Physical Simulation on GPUs

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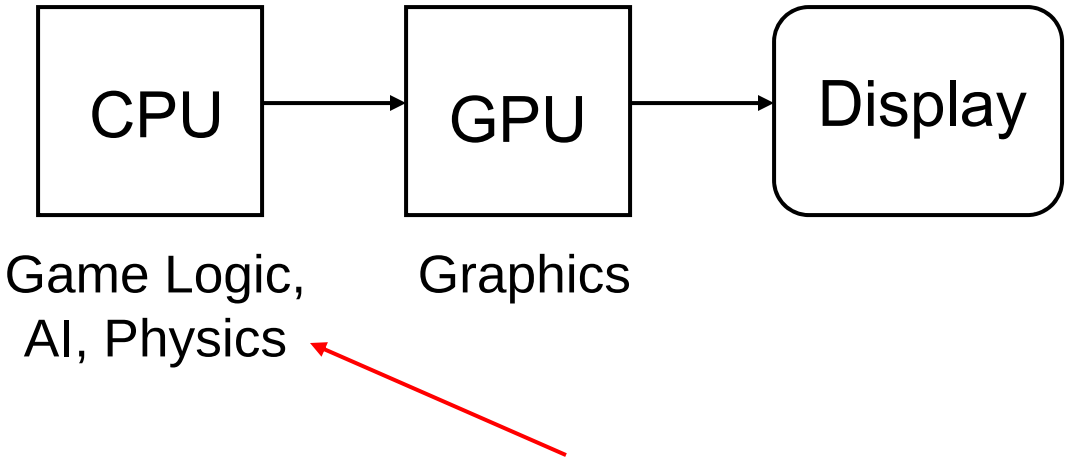
Physics on GPU

- Topics of discussion
  - Ways of parallelizing physics
  - Examples of GPU physics
  - CUDA and you

