

Implementation of Reynolds Equation Solver on GPGPU for Gas Film Lubrication Problem



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Problem overview

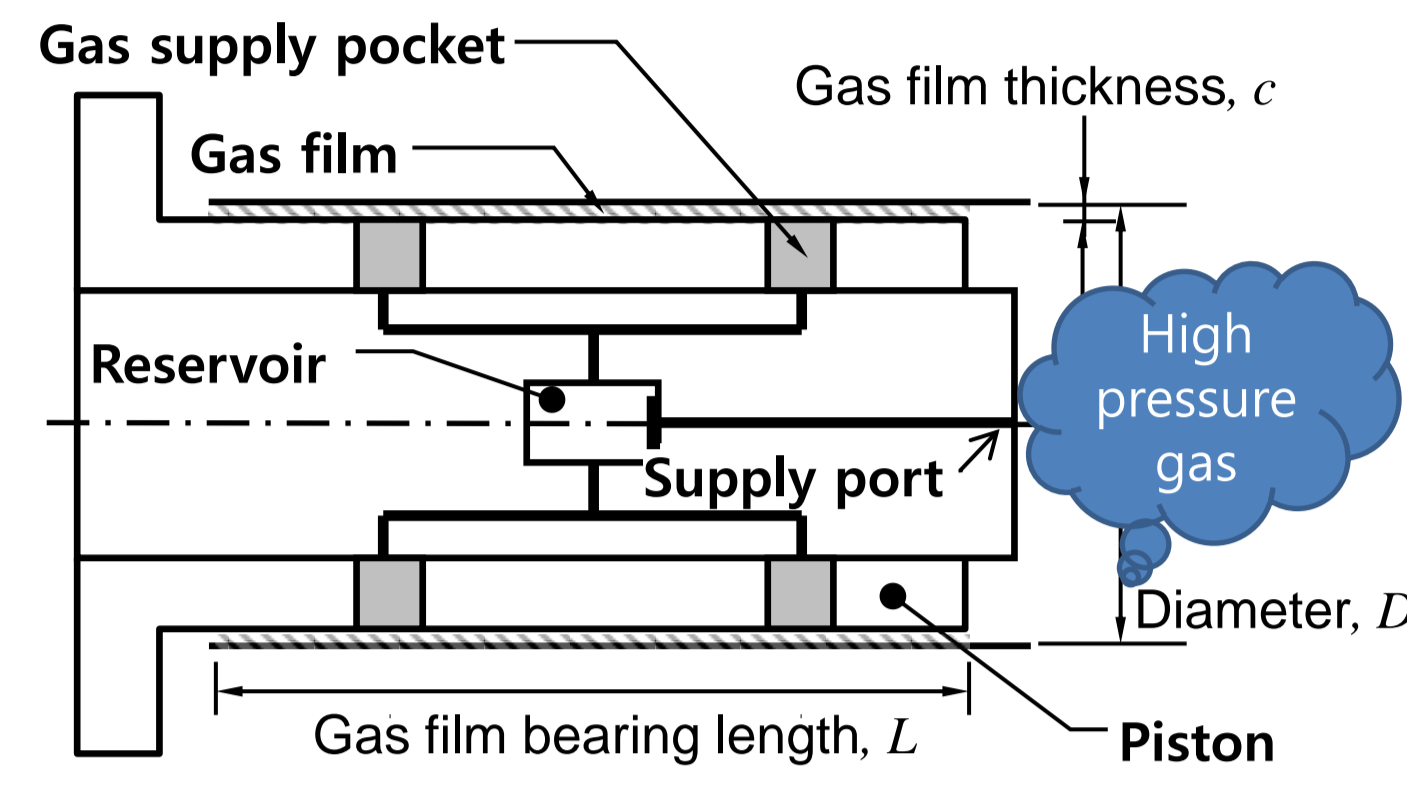
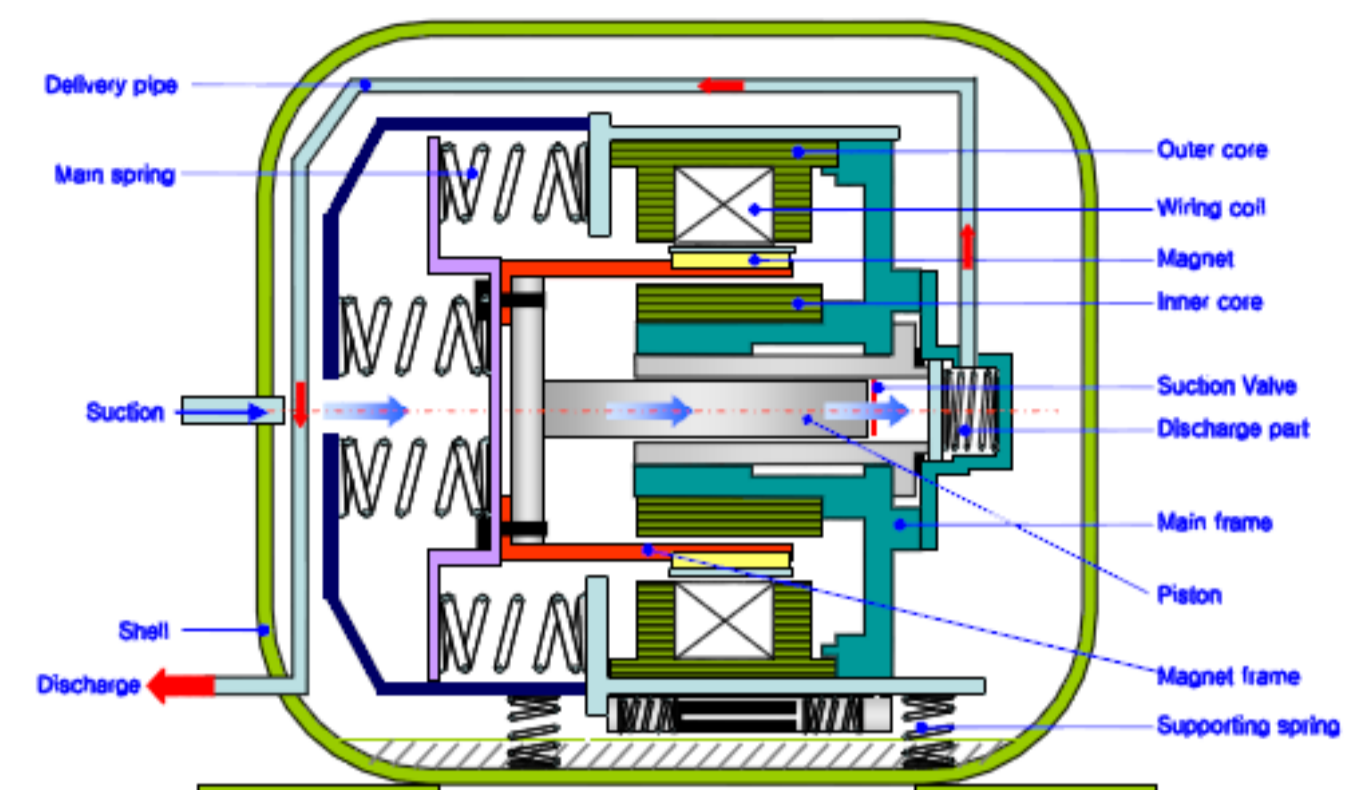


