Large Graph on multi-GPUs

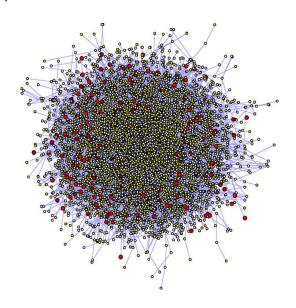
Enrico Mastrostefano¹ Massimo Bernaschi² Massimiliano Fatica³

¹Sapienza Università di Roma ²Istituto per le Applicazioni del Calcolo, IAC-CNR, Rome, Italy ³NVIDIA Corporation

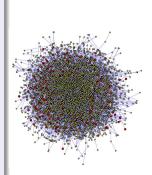
May 11, 2012

Outline

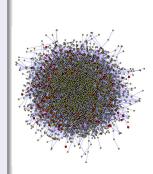
- Large Graphs and Supercomputing
- @ Graph500 on multi-GPUs
- Breadth First Search on multi-GPUs
- Sort-Unique Breadth First Search
- 6 Results



 Most of graph algorithms have low arithmetic intensity and irregular memory access patterns



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- Large-scale benchmark for data-intensive application
- "This is the first serious approach to complement the Top 500 with data-intensive applications ..." (from www.graph500.org)

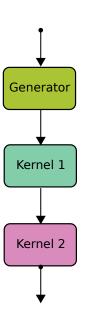


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- How do modern architectures perform running such algorithms?
- Large-scale benchmark for data-intensive application
- "This is the first serious approach to complement the Top 500 with data-intensive applications ..." (from www.graph500.org)
- The core of the benchmark is a set of graph algorithms



Generator

- Generate the edge list with real-world properties (RMAT generator).
- minimum size: 2²⁸ vertices and 16 * 2²⁸ edges (268, 435, 456 vertices and 8, 589, 934, 592 edges)

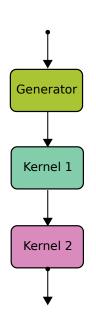


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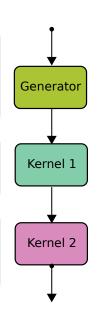
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Kernel 2

- Perform a Breadth First Search (BFS) visit starting from a random vertex: timed!
- Output the parent array.



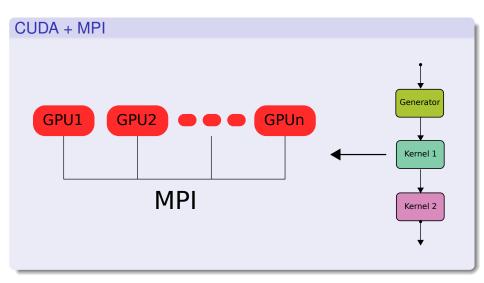
Outputs

- Execution time of K1
- Execution time of K2,
- TEPS: Traversed Edges Per Second in the BFS (actually the ranking is based only on TEPS)

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graph500 on multi-GPUs



Generate the edge list

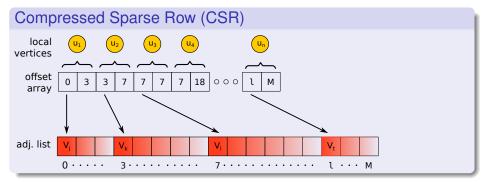
Edge list

- We have to generate: $|V| = 2^{SCALE}$; $|M| = 16 * 2^{SCALE}$
- Each task generates a subset of the edge list in the form: $(U_0, V_0), (U_1, V_1), ...$
- Edges are assigned to processes via a simple rule: edge $(U_i, V_i) \in P_k$ if $U_i \mod \#P == k$

Build the data structure

Data structure

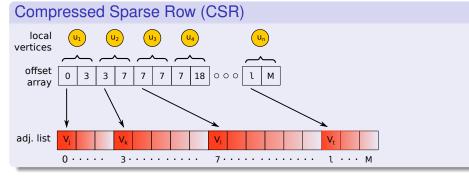
- We transform the edge list in a Compressed Sparse Row (CSR) data structure
- CSR is simple and has minimal memory requirements