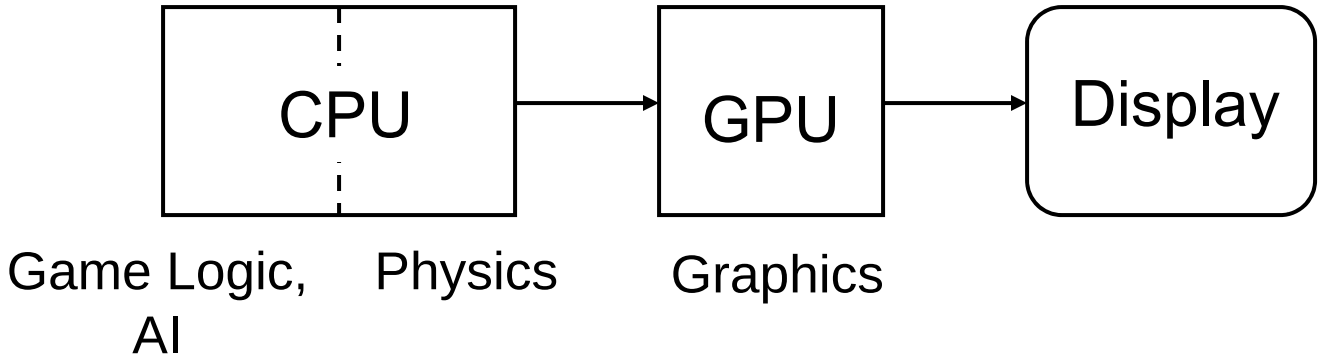
Parallelizing Physics

- What we've talked about so far



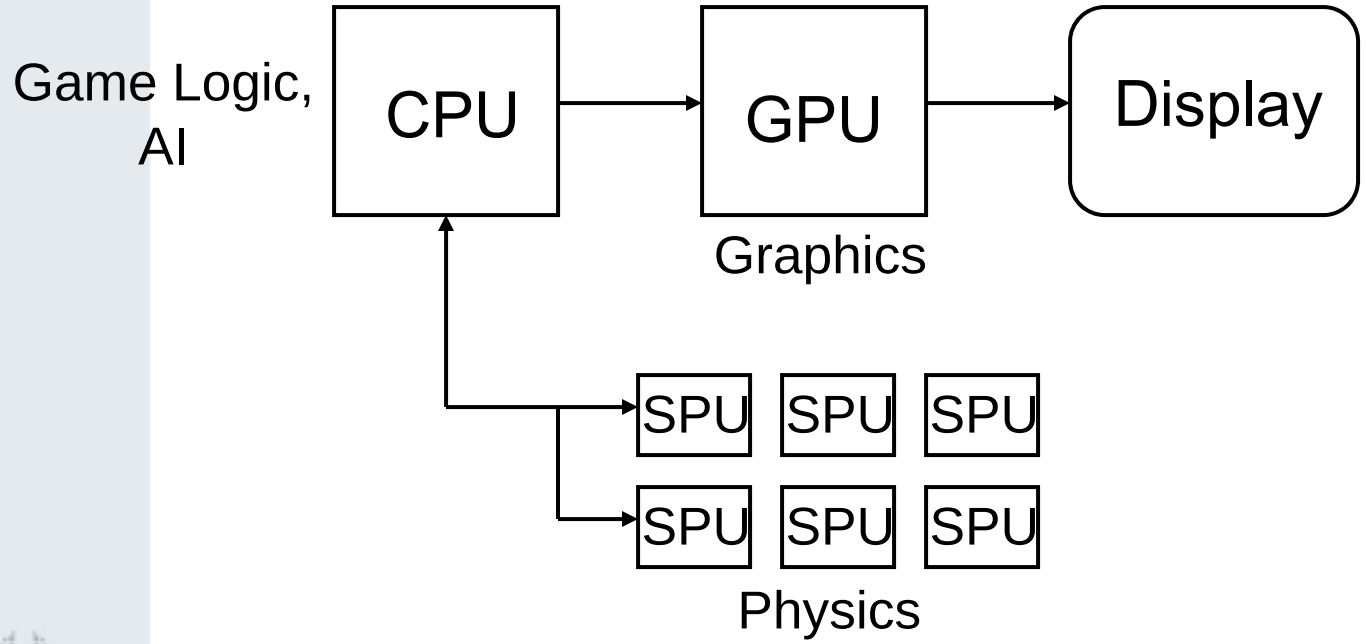
Parallelizing Physics

- Solution 1: Multicore CPU



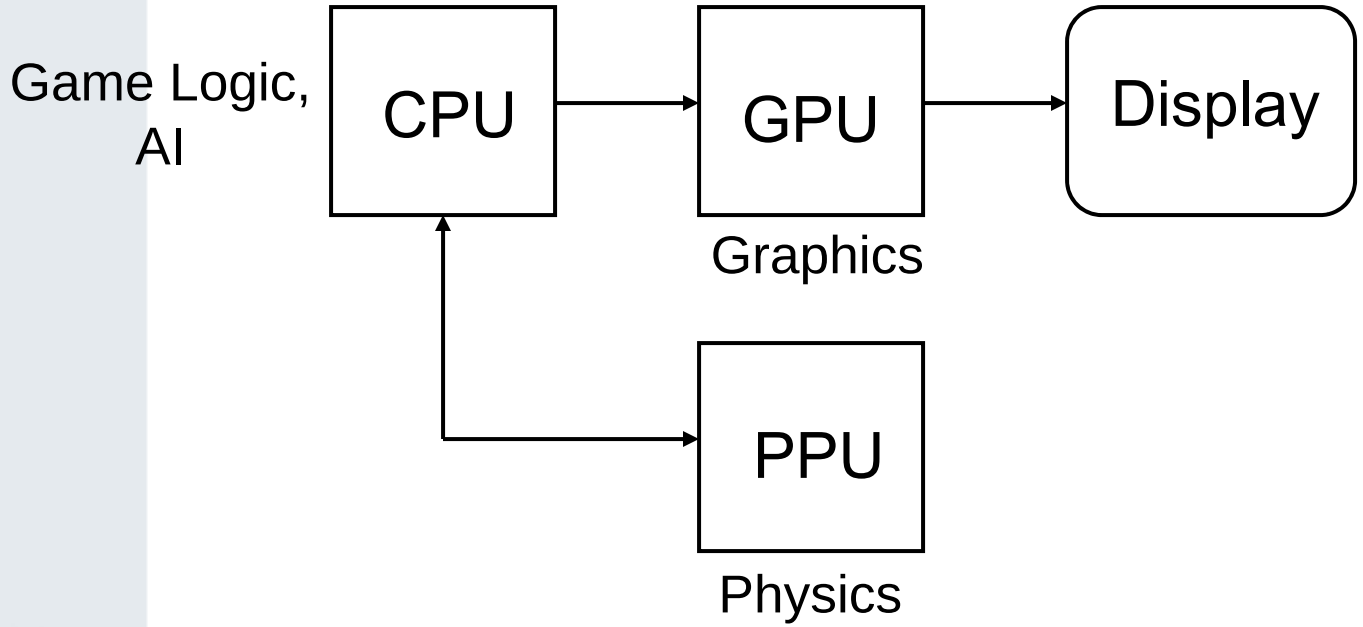
Parallelizing Physics

- Solution 2a: Cell processor



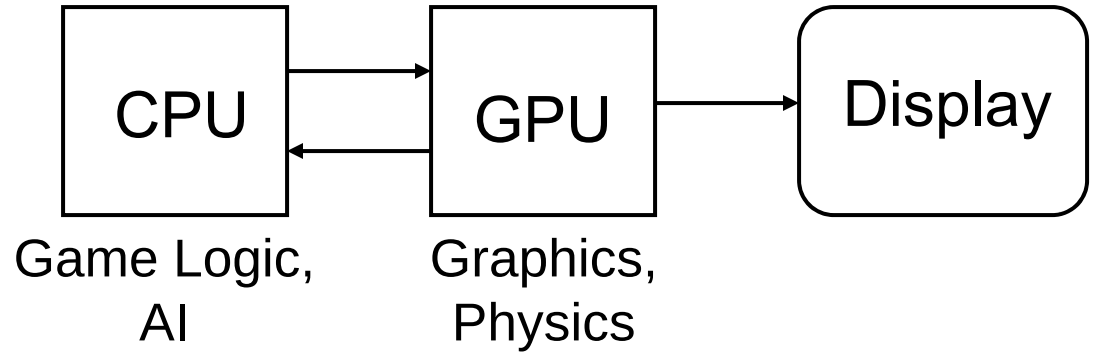
Parallelizing Physics

- Solution 2b: AGEIA processor



