

NVIDIA®

Particle-based Fluid Simulation

Simon Green
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Overview



- **Fluid Simulation Techniques**
- **A Brief History of Interactive Fluid Simulation**
- **CUDA particle simulation**
- **Spatial subdivision techniques**
- **Rendering methods**
- **Future**

Fluid Simulation Techniques

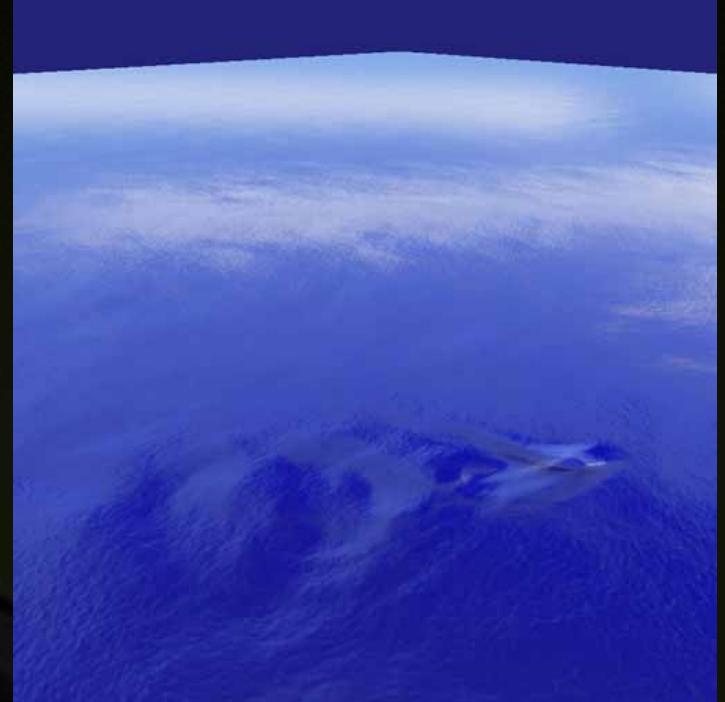


- **Various approaches:**
 - **Grid based (Eulerian)**
 - Stable fluids
 - Particle level set
 - **Particle based (Lagrangian)**
 - SPH (smoothed particle hydrodynamics)
 - MPS (Moving-Particle Semi-Implicit)
 - **Height field**
 - FFT (Tessendorf)
 - Wave propagation – e.g. Kass and Miller

History: 2D Waves



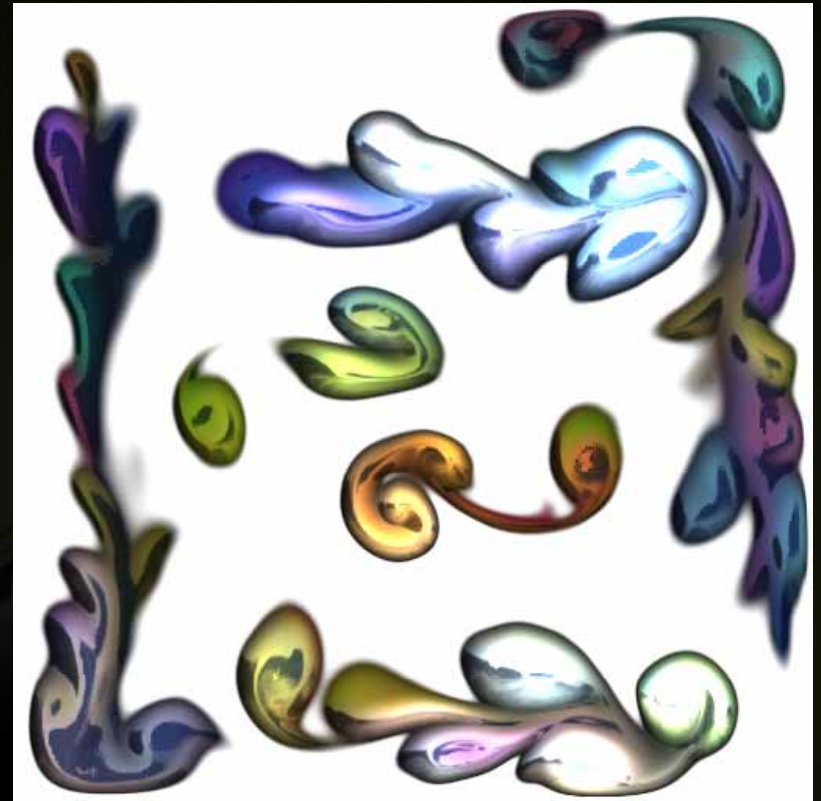
- Old demo-scene trick
- 2D wave equation
- First implemented on GPU by Greg James, 2003
- GeForce 3
- Pixel shader 1.1
- Used register combiners and texture shader
- 8-bit fixed point



2D Fluid Flow



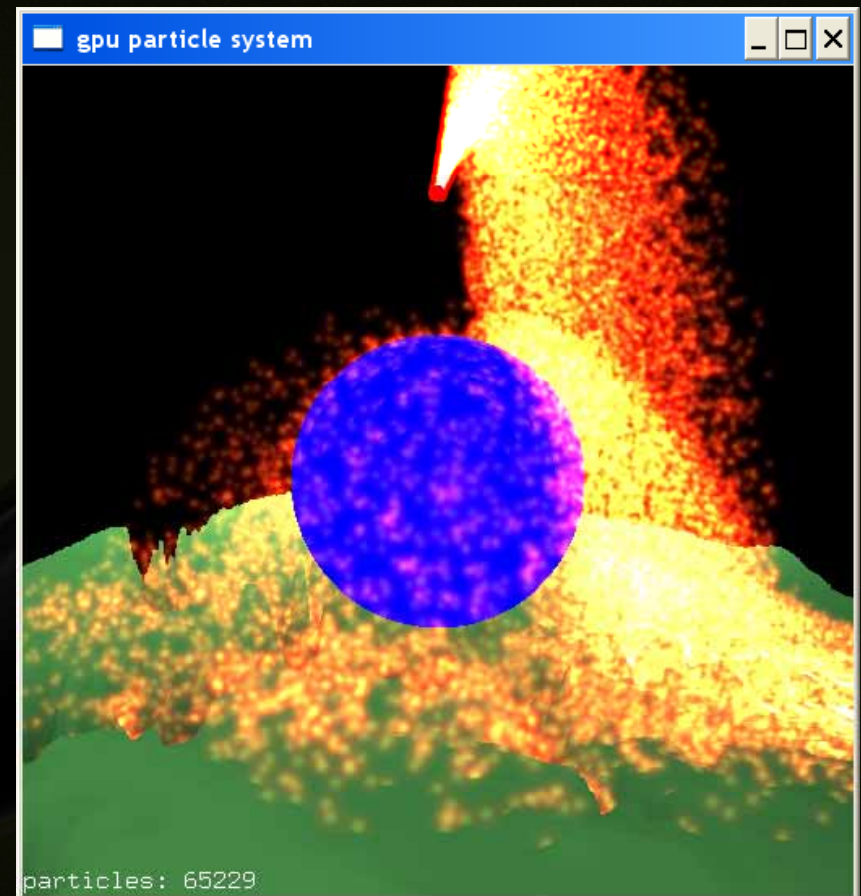
- Mark Harris, GPU Gems 1
- 2D Navier-Stokes solver
 - based on Jos Stam's Stable Fluids
- GeForce FX
- Used floating point textures
- Cg shaders
- Multiple passes to solve for pressure
- Texture interpolation used for advection step



