set up the `nvjpegImage_t` struct.
Chapter 4. NVJPEG API REFERENCE

This section describes the nvJPEG API.

4.1. nvJPEG Helper API Reference

The nvJPEG helper functions are used for initializing.

4.1.1. nvjpegGetProperty()

Gets the numeric value for the major or minor version, or the patch level, of the nvJPEG library.

**Signature:**

```c
nvjpegStatus_t nvjpegGetProperty(
    libraryPropertyType type,
    int *value);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>libraryPropertyType type</td>
<td>Input</td>
<td>Host</td>
<td>One of the supported libraryPropertyType values, that is, MAJOR_VERSION, MINOR_VERSION or PATCH_LEVEL.</td>
</tr>
<tr>
<td>int *value</td>
<td>Output</td>
<td>Host</td>
<td>The numeric value corresponding to the specific libraryPropertyType requested.</td>
</tr>
</tbody>
</table>

**Returns:**

*nvjpegStatus_t* - An error code as specified in nvJPEG API Return Codes.
4.1.2. nvjpegCreate()

Allocates and initializes the library handle.

This function is deprecated. Use either nvjpegCreateSimple() or nvjpegCreateEx() functions to create the library handle.

Signature:

```c
nvjpegStatus_t nvjpegCreate(
    nvjpegBackend_t backend,
    nvjpegDevAllocator_t *allocator,
    nvjpegHandle_t *handle);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegBackend_t backend</td>
<td>Input</td>
<td>Host</td>
<td>A backend parameter for the library. This backend will be used for all the functions called with this handle. If this is set to DEFAULT then it automatically chooses one of the underlying algorithms.</td>
</tr>
<tr>
<td>nvjpegDevAllocator_t *allocator</td>
<td>Input</td>
<td>Host</td>
<td>Device memory allocator. See nvjpegDevAllocator_t structure description. If NULL is provided, then the default CUDA runtime cudaMalloc() and cudaFree() functions will be used.</td>
</tr>
<tr>
<td>nvjpegHandle_t *handle</td>
<td>Input/Output</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
</tbody>
</table>

The `nvjpegBackend_t` parameter is an `enum` type, with the below enumerated list values:

```c
typedef enum {
    NVJPEG_BACKEND_DEFAULT = 0,
    NVJPEG_BACKEND_HYBRID = 1,
} nvjpegBackend_t;
```

Returns:

`nvjpegStatus_t` - An error code as specified in nvJPEG API Return Codes.

4.1.3. nvjpegCreateSimple()

Allocates and initializes the library handle, with default codec implementations selected by library and default memory allocators.

Signature:

```c
nvjpegStatus_t nvjpegCreateSimple(nvjpegHandle_t *handle);
```
Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t *handle</td>
<td>Input/Output</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
</tbody>
</table>

Returns:

nvjpegStatus_t - An error code as specified in nvJPEG API Return Codes.

4.1.4. nvjpegCreateEx()
Allocates and initializes the library handle using the provided arguments.

Signature:

nvjpegStatus_t nvjpegCreateEx(nvjpegBackend_t backend,
                              nvjpegDevAllocator_t *dev_allocator,
                              nvjpegPinnedAllocator_t *pinned_allocator,
                              unsigned int flags,
                              nvjpegHandle_t *handle);

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegBackend_t backend</td>
<td>Input</td>
<td>Host</td>
<td>A backend parameter for the library. This backend will be used for all of the functions called with this handle. If this is set to &quot;DEFAULT&quot; then it will choose one of underlying algorithms automatically.</td>
</tr>
<tr>
<td>nvjpegDevAllocator_t *dev_allocator</td>
<td>Input</td>
<td>Host</td>
<td>Device memory allocator. See nvjpegDevAllocator_t structure description. If NULL is provided, then the default CUDA runtime functions cudaMalloc() and cudaFree() will be used.</td>
</tr>
<tr>
<td>nvjpegPinnedAllocator_t *pinned_allocator</td>
<td>Input</td>
<td>Host</td>
<td>Pinned host memory allocator. See nvjpegPinnedAllocator_t structure description. If NULL is provided, then the default CUDA runtime functions cudaHostAlloc() and cudaFreeHost() will be used.</td>
</tr>
</tbody>
</table>

Returns:

nvjpegStatus_t - An error code as specified in nvJPEG API Return Codes.