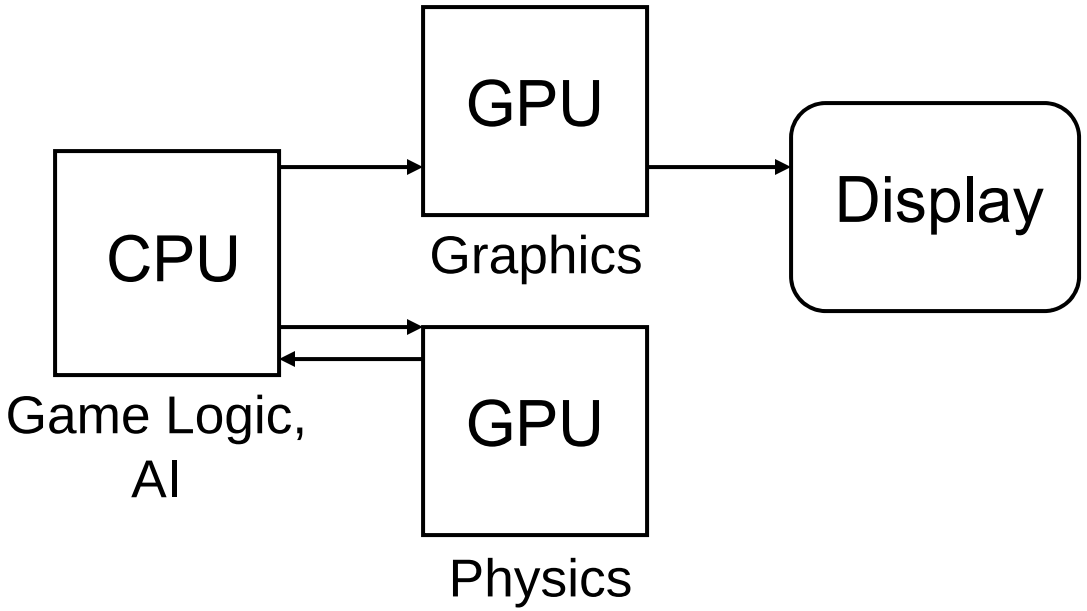
Parallelizing Physics

- Solution 3: Programmable GPU



Parallelizing Physics

- Solution 3b: SLI



GPU Computing

- Modern GPU has many independent processors:
  - GeForce 8800 GTX: 128 SPs
  - GeForce 8800 GT: 112 SPs
- Mostly processing power, not cache:
  - GeForce 8800 GTX: 300-400 Gflops
  - GeForce 8800 GT: 500 Gflops
- A lot of parallel power for physics!