GPU Particle Systems



- “Building a Million Particle System”, Lutz Latta, GDC 2004
- Position and velocity stored in FP textures
- Simple interactions with terrain height field and implicit shapes
- Emitters done on CPU
- Particles rendered using render-to-vertex array
- 1M particles at ~60fps



3D Fluids - Box of Smoke Demo



- G80 launch demo
- Written by Keenan Crane
- 3D Navier-Stokes solver
- Used tiled 2D textures
- Also tracked free surfaces for water
- BFECC advection scheme
- Ray cast rendering using pixel shader



NVIDIA SDK Smoke Demo



- 3D Navier-Stokes solver
- DirectX 10
- Used render to 3D texture
- Includes interaction with voxelized character



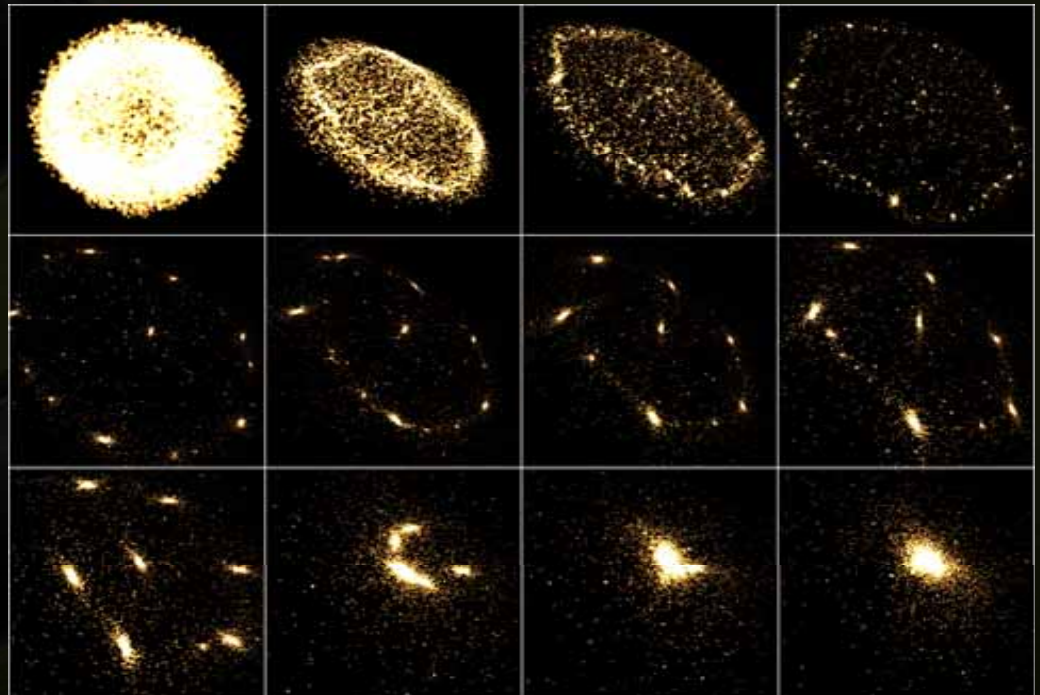
CUDA N-Body Demo



- Computes gravitational attraction between n bodies
- Computes all n^2 interactions
- Uses shared memory to reduce memory bandwidth

16K bodies @ 44 FPS
x 20 FLOPS / interaction
x $16K^2$ interactions /
frame
= 240 GFLOP/s

GeForce 8800 GTX



Particle Systems



- ***Particle Systems: A Technique for Modeling a Class of Fuzzy Objects, Reeves 1983***



Particle-based Fluid Simulation



Advantages

- Conservation of mass is trivial
- Easy to track free surface
- Only performs computation where necessary
- Not necessarily constrained to a finite grid
- Easy to parallelize

Disadvantages

- Hard to extract smooth surface from particles
- Requires large number of particles for realistic results

Particle Fluid Simulation Papers



- **Particle-Based Fluid Simulation for Interactive Applications, M. Müller, 2003**