Build the data structure

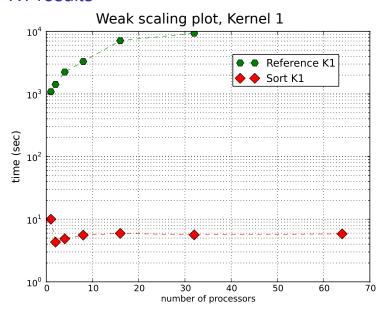
Data structure

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The core of the algorithm is a sort

K1 results

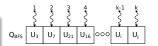


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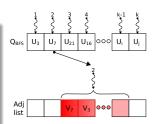
- Each vertex U_i of Q_{BFS} is assigned to one thread t_i
- Each thread t_i visits all the neighboring V_j of its vertex
- If V_i is local: visit it

- if V_i is not local: send to its owner
- ullet receive vertices V_k from other processes



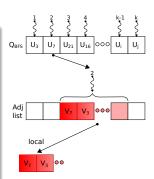
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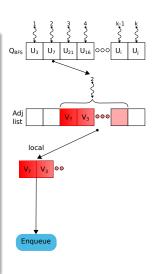


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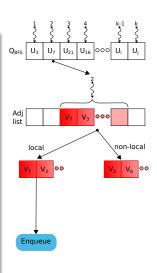
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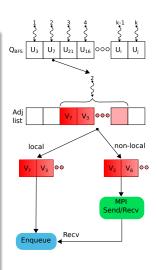
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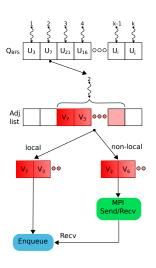
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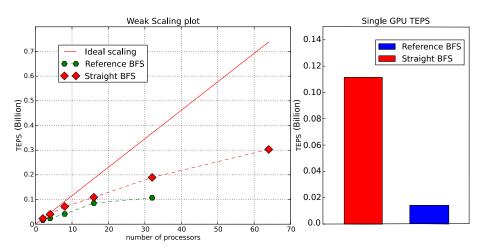
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- Output parent array and TEPS

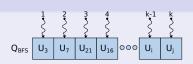


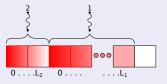
Straightforward BFS: Results



Gpu-related issues

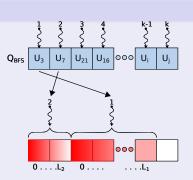
 Threads workloads are unbalanced when threads visit different adjacency lists





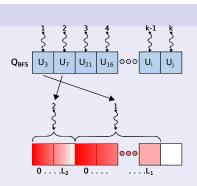
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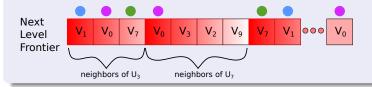
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Algorithms rely on the use of **Atomic Add**

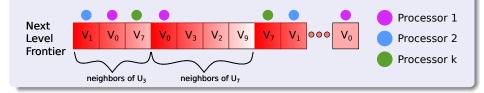
MPI-related issues

- We don't process non-local vertices so the array to send contains multiple copies of the same vertices.
- Multiple copies of the same vertex are sent to the owner.



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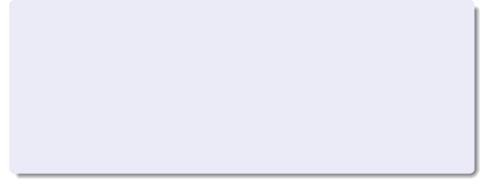
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Beyond the straightforward BFS



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- We want to use as many threads as the number of neighbors
- Neighbors of U are not-contiguous in the Adjacency list array
- We want a contiguous array of neighbors.
- We send/recv multiple copies
- We want to prune the array that we send

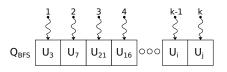
Beyond the straightforward BFS: Sort-Unique BFS overview

What we will do is:

- Occupate the total number of neighbors, say *m*
- Start m threads, read the Adjacency list and build a contiguous array of neighbors (We call this array Next Level Frontier)
- With m threads prune the Next Level Frontier
- Exchange vertices with other processes and update the parent array