GPU Physics Example

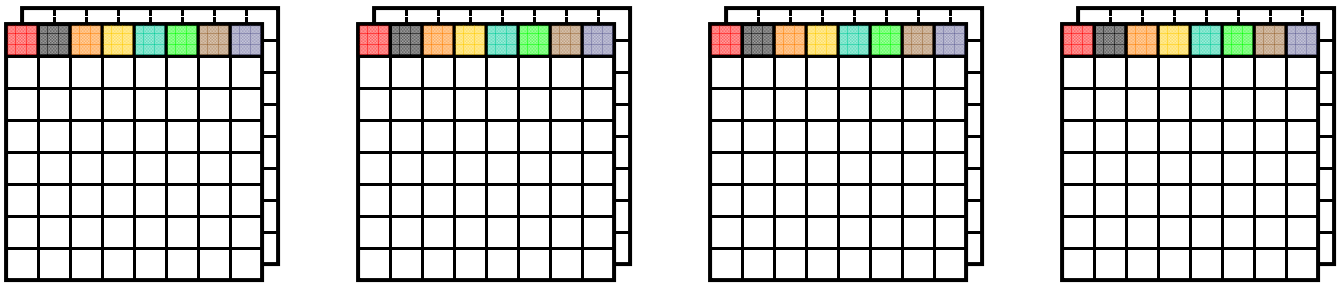
- From GPU Gems 3
- Takahiro Harada, “Real-time Rigid Body Simulation on GPUs”
- Simple physics engine, all running on GPU

GPU Physics Example

- Idea: GPU is good at:
  - Many similar computations
  - Simple data
- So:
  - Particles for collision representation
  - Grid for collision detection
  - Simple collision response

Object Representation

- Global object data in texture pairs

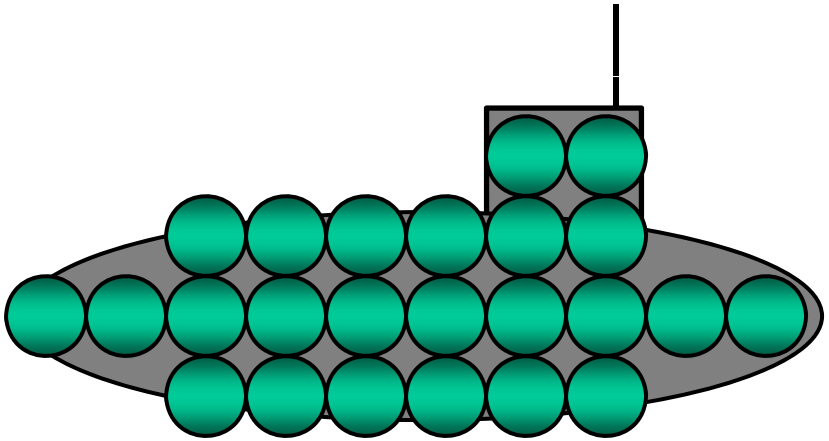


Position | Orientation | Linear Momentum | Angular Momentum

- Alternate frame to frame

Object Representation

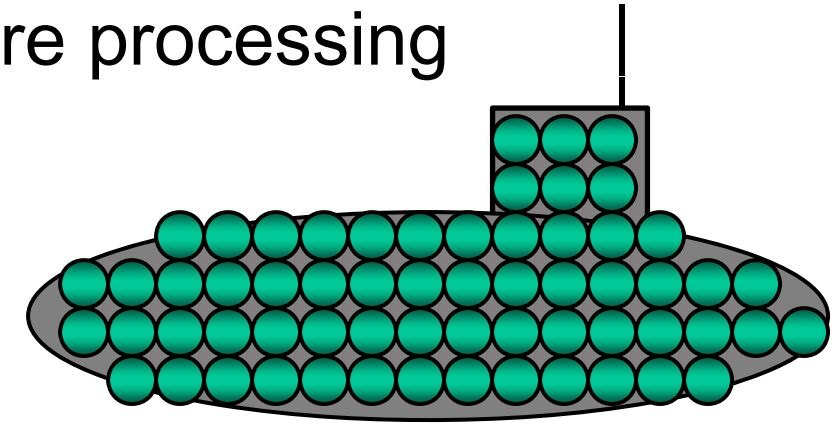
- Collision rep: Solid (or shell) of particles