4.1.5. nvjpegDestroy()

Releases the library handle.
Signature:
```
nvjpegStatus_t nvjpegDestroy(nvjpegHandle_t handle);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t handle</td>
<td>Input/Output</td>
<td>Host</td>
<td>The library handle to release.</td>
</tr>
</tbody>
</table>

Returns:

```
nvjpegStatus_t - An error code as specified in nvJPEG API Return Codes.
```

### 4.1.6. `nvjpegSetDeviceMemoryPadding()`

Use the provided padding for all device memory allocations with specified library handle. A large number will help to amortize the need for device memory reallocations when needed.

Signature:
```
nvjpegStatus_t nvjpegSetDeviceMemoryPadding(
    size_t padding,
    nvjpegHandle_t handle);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>size_t padding</td>
<td>Input</td>
<td>Host</td>
<td>Device memory padding to use for all further device memory allocations.</td>
</tr>
<tr>
<td>nvjpegHandle_t *handle</td>
<td>Input/Output</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
</tbody>
</table>

Returns:

```
nvjpegStatus_t - An error code as specified in nvJPEG API Return Codes.
```

### 4.1.7. `nvjpegGetDeviceMemoryPadding()`

Retrieve the device memory padding that is currently used for the specified library handle.

Signature:
```
nvjpegStatus_t nvjpegGetDeviceMemoryPadding(
    size_t *padding,
    nvjpegHandle_t handle);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>size_t *padding</td>
<td>Output</td>
<td>Host</td>
<td>Device memory padding that is currently used for device memory allocations.</td>
</tr>
<tr>
<td>nvjpegHandle_t *handle</td>
<td>Input/Output</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
</tbody>
</table>

Returns:
**nvjpegStatus_t** - An error code as specified in *nvJPEG API Return Codes.*

### 4.1.8. `nvjpegSetPinnedMemoryPadding()`

Use the provided padding for all pinned host memory allocations with specified library handle. A large number will help to amortize the need for pinned host memory reallocations when needed.

**Signature:**
```
nvjpegStatus_t nvjpegSetPinnedMemoryPadding(
    size_t padding,
    nvjpegHandle_t handle);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>size_t padding</code></td>
<td>Input</td>
<td>Host</td>
<td>Pinned host memory padding to use for all further pinned host memory allocations.</td>
</tr>
<tr>
<td><code>nvjpegHandle_t handle</code></td>
<td>Input/Output</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
</tbody>
</table>

**Returns:**

`nvjpegStatus_t` - An error code as specified in *nvJPEG API Return Codes.*

### 4.1.9. `nvjpegGetPinnedMemoryPadding()`

Retrieve the pinned host memory padding that is currently used for specified library handle.

**Signature:**
```
nvjpegStatus_t nvjpegGetPinnedMemoryPadding(
    size_t *padding,
    nvjpegHandle_t handle);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>size_t *padding</code></td>
<td>Output</td>
<td>Host</td>
<td>Pinned host memory padding that is currently used for pinned host memory allocations.</td>
</tr>
<tr>
<td><code>nvjpegHandle_t handle</code></td>
<td>Input/Output</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
</tbody>
</table>

**Returns:**

`nvjpegStatus_t` - An error code as specified in *nvJPEG API Return Codes.*

### 4.1.10. `nvjpegJpegStateCreate()`

Allocates and initializes the internal structure required for the JPEG processing.
Signature:

```c
nvjpegStatus_t nvjpegJpegStateCreate(
    nvjpegHandle_t      handle,
    nvjpegJpegState_t   *jpeg_handle);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t handle</td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td>nvjpegJpegState_t *jpeg_handle</td>
<td>Input/Output</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
</tbody>
</table>

Returns:

`nvjpegStatus_t` - An error code as specified in `nvJPEG API Return Codes`.