Recipe #1: compute the total number of neighbors

 Start k threads, each element of Q_{BFS} is assigned to one thread

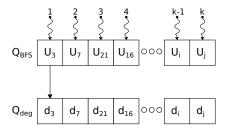


 Build Q_{deg}, substituting each vertex with its degree

 Perform a prefix-sum operation on Q_{deg} to build the New Offset array

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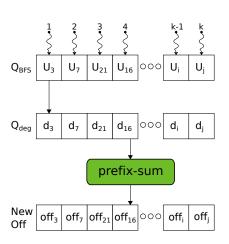
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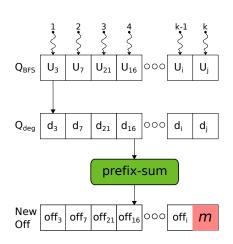


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The last element of **New Offset** is: $m = \sum_{i \in Q_{BFS}} d_i$

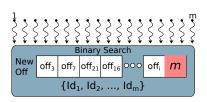
Recipe #2: build a contiguos array of neighbors

- Start m threads
- Each thread performs a binary search on New Offset and finds its index
- Each thread reads from the Adj list the element corresponding to the index
- and write it in the Next Level Frontier.



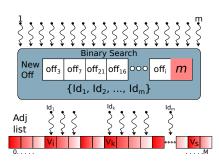
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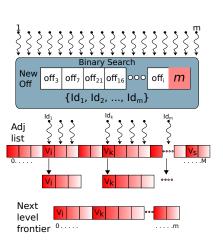
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Recipe #3: prune the Next Level Frontier

• Start *m* threads



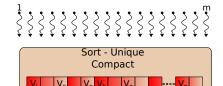
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 and compact it to n unique elements

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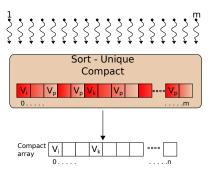
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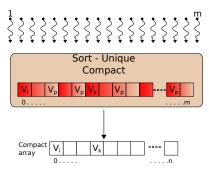


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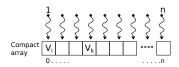
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• Unique ratio $\frac{m}{n} \sim 20$

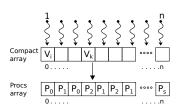
Recipe #4: Exchange vertices and update the parent array



- Substitute vertices with tasks
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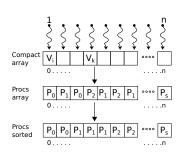
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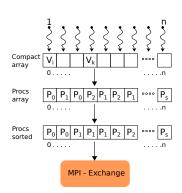
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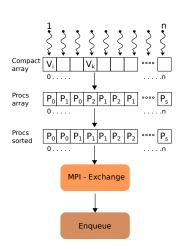
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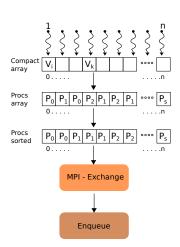
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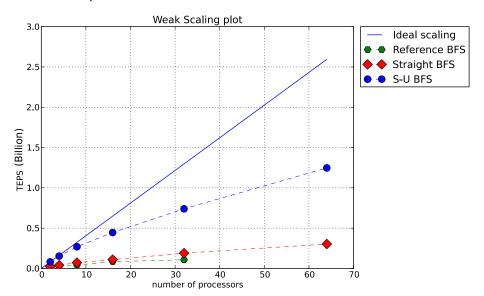
- Substitute vertices with tasks
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- Exchange non-local edges
- Update the array of predecessors and Enqueue
 - If $Q_{BES} == 0$ quit.