Figure of linear compressor
H. Lee, et al., ICSV15 (2008)

Schematic diagram of piston and gas film bearing

Gas film bearing in linear compressor

- One of key components in linear compressor
- Supporting the piston in reciprocating motion
- Having gas supply pocket/port for high pressure gas supply
- Generating supporting pressure using high pressure gas

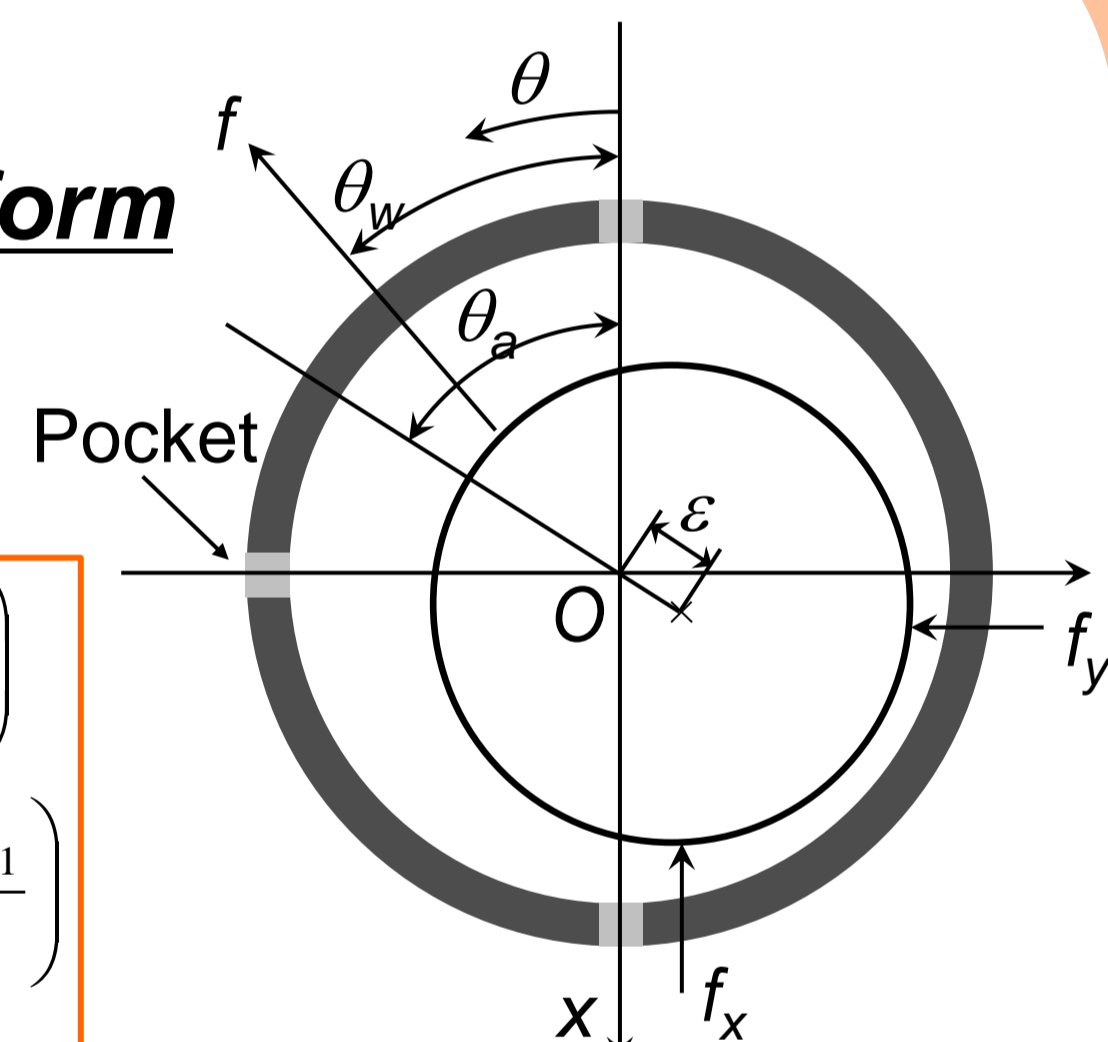
Formulation

Reynolds equation and discretized form

$$\frac{\partial}{\partial Z} \left(PH^3 \frac{\partial P}{\partial Z} \right) + \frac{\partial}{\partial \theta} \left(PH^3 \frac{\partial P}{\partial \theta} \right) = \Lambda \frac{\partial PH}{\partial Z} + \Gamma \frac{\partial PH}{\partial \tau}$$