- Store as
  - Fixed radius
  - Displacement from center of mass

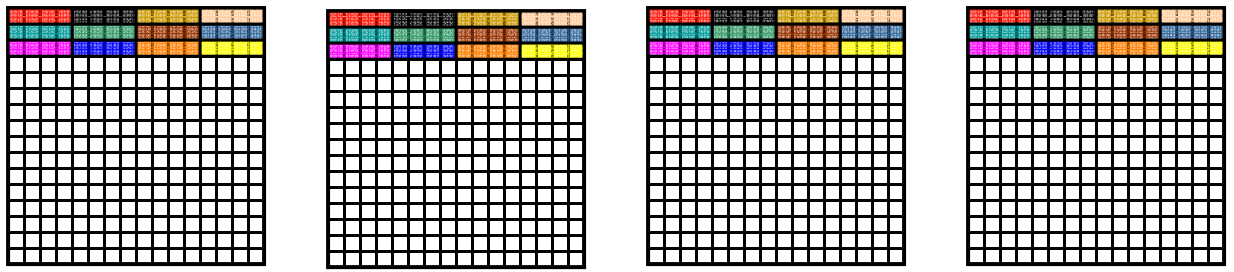
Object Representation

- Smaller particles == better fit
- But more processing



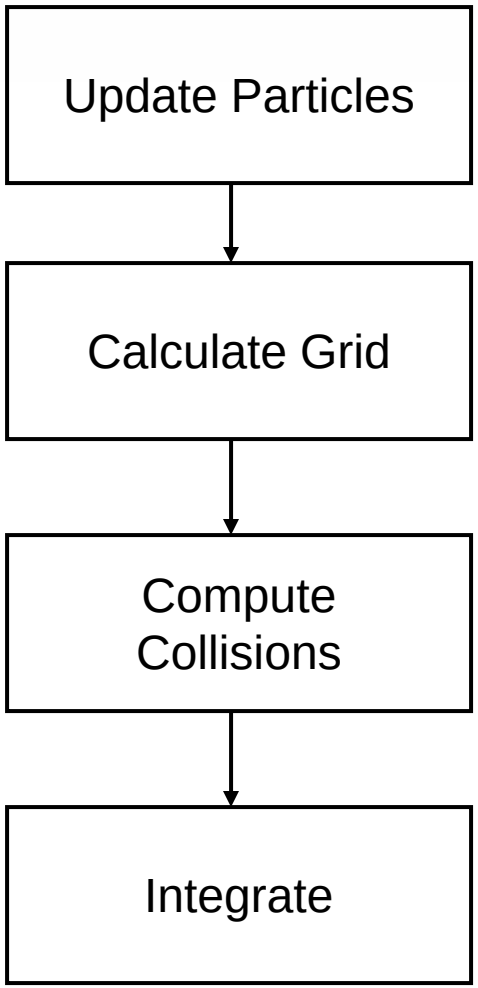
Object Representation

- Particle data stored in texture and three rendertargets



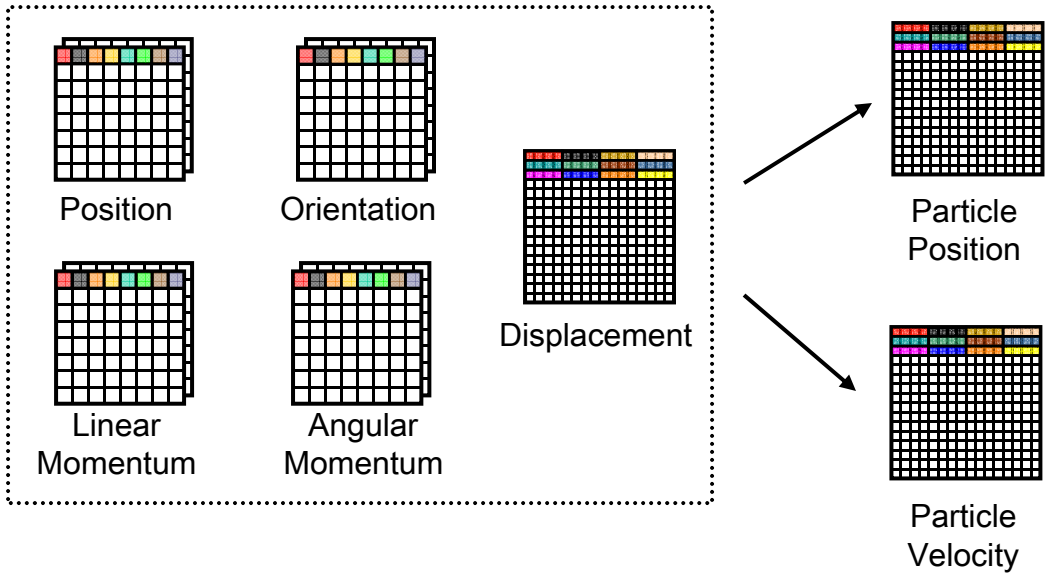
- Update position, velocity each frame from global object data
- Update force from collisions