Outline

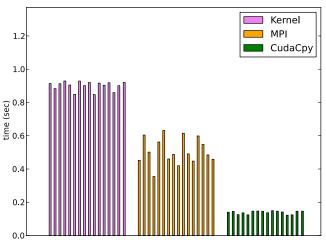
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Sort-Uniq BFS: Results



K2: balancing

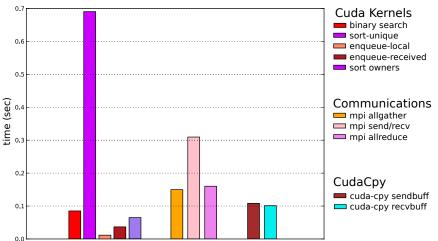
Cumulative running time, 16 processors



Computations and communications among processes are well balanced

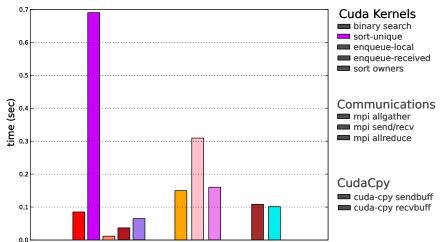
K2: cuda kernels times

Sum of running time over bfs levels, proc 0 of 64



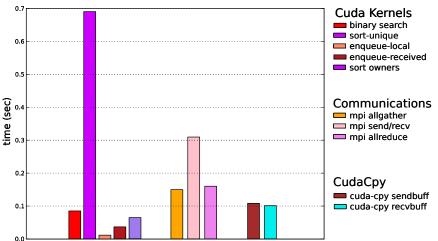
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The Graph 500 List

November 2011 | June 2011 | November 2010

Complete Results - November 2011

	p.ococou.co				
Rank	Machine	Owner	Problem Size	TEPS	Implementation
1	NNSA/SC Blue Gene/Q Prototype II (4096 nodes / 65,536 cores)	NNSA and IBM Research, T.J. Watson	32	254,349,000,000	Custom
2	Hopper (1800 nodes / 43,200 cores)	LBL	37	113,368,000,000	Custom
2	Lomonosov (4096 nodes / 32,768 cores)	Moscow State University	37	103,251,000,000	Custom
3	TSUBAME (2732 processors / 1366 nodes / 16,392 CPU cores)	GSIC Center, Tokyo Institute of Technology	36	100,366,000,000	Custom
4	Jugene (65,536 nodes)	Forschungszentrum Jülich	37	92,876,900,000	Custom

18	Blacklight (512 processors)	PSC	32 (Small)	4,452,270,000	Custom
19	Todi (176 AMD Interlagos, 176 NVIDIA Tesla X2090)	CSCS	28	3,059,970,000	Custom GPU Result
20	Dingus (Convey HC-1ex 1 node / 4 cores, 4 FPGAs)	SNL	28	1,758,682,718	Convey Custom

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Conclusions and Outlook

- To visit large graphs we need a distributed algorithm
- We are slower on a single GPU
- We relay on sorting to achieve better scaling
- If we can speed-up the sorting then we will speed up the BFS

- D. Chakrabarti, D. Chakrabarti, Y. Zhan, and C. Faloutsos. R-mat: A recursive model for graph mining. *IN SDM*. 2004.
 - A. G. Duane Merrill, Michael Garland. High performance and scalable gpu graph traversal. Technical report, Nvidia, 2011.
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 Accelerating large graph algorithms on the gpu using cuda, 2007.
- J. Leskovec, D. Chakrabarti, J. Kleinberg, C. Faloutsos, and Z. Ghahramani. Kronecker graphs: An approach to modeling networks.
 - J. Mach. Learn. Res., 11:985-1042, March 2010.
- R. Murphy and G. Chukkapalli.
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 Technical report, Oracle.

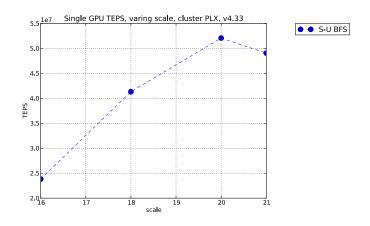


P. of the 16th ACM symposium on Principles and practice of parallel programming, editors.

Accelerating CUDA Graph Algorithms at Maximum Warp, 2011.

[5] [1, 4] [3, 6, 2]

Single GPU with the multi-GPUs code



Random Graph

Unique ratio example

```
2 0.28 2 0.47 2 0.18
3 0.16 3 0.15 3 0.21
4 0.77 4 0.50 4 0.97
5 1.00 5 1.00 5 1.00
6 1.00 6 1.00 6 1.00
7 1.00
```

Table: Unique ratio, proc 0 of 64, 3 run of BFS