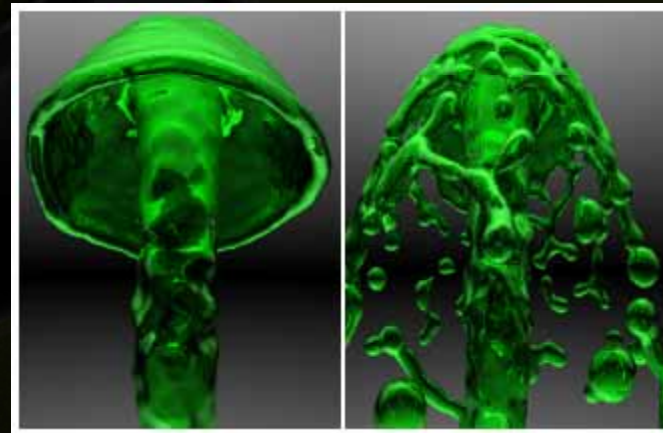
- **3000 particles, 5fps**



- **Particle-based Viscoelastic Fluid Simulation, Clavet et al, 2005**

- **1000 particles, 10fps**

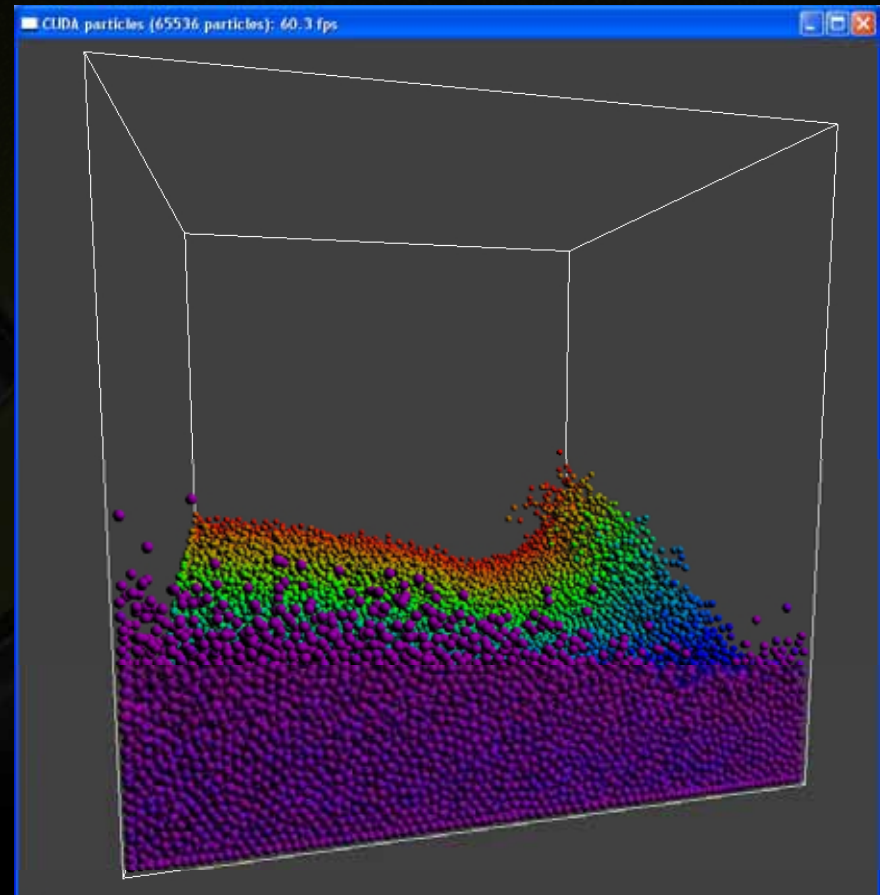
- **20,000 particles, 2 secs / frame**



CUDA SDK Particles Demo



- **Particles with simple collisions**
- **Uses uniform grid based on sorting**
- **Uses fast CUDA radix sort**
- **Current performance:
>100 fps for 65K
interacting particles
on 8800 GT**



Uniform Grid



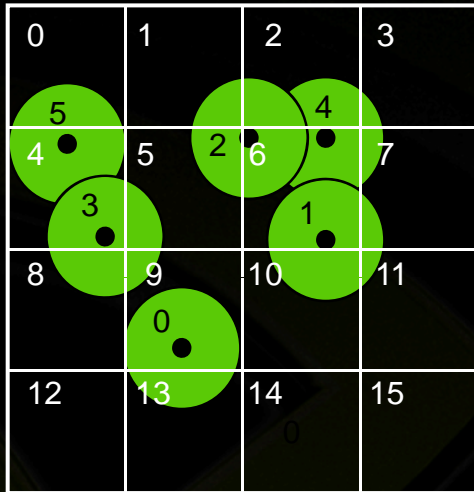
- Particle interaction requires finding neighbouring particles
- Exhaustive search requires n^2 comparisons
- Solution: use spatial subdivision structure
- Uniform grid is simplest possible subdivision
 - Divide world into cubical grid (cell size = particle size)
 - Put particles in cells
 - Only have to compare each particle with the particles in neighbouring cells
- Building data structures is hard on data parallel machines like the GPU
 - possible in OpenGL (using stencil routing technique)
 - easier using CUDA (fast sorting, scattered writes)

Uniform Grid using Sorting



- **Grid is built from scratch each frame**
 - Future work: incremental updates?
- **Algorithm:**
 - Compute which grid cell each particle falls in (based on center)
 - Calculate cell index
 - Sort particles based on cell index
 - Find start of each bucket in sorted list (store in array)
 - Process collisions by looking at $3 \times 3 \times 3 = 27$ neighbouring grid cells of each particle
- **Advantages**
 - supports unlimited number of particles per grid cell
 - Sorting improves memory coherence during collisions

Example: Grid using Sorting



unsorted list
(cell id, particle id)

0: (9, 0)
1: (6, 1)
2: (6, 2)
3: (4, 3)
4: (6, 4)
5: (4, 5)

sorted by
cell id

0: (4, 3)
1: (4, 5)
2: (6, 1)
3: (6, 2)
4: (6, 4)
5: (9, 0)

cell start

0: -
1: -
2: -
3: -
4: 0
5: -
6: 2
7: -
8: -
9: 5
10: -
...
15: -

Spatial Hashing (Infinite Grid)



- For games, we don't want particles to be constrained to a finite grid
- Solution: use a fixed number of grid buckets, and store particles in buckets based on hash function of grid position
- Pro: Allows grid to be effectively infinite
- Con: Hash collisions (multiple positions hashing to same bucket) causes inefficiency
 - Choice of hash function can have big impact
- See: “*Optimized Spatial Hashing for Collision Detection of Deformable Objects*”, Teschner et al.

Example Hash Function



```
__device__ uint calcGridHash(int3 gridPos)
{
    const uint p1 = 73856093;    // some large primes
    const uint p2 = 19349663;
    const uint p3 = 83492791;
    int n = p1*gridPos.x ^ p2*gridPos.y ^ p3*gridPos.z;
    n %= numBuckets;
    return n;
}
```

Smoothed Particle Hydrodynamics (SPH)



- Particle based fluid simulation technique
 - Originally developed for astrophysics simulations
- Interpolates fluid attributes over space using kernel functions
- For games, we can often get away with simpler simulations
 - combine soft particle collisions with attractive forces

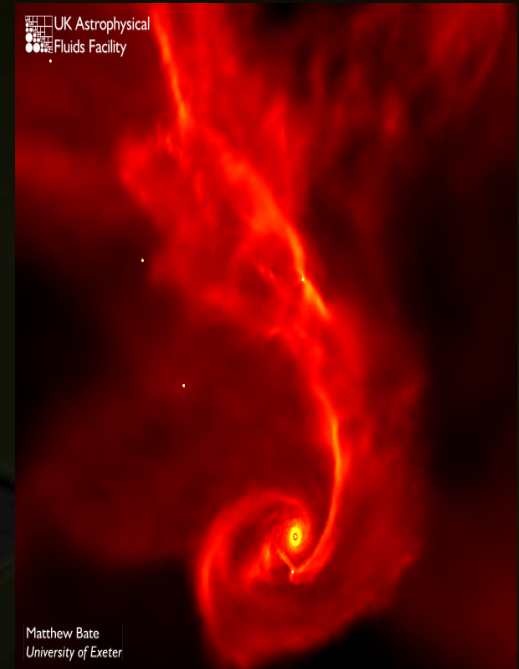


Image courtesy Matthew Bate

Fluid Rendering Methods



- 3D isosurface extraction (marching cubes)
- 2.5D isosurfaces (Ageia screen-space meshes)
- 3D texture ray marching (expensive)
- Image-space tricks (blur normals in screen space)