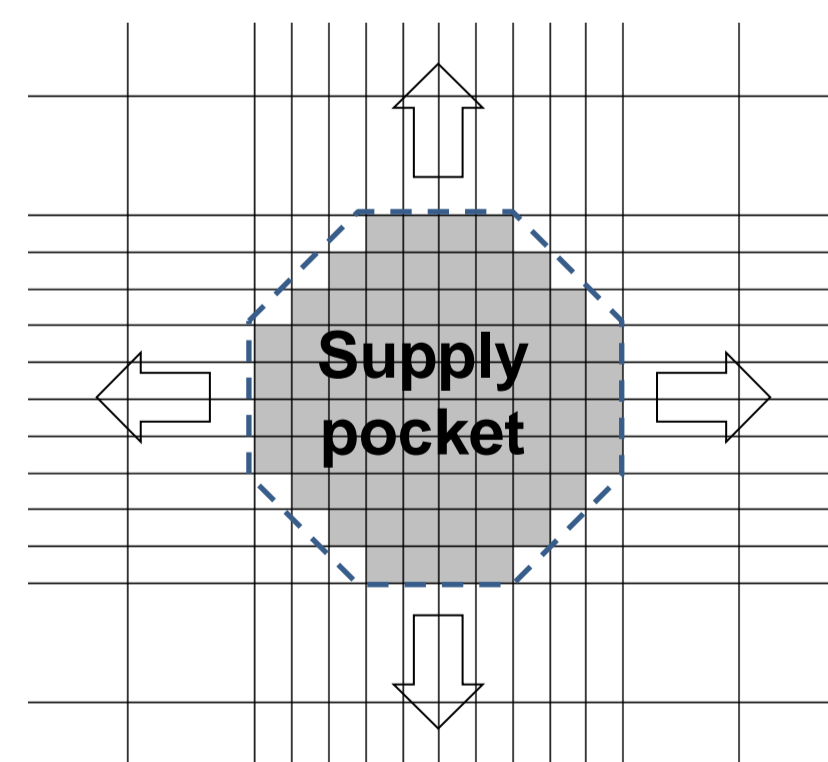
$$\frac{1}{\Delta Z} \left(P_{i+1/2,j} H_{i+1/2,j}^3 \frac{P_{i+1,j} - P_{i,j}}{\Delta Z} - P_{i-1/2,j} H_{i-1/2,j}^3 \frac{P_{i,j} - P_{i-1,j}}{\Delta Z} \right) + \frac{1}{\Delta \theta} \left(P_{i,j+1/2} H_{i,j+1/2}^3 \frac{P_{i,j+1} - P_{i,j}}{\Delta \theta} - P_{i,j-1/2} H_{i,j-1/2}^3 \frac{P_{i,j} - P_{i,j-1}}{\Delta \theta} \right) = \Lambda \frac{P_{i+1/2,j} H_{i+1/2,j} - P_{i-1/2,j} H_{i-1/2,j}}{\Delta Z} + \Gamma \frac{P_{i,j}^n - P_{i,j}^{n-1}}{\Delta \tau}$$