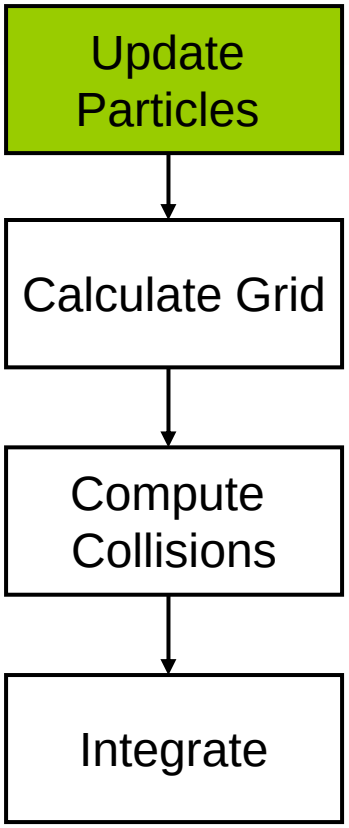
Pipeline



Update Particles

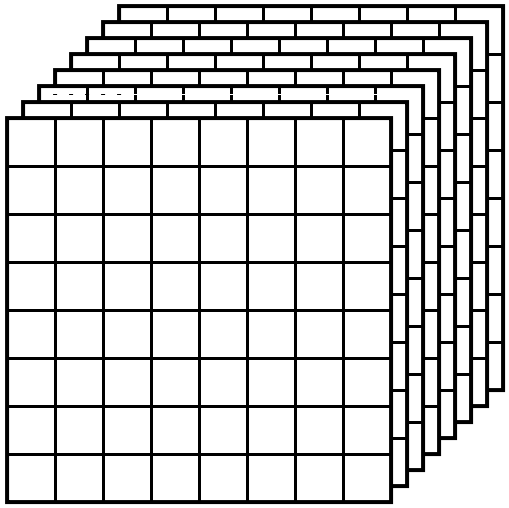
- For each object do:
  - Iterate through all particles
  - Update particle position, velocity