Marching Cubes



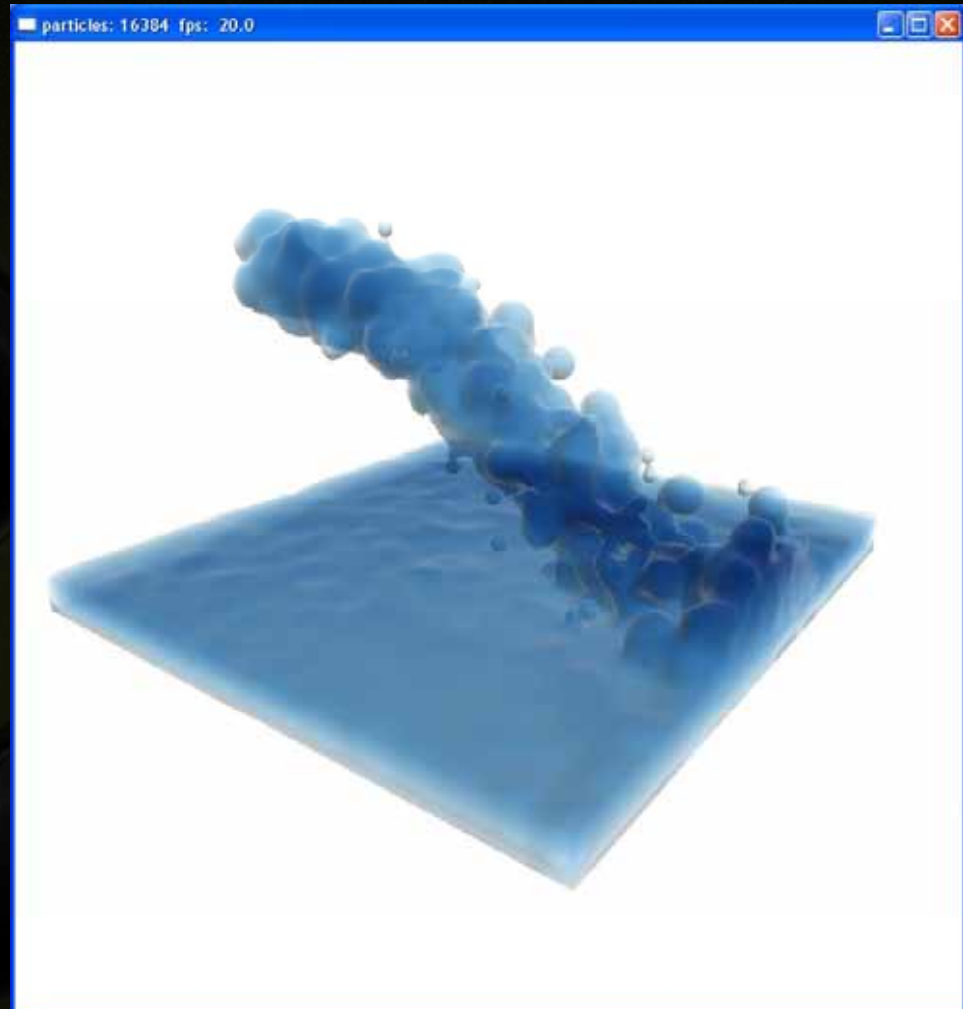
- Standard method for extracting isosurfaces from volume data
- CUDA marching cubes uses scan functions from CUDPP library for stream compaction
 - Up to 8x faster than OpenGL geometry shader implementation using marching tetrahedra
- But still requires evaluating field function at every point in space
 - E.g. $128^3 = 2\text{M}$ points
 - Very expensive



Ray Marching



- Volume rendering technique
- Voxelize particles into 3D texture
 - Requires several passes for thickness
- Ray march through 3D texture in pixel shader
 - Can shade based on optical thickness
- Very fill intensive