$$H = \frac{h}{c} = 1 + \varepsilon \cos(\theta - \theta_a)$$

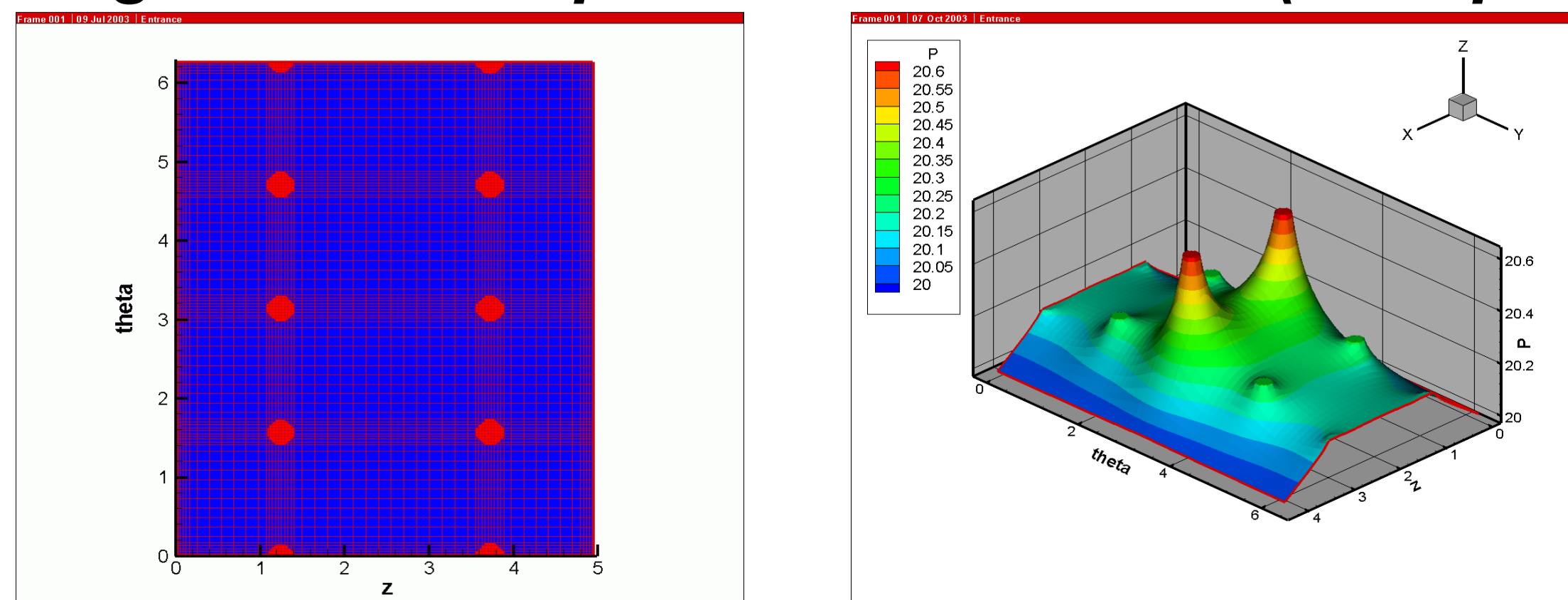


Boundary condition

- ▶ Bearing ends $P(\theta, 0) = P(\theta, L) = P_0$
- ▶ Periodicity $P(0, z) = P(2\pi, z)$
- ▶ Mass continuity at supply pocket
- ▶ Capillary restrictor



Bearing surface and pressure distribution (example)