### 4.1.11. `nvjpegJpegStateDestroy()`

Releases the image internal structure.

Signature:

```c
nvjpegStatus_t nvjpegJpegStateDestroy(nvjpegJpegState handle);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegJpegState handle</td>
<td>Input/Output</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
</tbody>
</table>

Returns:

`nvjpegStatus_t` - An error code as specified in `nvJPEG API Return Codes`.

### 4.2. Retrieve Encoded Image Information API

The helper functions for retrieving the encoded image information.

#### 4.2.1. `nvjpegGetImageInfo()`

Decodes the JPEG header and retrieves the basic information about the image.

Signature:

```c
nvjpegStatus_t nvjpegGetImageInfo(
    nvjpegHandle_t              handle,
    const unsigned char         *data,              
    size_t                      length,             
    int                         *nComponents, 
    nvjpegChromaSubsampling_t   *subsampling, 
    int                         *widths,            
    int                         *heights);
```

Parameters:
### Parameter Table

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t handle</td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td>const unsigned char *data</td>
<td>Input</td>
<td>Host</td>
<td>Pointer to the encoded data.</td>
</tr>
<tr>
<td>size_t length</td>
<td>Input</td>
<td>Host</td>
<td>Size of the encoded data in bytes.</td>
</tr>
<tr>
<td>int *nComponents</td>
<td>Output</td>
<td>Host</td>
<td>Chroma subsampling for the 1- or 3- channel encoding.</td>
</tr>
<tr>
<td>int *widths</td>
<td>Output</td>
<td>Host</td>
<td>Pointer to the first element of array of size NVJPEG_MAX_COMPONENT, where the width of each channel (up to NVJPEG_MAX_COMPONENT) will be saved. If the channel is not encoded, then the corresponding value would be zero.</td>
</tr>
<tr>
<td>int *heights</td>
<td>Output</td>
<td>Host</td>
<td>Pointer to the first element of array of size NVJPEG_MAX_COMPONENT, where the height of each channel (up to NVJPEG_MAX_COMPONENT) will be saved. If the channel is not encoded, then the corresponding value would be zero.</td>
</tr>
</tbody>
</table>

### Returns:

nvjpegStatus_t - An error code as specified in nvJPEG API Return Codes.

### 4.3. Decode API -- Single Phase

Functions for decoding single image or batched images in a single phase.

#### 4.3.1. nvjpegDecode()

Decodes a single image, and writes the decoded image in the desired format to the output buffers. This function is asynchronous with respect to the host. All GPU tasks for this function will be submitted to the provided stream.

### Signature:

```c
nvjpegStatus_t nvjpegDecode(
    nvjpegHandle_t          handle,
    nvjpegJpegState_t       jpeg_handle,
    const unsigned char     *data,
    size_t                  length,
    nvjpegOutputFormat_t    output_format,
    nvjpegImage_t           *destination,
    cudaStream_t            stream);
```

### Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t handle</td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
</tbody>
</table>
4.3.2. `nvjpegDecodeBatchedInitialize()`

This function initializes the batched decoder state. The initialization parameters include the batch size, the maximum number of CPU threads, and the specific output format in which the decoded image will be saved. This function should be called once, prior to decoding the batches of images. Any currently running batched decoding should be finished before calling this function.

**Signature:**