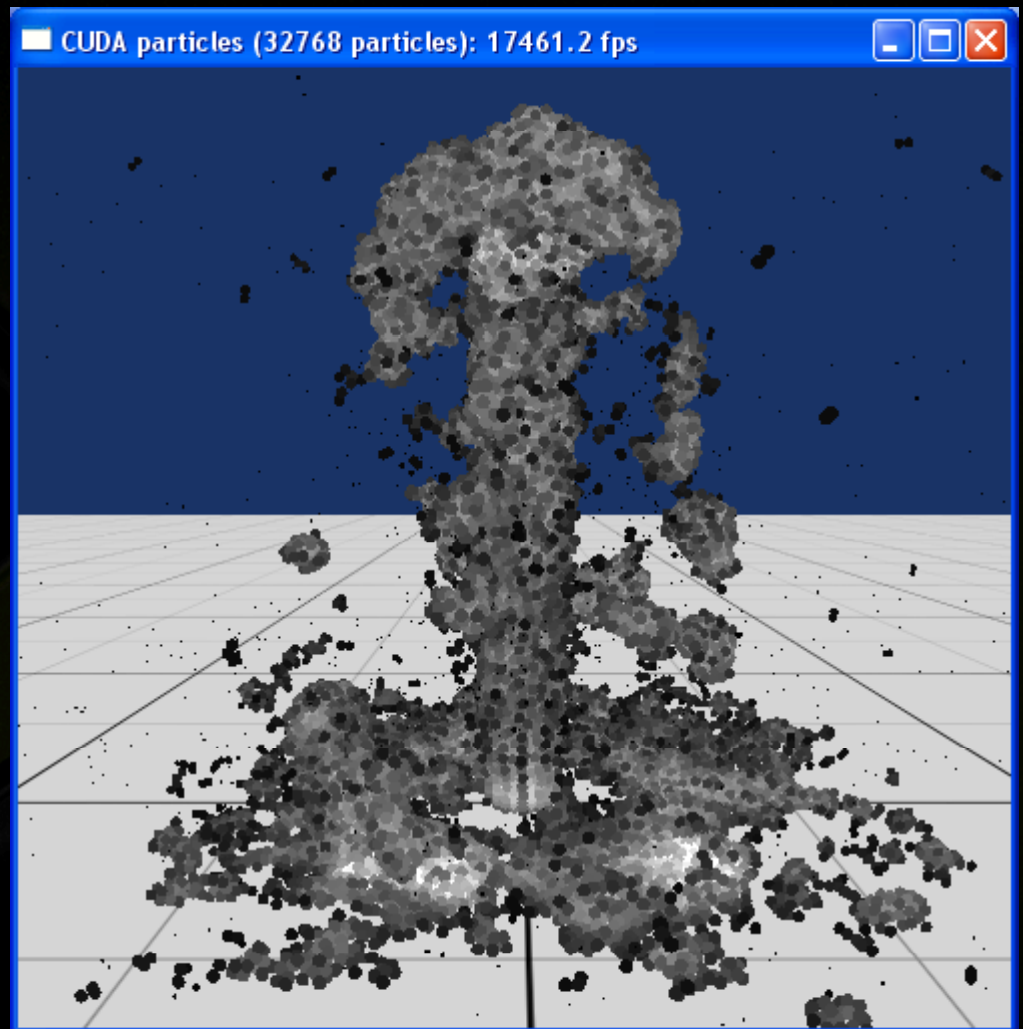


Density-based Shading

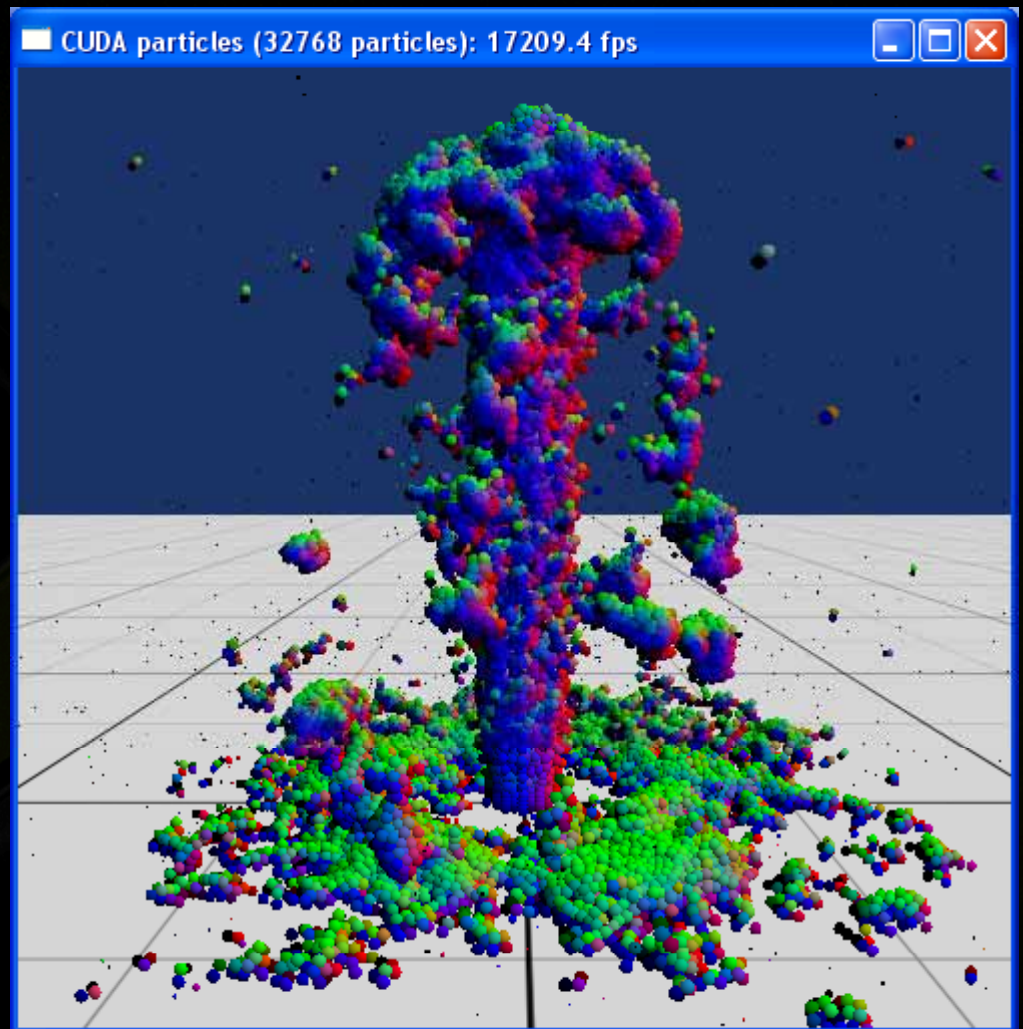


- **Can calculate per-particle density and normal based on field function**
 - **SPH simulations often already have this data**
 - **Usually need to look at a larger neighbourhood (e.g. 5x5x5 cells) to get good results – expensive**
- **Can use density and normal for point sprite shading**
- **Normal only well defined when particles are close to each other**
 - **treat isolated particles separately – e.g. render as spray**