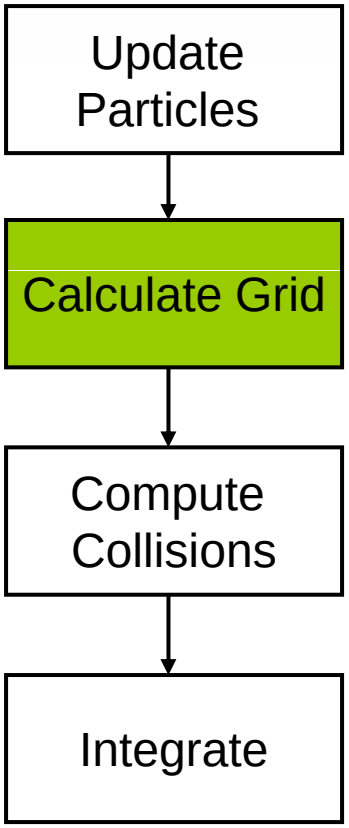


Grid Representation

- Stored as slabs within 2D rendertarget

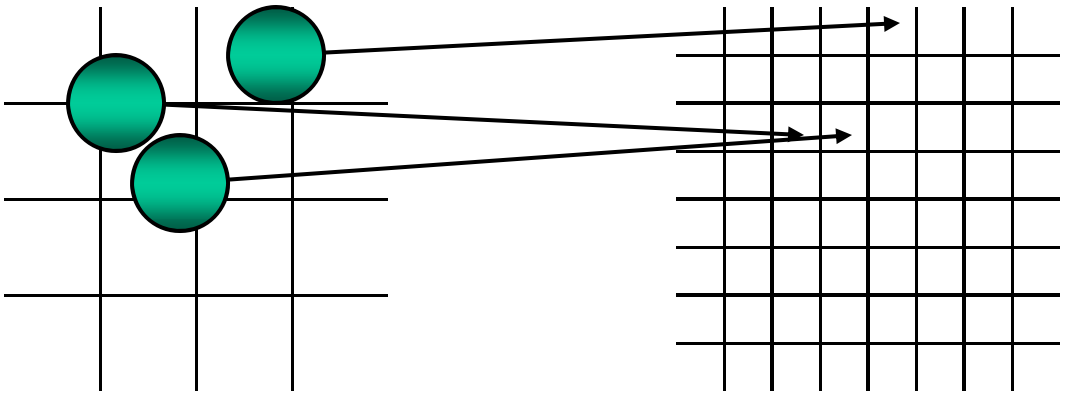


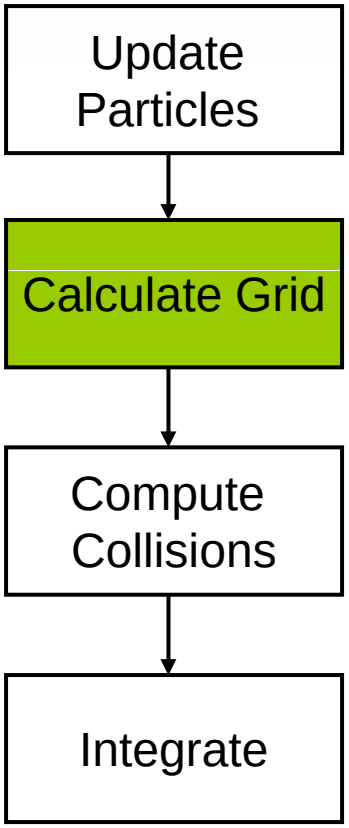
- Voxel stored as texel
- Four particle indices per texel



Grid Creation

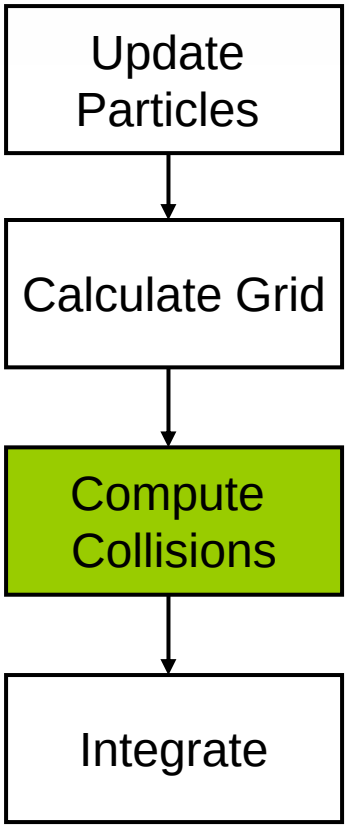
- For each particle do
  - Compute grid index
  - Write particle index to appropriate component at that location





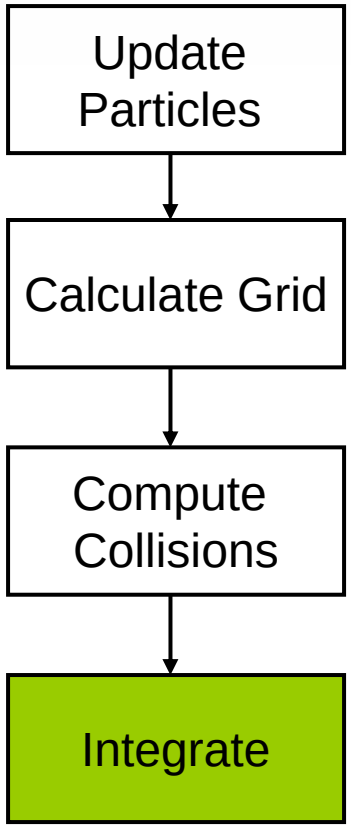
Collision Resolution

- For each voxel do
  - For each particle in voxel do
    - Compute force based on particles in this and 27 neighboring voxels
    - Regardless of collision!
      - Spring force
      - Damping from relative vel.
      - Tangential force