```c
nvjpegStatus_t nvjpegDecodeBatchedInitialize(  
    nvjpegHandle_t          handle,  
    nvjpegJpegState_t       jpeg_handle,  
    int                     batch_size,  
    int                     max_cpu_threads,  
    nvjpegOutputFormat_t    output_format);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>nvjpegHandle_t handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td><code>nvjpegJpegState_t jpeg_handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td><code>int batch_size</code></td>
<td>Input</td>
<td>Host</td>
<td>Batch size.</td>
</tr>
<tr>
<td><code>int max_cpu_threads</code></td>
<td>Input</td>
<td>Host</td>
<td>Maximum number of CPU threads that can participate in decoding a batch.</td>
</tr>
<tr>
<td><code>nvjpegOutputFormat_t output_format</code></td>
<td>Input</td>
<td>Host</td>
<td>Format in which the decoded output will be saved.</td>
</tr>
</tbody>
</table>

**Returns:**

`nvjpegStatus_t` - An error code as specified in `nvJPEG API Return Codes`. 

---
4.3.3. nvjpegDecodeBatched()

Decodes the batch of images, and writes them to the buffers described in the `destination` parameter in a format provided to `nvjpegDecodeBatchedInitialize()` function. This function is asynchronous with respect to the host. All GPU tasks for this function will be submitted to the provided stream.

**Signature:**

```c
nvjpegStatus_t nvjpegDecodeBatched(
    nvjpegHandle_t             handle,
    nvjpegJpegState_t          jpeg_handle,
    const unsigned char *const *data,
    const size_t               *lengths,
    nvjpegImage_t              *destinations,
    cudaStream_t               stream);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>nvjpegHandle_t handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td><code>nvjpegJpegState_t jpeg_handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td><code>const unsigned char *const *data</code></td>
<td>Input</td>
<td>Host</td>
<td>Pointer to the first element of array of the input data. The size of the array is assumed to be <code>batch_size</code> provided to <code>nvjpegDecodeBatchedInitialize()</code> batch initialization function.</td>
</tr>
<tr>
<td><code>const size_t *lengths</code></td>
<td>Input</td>
<td>Host</td>
<td>Pointer to the first element of array of input sizes. Size of array is assumed to be <code>batch_size</code> provided to <code>nvjpegDecodeBatchedInitialize()</code>, the batch initialization function.</td>
</tr>
<tr>
<td><code>nvjpegImage_t *destinations</code></td>
<td>Input/Output</td>
<td>Host/Device</td>
<td>Pointer to the first element of array of output descriptors. The size of array is assumed to be <code>batch_size</code> provided to <code>nvjpegDecodeBatchedInitialize()</code>, the batch initialization function. See also <code>nvjpegImage_t</code>.</td>
</tr>
<tr>
<td><code>cudaStream_t stream</code></td>
<td>Input</td>
<td>Host</td>
<td>The CUDA stream where all the GPU work will be submitted.</td>
</tr>
</tbody>
</table>

**Returns:**

`nvjpegStatus_t` - An error code as specified in `nvJPEG API Return Codes`.
4.4. Decode API -- Multiple Phases

The nvJPEG library provides an ability to control the decoding process in phases. In the simple case of a single-image decode you can split the decoding into phases. For decoding multiple images, you can overlap the decoding phases of separate images within a single thread. Finally, for the batched decode you can use multiple threads to split the host tasks. Synchronization between phases should be handled with CUDA events and CUDA stream synchronization mechanisms, by the user.

Note that first phases are synchronous with the respect to the host, while the second and third phases are asynchronous--for both single image and batched decode.

4.4.1. nvjpegDecodePhaseOne()

The first phase of a single-image decode. You provide all the inputs, and the nvJPEG library performs any required preprocessing on the host. Any previous calls to nvjpegDecodePhaseOne() and nvjpegDecodePhaseTwo() with the same nvjpeg_handle parameter should be finished prior to this call.

Signature:

```c
nvjpegStatus_t nvjpegDecodePhaseOne(
    nvjpegHandle_t          handle,
    nvjpegJpegState_t       jpeg_handle,
    const unsigned char     *data,
    size_t                  length,
    nvjpegOutputFormat_t    output_format,
    cudaStream_t            stream);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t handle</td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td>nvjpegJpegState_t jpeg_handle</td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td>const unsigned char *data</td>
<td>Input</td>
<td>Host</td>
<td>Pointer to the encoded stream.</td>
</tr>
<tr>
<td>size_t length</td>
<td>Input</td>
<td>Host</td>
<td>Size of the encoded stream.</td>
</tr>
<tr>
<td>nvjpegOutputFormat_t output_format</td>
<td>Input</td>
<td>Host</td>
<td>Format in which the decoded image will be saved.</td>
</tr>
<tr>
<td>cudaStream_t stream</td>
<td>Input</td>
<td>Host</td>
<td>The CUDA stream where all the GPU work will be submitted.</td>
</tr>
</tbody>
</table>

Returns:

nvjpegStatus_t - An error code as specified in nvJPEG API Return Codes.
4.4.2. nvjpegDecodePhaseTwo()

In this second phase of the decoding process, the GPU (that is, the device) is involved. The decoding task is transferred to the device memory. Any required preprocessing is performed on the device. Any previous calls to `nvjpegDecodePhaseTwo()` and `nvjpegDecodePhaseThree()` with the same `jpeg_handle` parameter should be finished prior to this call.

**Signature:**

```c
nvjpegStatus_t nvjpegDecodePhaseTwo(
    nvjpegHandle_t handle,
    nvjpegJpegState_t jpeg_handle,
    cudaStream_t stream);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>nvjpegHandle_t handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td><code>nvjpegJpegState_t jpeg_handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td><code>cudaStream_t stream</code></td>
<td>Input</td>
<td>Host</td>
<td>The CUDA stream where all the GPU work will be submitted.</td>
</tr>
</tbody>
</table>

**Returns:**

`nvjpegStatus_t` - An error code as specified in `nvJPEG API Return Codes`.

4.4.3. nvjpegDecodePhaseThree()

In this third phase of the decoding process, the decoded image is written to the output, in the specified decoding format.

**Signature:**

```c
nvjpegStatus_t nvjpegDecodePhaseThree(
    nvjpegHandle_t handle,
    nvjpegJpegState_t jpeg_handle,
    nvjpegImage_t *destination,
    cudaStream_t stream);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>nvjpegHandle_t handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td><code>nvjpegJpegState_t jpeg_handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td><code>nvjpegImage_t *destination</code></td>
<td>Input/Output</td>
<td>Host/Device</td>
<td>Pointer to the structure that describes the output destination. This structure should be on host,</td>
</tr>
</tbody>
</table>
but the pointers in this structure should be pointing to the device memory. See `nvjpegImage_t` description for details.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>cudaStream_t stream</td>
<td>Input</td>
<td>Host</td>
<td>The CUDA stream where all the GPU work will be submitted.</td>
</tr>
</tbody>
</table>

**Returns:**

`nvjpegStatus_t` - An error code as specified in nvJPEG API Return Codes.

### 4.4.4. nvjpegDecodeBatchedPhaseOne()

This first phase of the batched decoding should be called separately for each image in the batch. The batch initialization API, with appropriate batch parameters, should be called prior to starting the task with the batch.

If the batch parameters (batch size, number of threads, output format) did not change, then there is no need to initialize the batch again before starting the task.

It is possible to use multiple threads to split this first phase of the task. In which case, each thread should have a unique index. Provide the index of the image in the batch, and use the same JPEG decoding state parameter.

The thread index for the batch should be in the range of \([0, \text{max_cpu_threads}-1]\). The image index should be in the range of \([0, \text{batch_size}-1]\). Any previous calls to `nvjpegDecodeBatchedPhaseOne()` and `nvjpegDecodeBatchedPhaseTwo()` on a different batch with the same JPEG state handle parameter should be completed prior to this call.