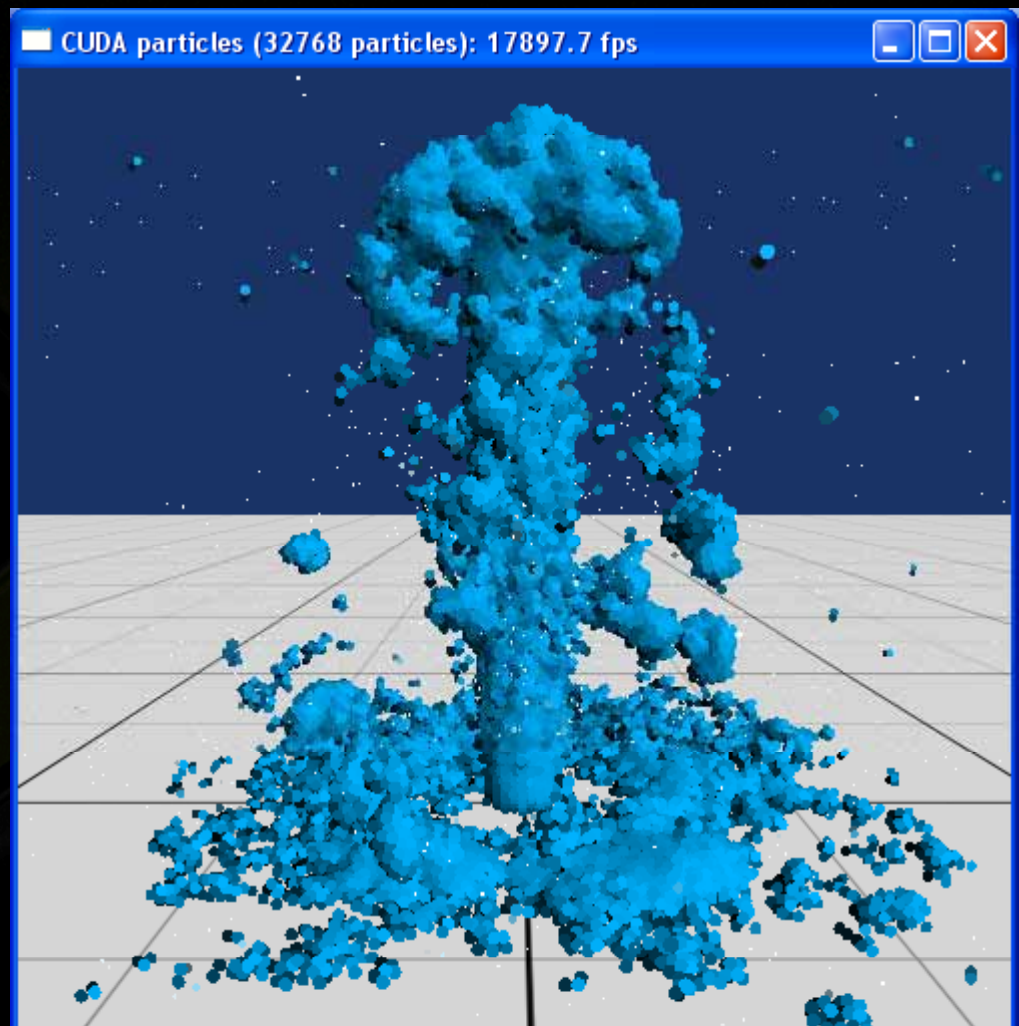
Particle Density



Particle Normal



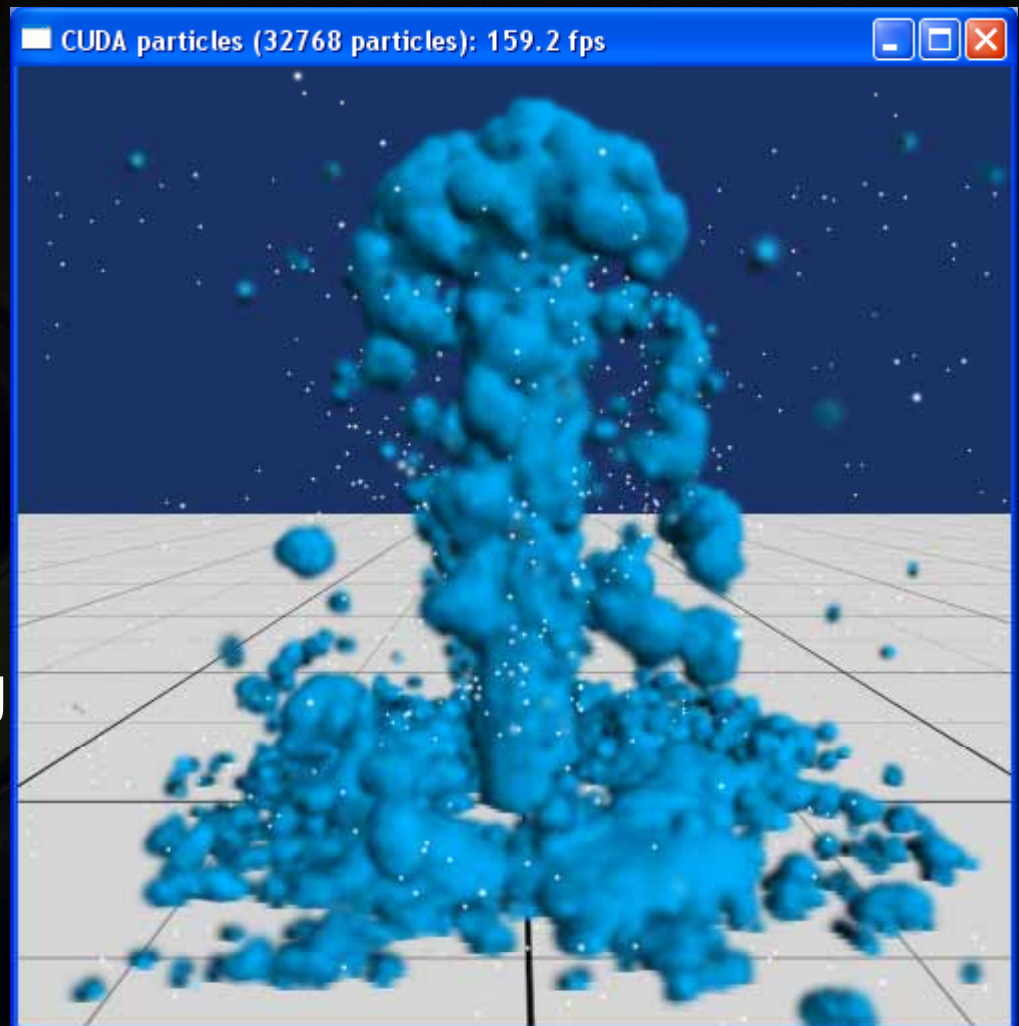
Flat Shaded Point Sprites



Blended Points Sprites (Splats)



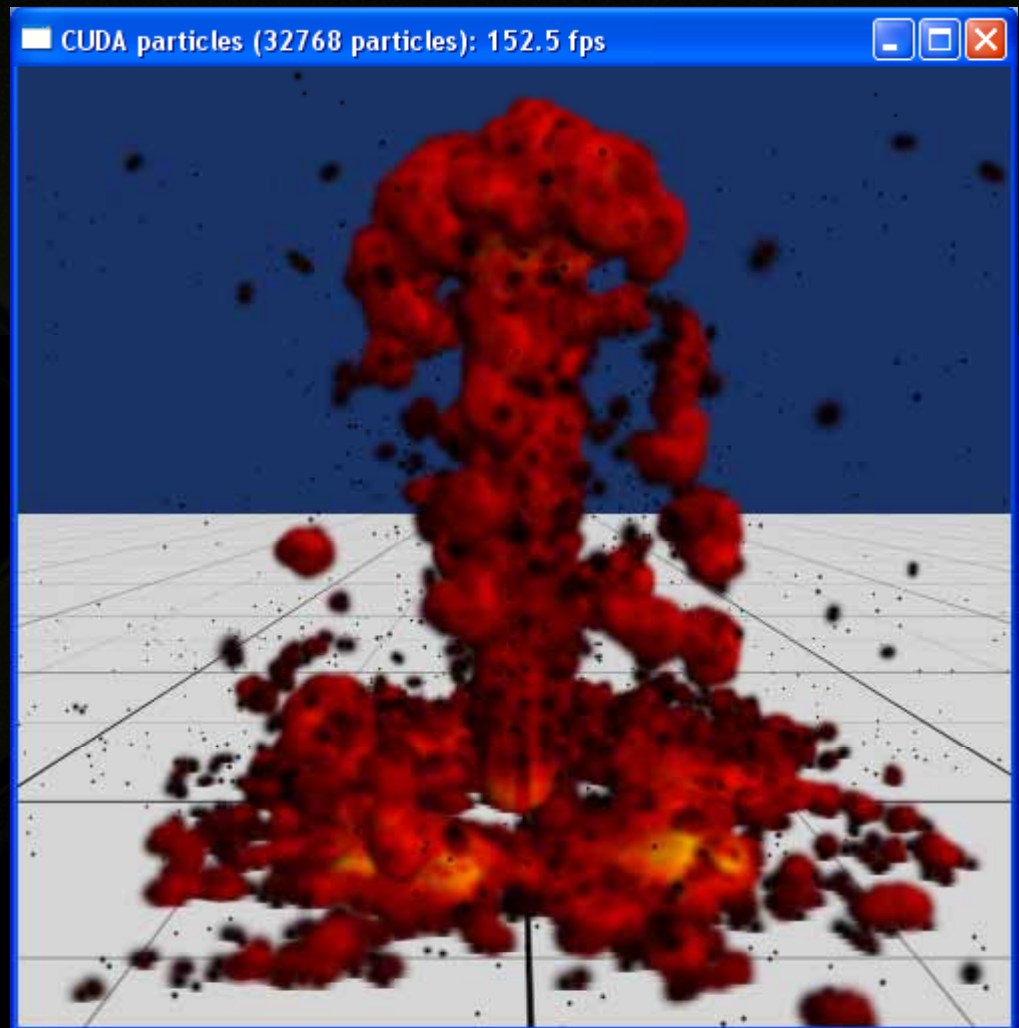
- Scale up point size so they overlap
- Add alpha to points with Gaussian falloff
- Requires sorting from back to front
- Has effect of interpolating shading between points
- Fill-rate intensive, but interactive