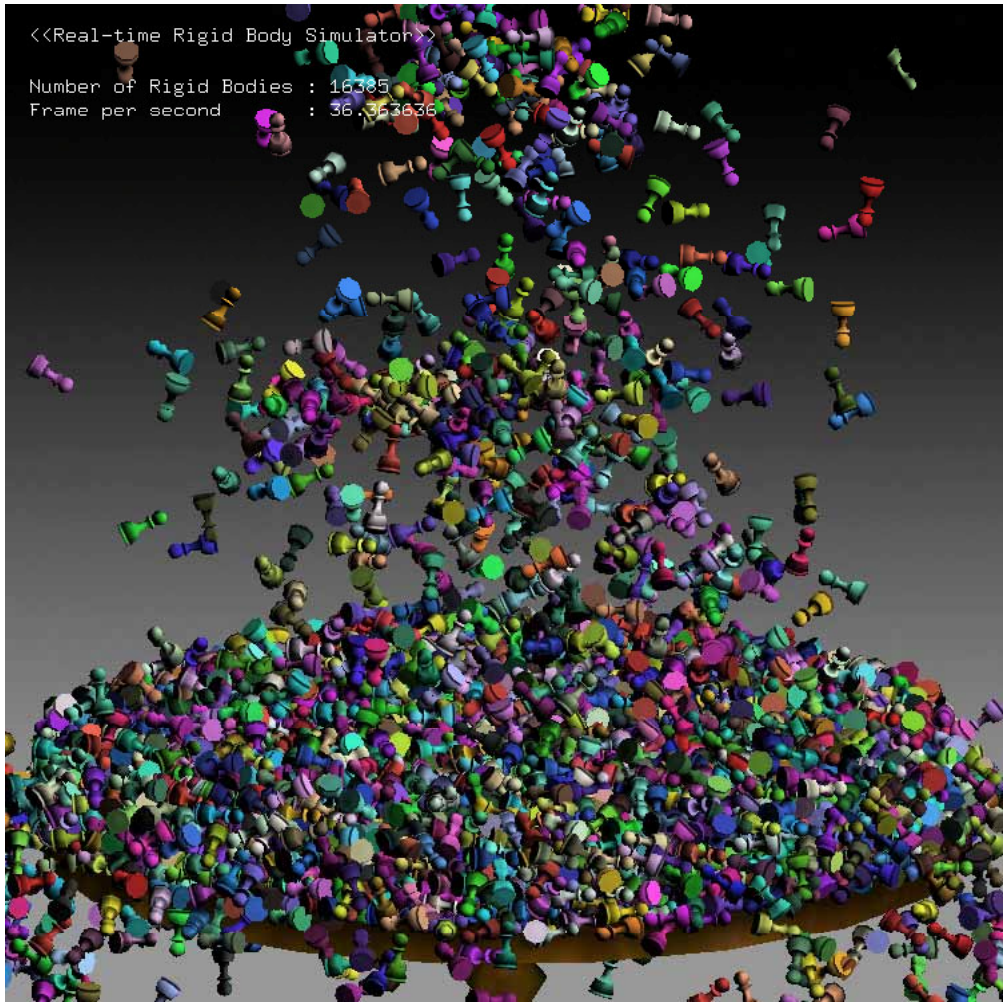


Integration

- Compute new linear and angular momenta based on collision (and other) forces
  - Force/torque on rigid body is weighted sum of forces from each particle
- Compute new position and orientation from momenta



Demo



Other approaches

- Simon Green's particles
- Nyland, Harris and Prins: N-body sim.
- Parallelize one piece:
  - Ex. Broad Phase (from GPU Gems 3)
- Do smaller problem
  - Ex. Fluid dynamics (Hellfire: London)

GPU Computing

- How to program?
- In the past had to use Cg, GLSL, HLSL
- Problems:
  - Requires specialized shader knowledge
  - Data is often texture or rendertarget
  - Can’t “scatter” data easily

CUDA

- Solution is CUDA
- Stands for Compute Unified Device Architecture
- Extensions on C/C++
- Interoperable with D3D and OpenGL
- www.nvidia.com/cuda
- Use it!

CUDA

- Updating our example:
  - Instead of Cg, use standard C++ w/CUDA extensions
  - Instead of textures or rendertargets, just use CUDA arrays
  - Instead of vertex shader, use scatter operation

References

Takahiro Harada. “Real-Time Rigid Body Simulation on GPUs.” In *GPU Gems 3*, Hubert Nguyen, ed., Addison-Wesley, 2007.

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NVIDIA CUDA Compute Unified Device Architecture Programming Guide Version 1.1, November 2007.