**Signature:**

```c
nvjpegStatus_t nvjpegDecodeBatchedPhaseOne(
    nvjpegHandle_t          handle,
    nvjpegJpegState_t       jpeg_handle,
    const unsigned char     *data,
    size_t                  length,
    int                     image_idx,
    int                     thread_idx,
    cudaStream_t            stream);
```

**Parameters:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t handle</td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td>nvjpegJpegState_t jpeg_handle</td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td>const unsigned char *data</td>
<td>Input</td>
<td>Host</td>
<td>Pointer to the encoded stream.</td>
</tr>
<tr>
<td>size_t length</td>
<td>Input</td>
<td>Host</td>
<td>Size of the encoded stream.</td>
</tr>
<tr>
<td>int image_idx</td>
<td>Input</td>
<td>Host</td>
<td>Image index in the batch. Should be in the range from 0 to <code>batch_size-1</code>.</td>
</tr>
</tbody>
</table>
### `int thread_idx`

| Input | Host | Thread index that calls this phase. Should be in the range from 0 to `max_cpu_threads-1`. |

| `cudaStream_t stream` | Input | Host | The CUDA stream where all the GPU work will be submitted. |

### Returns:

- `nvjpegStatus_t` - An error code as specified in `nvJPEG API Return Codes`.

#### 4.4.5. `nvjpegDecodeBatchedPhaseTwo()`

This phase should be called once per batch. It should be called only after the `nvjpegDecodeBatchedPhaseOne()` calls for every image in the batch have finished. Any prior calls to `nvjpegDecodeBatchedPhaseTwo()` and `nvjpegDecodeBatchedPhaseThree()` for other batches with the same JPEG state handle parameter should be finished prior this call.

### Signature:

```c
nvjpegStatus_t nvjpegDecodeBatchedPhaseTwo(
    nvjpegHandle_t          handle,
    nvjpegJpegState_t       jpeg_handle,
    cudaStream_t            stream);
```

### Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>nvjpegHandle_t handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td><code>nvjpegJpegState_t jpeg_handle</code></td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td><code>cudaStream_t stream</code></td>
<td>Input</td>
<td>Host</td>
<td>The CUDA stream where all the GPU work will be submitted.</td>
</tr>
</tbody>
</table>

### Returns:

- `nvjpegStatus_t` - An error code as specified in `nvJPEG API Return Codes`.

#### 4.4.6. `nvjpegDecodeBatchedPhaseThree()`

This phase should be called once per batch. It should be called only after the `nvjpegDecodeBatchedPhaseTwo()` call for the same batch has finished.

Between a call to `nvjpegDecodeBatchedPhaseTwo()` and a call to this function, no calls are allowed to `nvjpegDecodeBatchedPhaseTwo()` or `nvjpegDecodeBatchedPhaseThree()` for any other batch with the same JPEG state handle parameter.
Signature:

```
nvjpegStatus_t nvjpegDecodeBatchedPhaseThree(
    nvjpegHandle_t            handle,
    nvjpegJpegState_t         jpeg_handle,
    nvjpegImage_t             *destinations,
    cudaStream_t              stream);
```

Parameters:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input / Output</th>
<th>Memory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvjpegHandle_t handle</td>
<td>Input</td>
<td>Host</td>
<td>The library handle.</td>
</tr>
<tr>
<td>nvjpegJpegState_t jpeg_handle</td>
<td>Input</td>
<td>Host</td>
<td>The image state handle.</td>
</tr>
<tr>
<td>nvjpegImage_t *destinations</td>
<td>Input/Output</td>
<td>Host/Device</td>
<td>Pointer to the first element of the array of output descriptors. The size of the array is assumed to be the batch_size parameter that was provided to the batch initialization function. See nvjpegImage_t description for details.</td>
</tr>
<tr>
<td>cudaStream_t stream</td>
<td>Input</td>
<td>Host</td>
<td>The CUDA stream to which all the GPU tasks will be submitted.</td>
</tr>
</tbody>
</table>

Returns:

```
nvjpegStatus_t - An error code as specified in nvJPEG API Return Codes.
```