Alternative Shading (Lava)



- Modifies particle color based on density



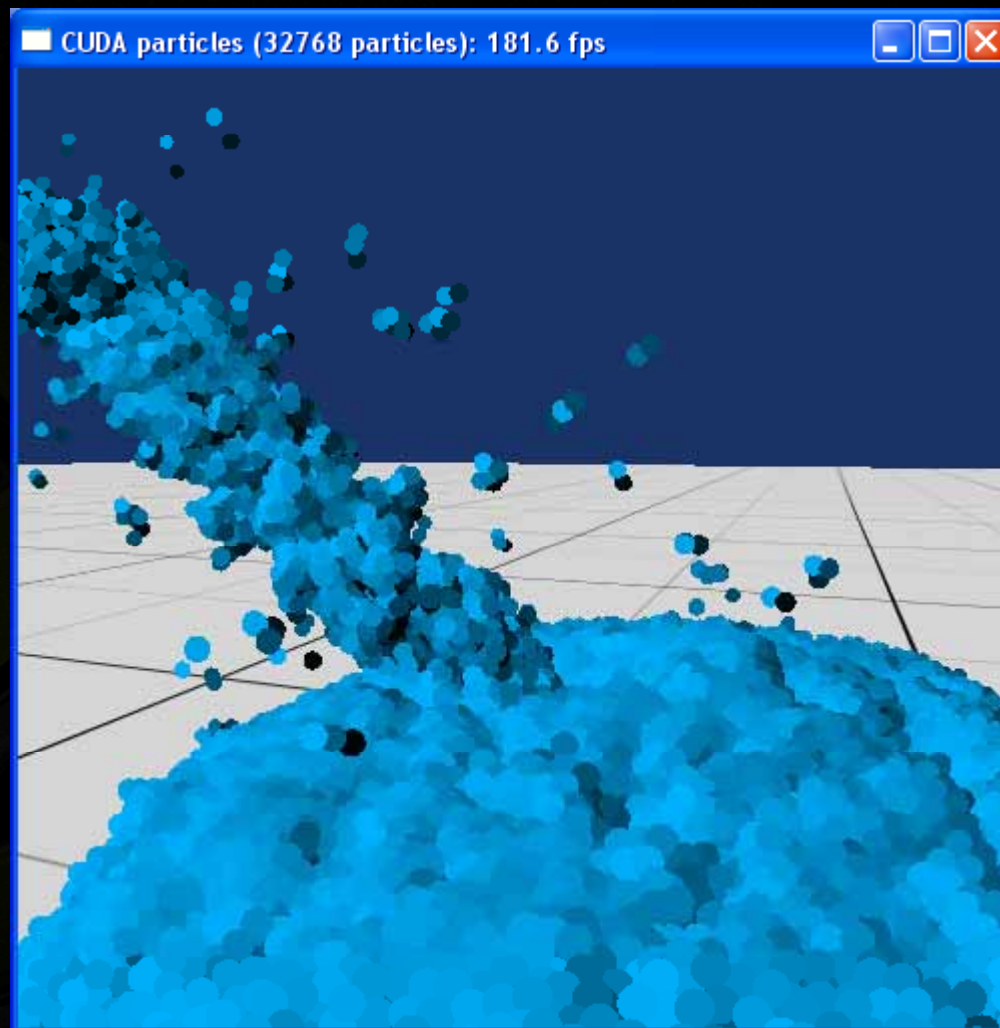
Motion Blur



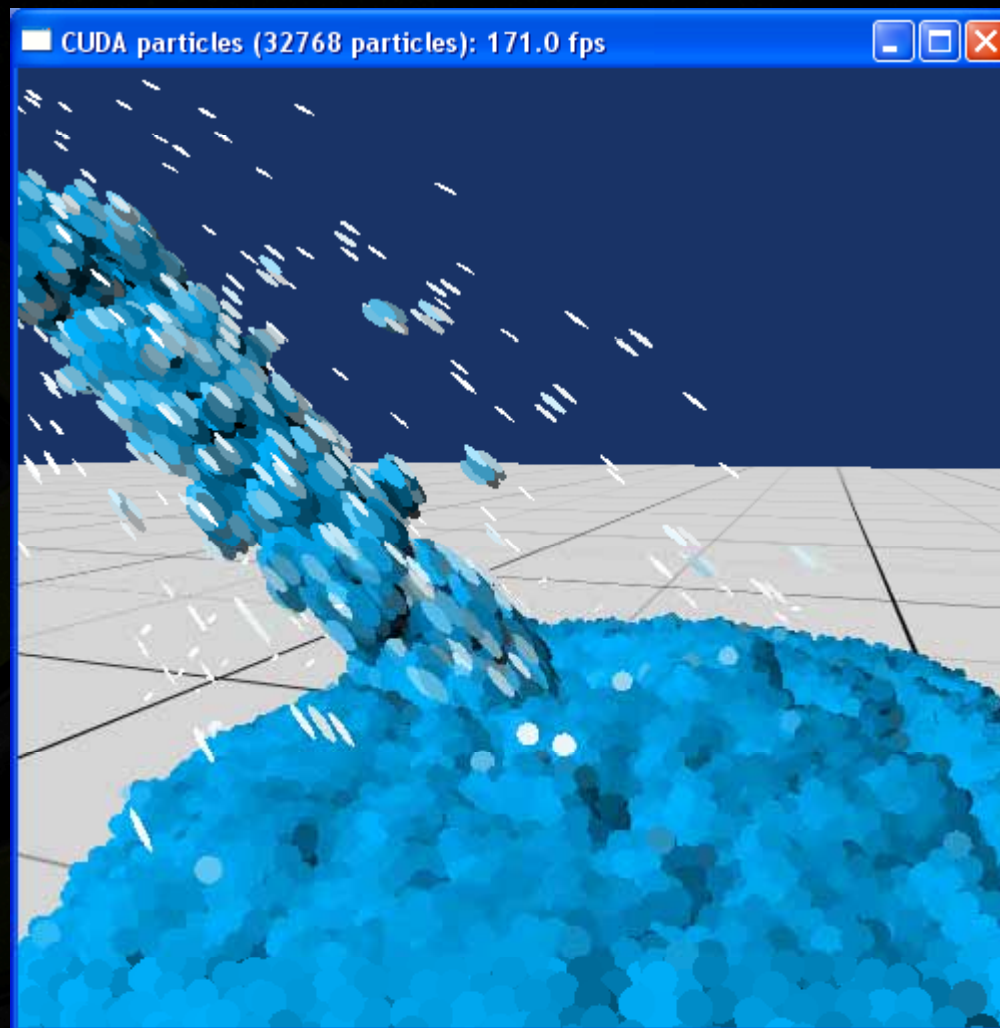
- Create quads between previous and current particle position
 - Using geometry shader
- Try and orient quad towards view direction
- Improves look of rapidly moving fluids (eliminates gaps between particles)