### 4.5. `nvjpeg-api-return-codes`

The nvJPEG API adheres to the following return codes and their indicators:

```
typedef enum {
    NVJPEG_STATUS_SUCCESS = 0,
    NVJPEG_STATUS_NOT_INITIALIZED = 1,
    NVJPEG_STATUS_INVALID_PARAMETER = 2,
    NVJPEG_STATUS_BAD_JPEG = 3,
    NVJPEG_STATUS_JPEG_NOT_SUPPORTED = 4,
    NVJPEG_STATUS_ALLOCATOR_FAILURE = 5,
    NVJPEG_STATUS_EXECUTION_FAILED = 6,
    NVJPEG_STATUS_ARCH_MISMATCH = 7,
    NVJPEG_STATUS_INTERNAL_ERROR = 8,
} nvjpegStatus_t;
```

Description of the returned error codes:

<table>
<thead>
<tr>
<th>Returned Error (Returned Code)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>NVJPEG_STATUS_SUCCESS (0)</code></td>
<td>The API call has finished successfully. Note that many of the calls are asynchronous and some of the errors may be seen only after synchronization.</td>
</tr>
<tr>
<td><code>NVJPEG_STATUS_NOT_INITIALIZED (1)</code></td>
<td>The library handle was not initialized. A call to <code>nvjpegCreate()</code> is required to initialize the handle.</td>
</tr>
</tbody>
</table>
4.6. nvjpeg-chroma-subsampling

One of the outputs of the `nvjpegGetImageInfo()` API is `nvjpegChromaSubsampling_t`. This parameter is an `enum` type, and its enumerator list comprises of the chroma subsampling property retrieved from the encoded JPEG image. Below are the chroma subsampling types the `nvjpegGetImageInfo()` function currently supports:

```c
typedef enum
{
    NVJPEG_CSS_444,
    NVJPEG_CSS_422,
    NVJPEG_CSS_420,
    NVJPEG_CSS_440,
    NVJPEG_CSS_411,
    NVJPEG_CSS_410,
    NVJPEG_CSS_GRAY,
    NVJPEG_CSS_UNKNOWN
} nvjpegChromaSubsampling_t;
```

4.7. Reference Documents

Refer to the JPEG standard: https://jpeg.org/jpeg/
Chapter 5.
EXAMPLES OF NVJPEG

This package contains the library header and a set of libraries—static and shared. Shared libraries (the libnvjpeg.so and the respective versioned libraries) have all of the CUDA toolkit dependencies statically linked. However, if you want to link against the static library (libnvjpeg_static.a) you also need to link the other dependencies—for example dl, rt and thread libraries.

Example of linking shared library:

```bash
g++ -Icuda-linux64-nvjpeg/include -lnvjpeg -Lcuda-linux64-nvjpeg/lib64 my_example.cpp -o my_example
```

Example of linking static library:

```bash
g++ -Icuda-linux64-nvjpeg/include -lnvjpeg_static -ldl -lrt -pthread -Lcuda-linux64-nvjpeg/lib64 my_example.cpp -o my_example
```

Example

Below example shows how to use the various nvJPEG APIs.

Compile with the following command from the examples folder, assuming CUDA 9.0 is installed at the path /usr/local/cuda-9.0:

```bash
g++ -O3 -m64 nvjpeg_example.cpp -I../include -lnvjpeg -L../lib64 -I/usr/local/cuda-9.0/include -ldl -lrt -pthread -lcudart -L/usr/local/cuda-9.0/lib64 -Wl,-rpath=../lib64 -Wl,-rpath=/usr/local/cuda-9.0/lib64 -o nvjpeg_example
```

The below examples show how to decode the JPEG files using either single or batched API, and write the decoded files as BMP images.

To decode a single image:

```bash
./nvjpeg_example -i /tmp/my_image.jpg -fmt rgb -o /tmp
```

To decode multiple images in the folder using the batched API in separate phases:

```bash
./nvjpeg_example -i /tmp/my_images/ -fmt rgb -b 32 -pipelined -batched -o /tmp
```

Run the command ./nvjpeg_example -h for the description of the parameters.
Notice

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