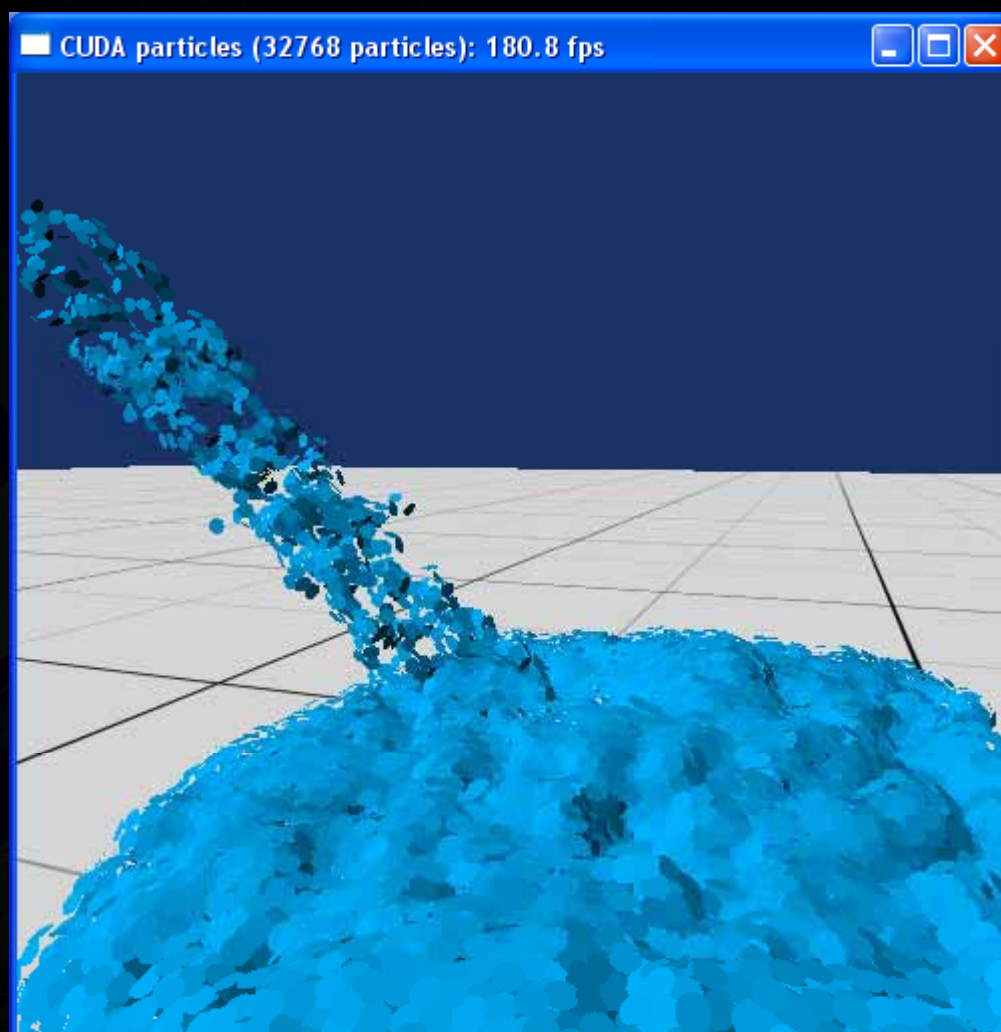
Spheres



Motion Blurred Spheres



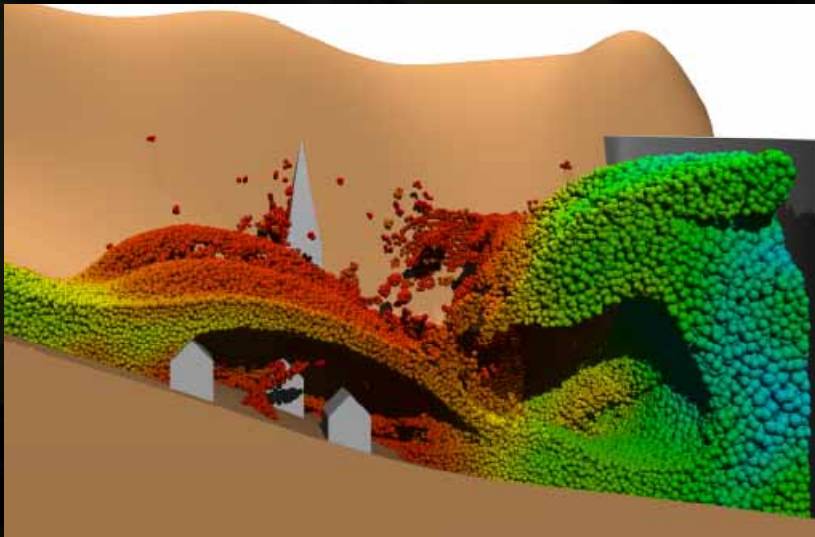
Oriented Discs



The Future



- Practical game fluids will need to combine particle, height field, and grid techniques
- GPU performance continues to double every 12 months



Adaptively Sampled Particle Fluids, Adams 2007



Two way coupled SPH and particle level set fluid simulation, Losasso, F., Talton, J., Kwatra, N. and Fedkiw, R