Implementation on GPGPU

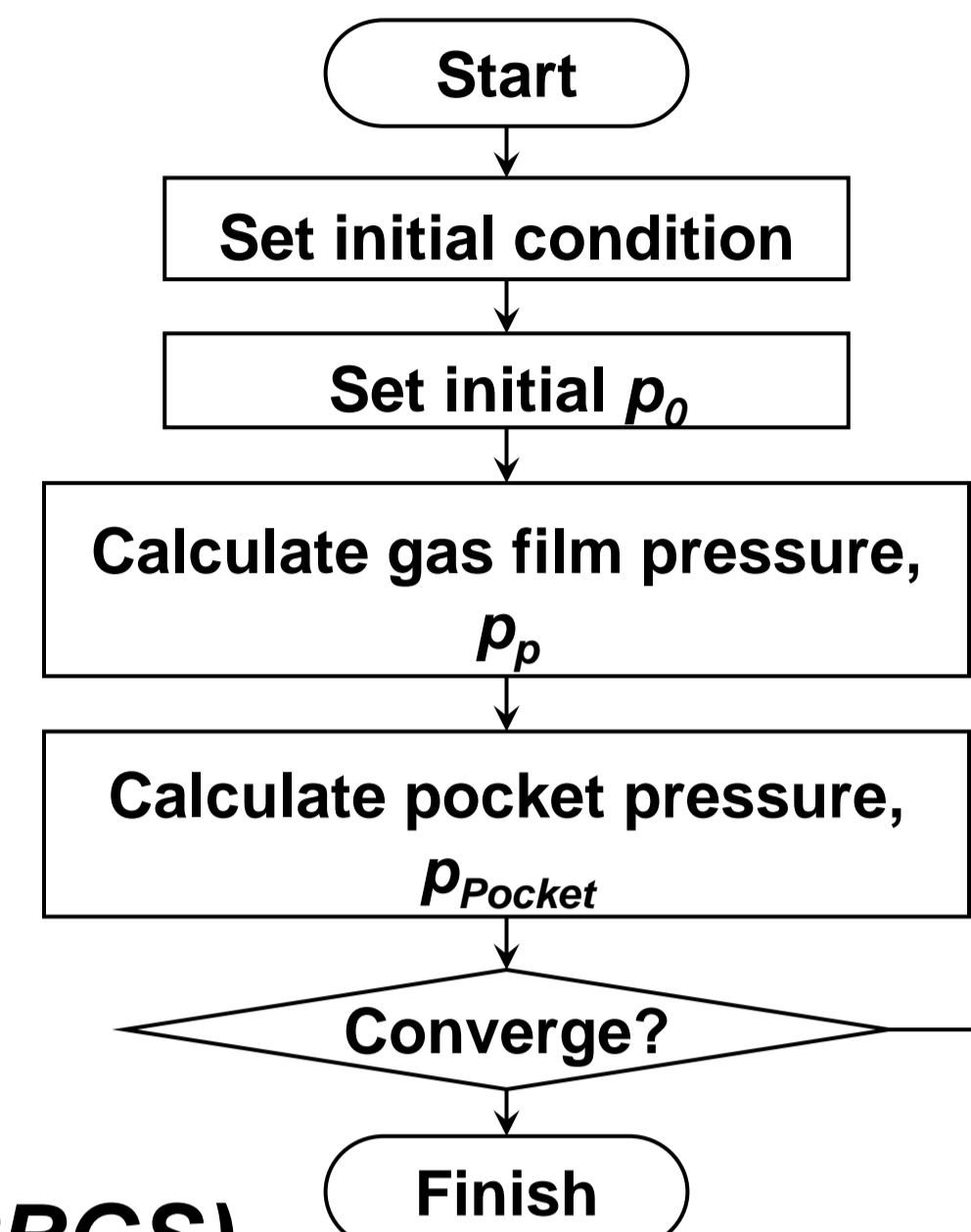
Gauss-Siedel iteration

- ▶ Reynolds eqn. for gas film pressure

$$a_P P_P = a_E P_E + a_W P_W + a_N P_N + a_S P_S + b P_P^{(n-1)}$$

- ▶ Mass continuity eqn. for pocket pressure

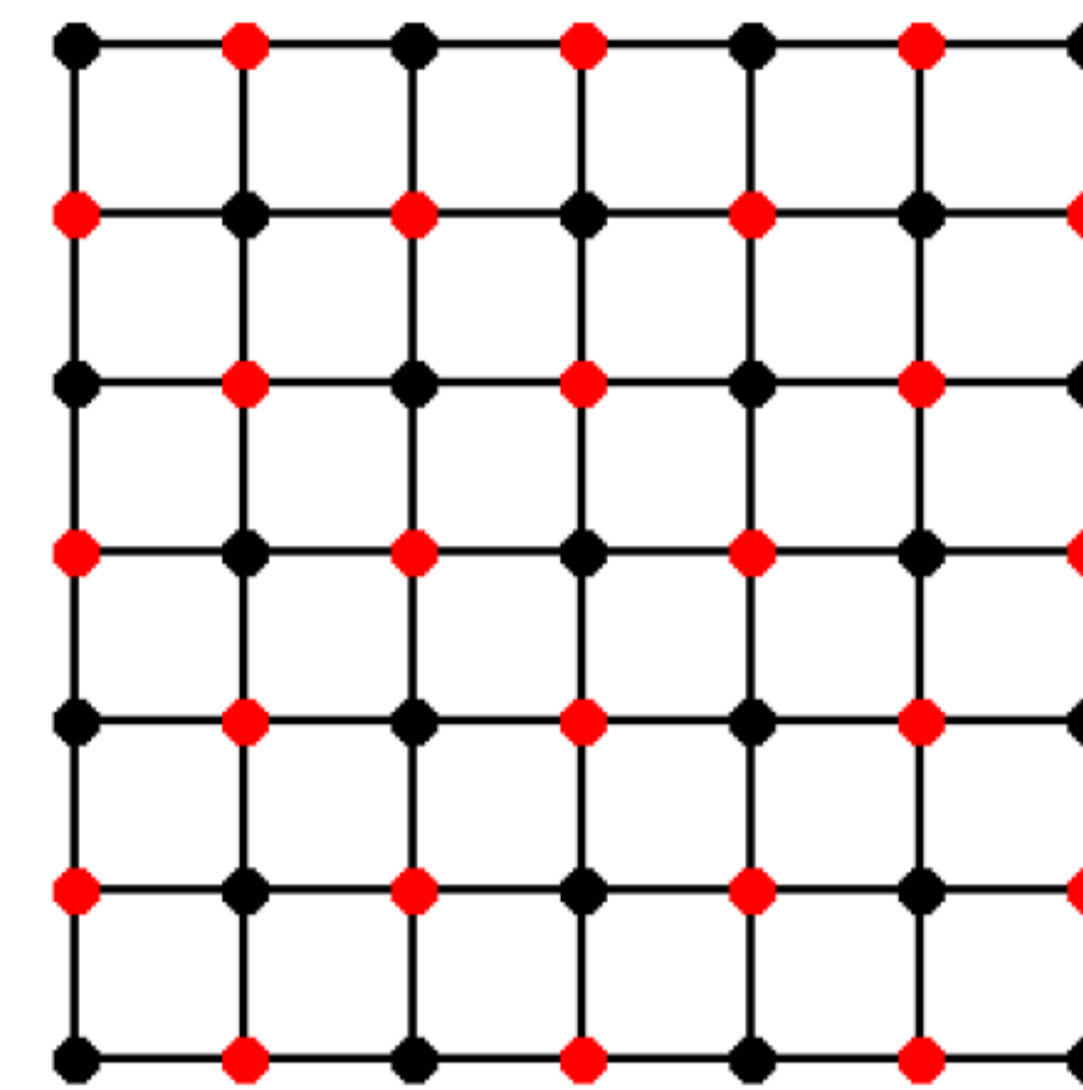
$$\sum_{\text{faces}} a_P P_{\text{Pocket}} = \sum_{\text{faces}} (a_E P_E + a_W P_W + a_N P_N + a_S P_S + b P_{\text{Pocket}}^{(n-1)}) + A_{\text{Supply}} P_{\text{Supply}}$$



Red/Black Gauss-Siedel iteration (RBGS)

In iteration n:

- ▶ **1st pass**
All red nodes are updated using old values of black nodes.
 - ▶ **2nd pass**
All black nodes are updated using updated values of red nodes
- No data dependency among nodes of same colors
→ the nodes can be assigned to each thread and updated in parallel within each pass



- ▶ Assign each z node to each thread and each theta node to each block

// Red/Black Gauss-Siedel iterative pressure solver structure

```
void Pressure_CUDA::iterate(){
    int redblack;
    unsigned int threads = NzNode;
    unsigned int blocks = NthNode;
    do{
        redblack = 0; //1st pass
        iteratePressure_kernel<<<blocks, threads, Mem_size>>>(d_MeshType,...,redblack);
        cutilSafeCall(cudaMemcpy(err,d_err, sizeof(double)*blocks, cudaMemcpyDeviceToHost));
        for(i=0;i<blocks;i++) { error+=err[i]; } // Error summation

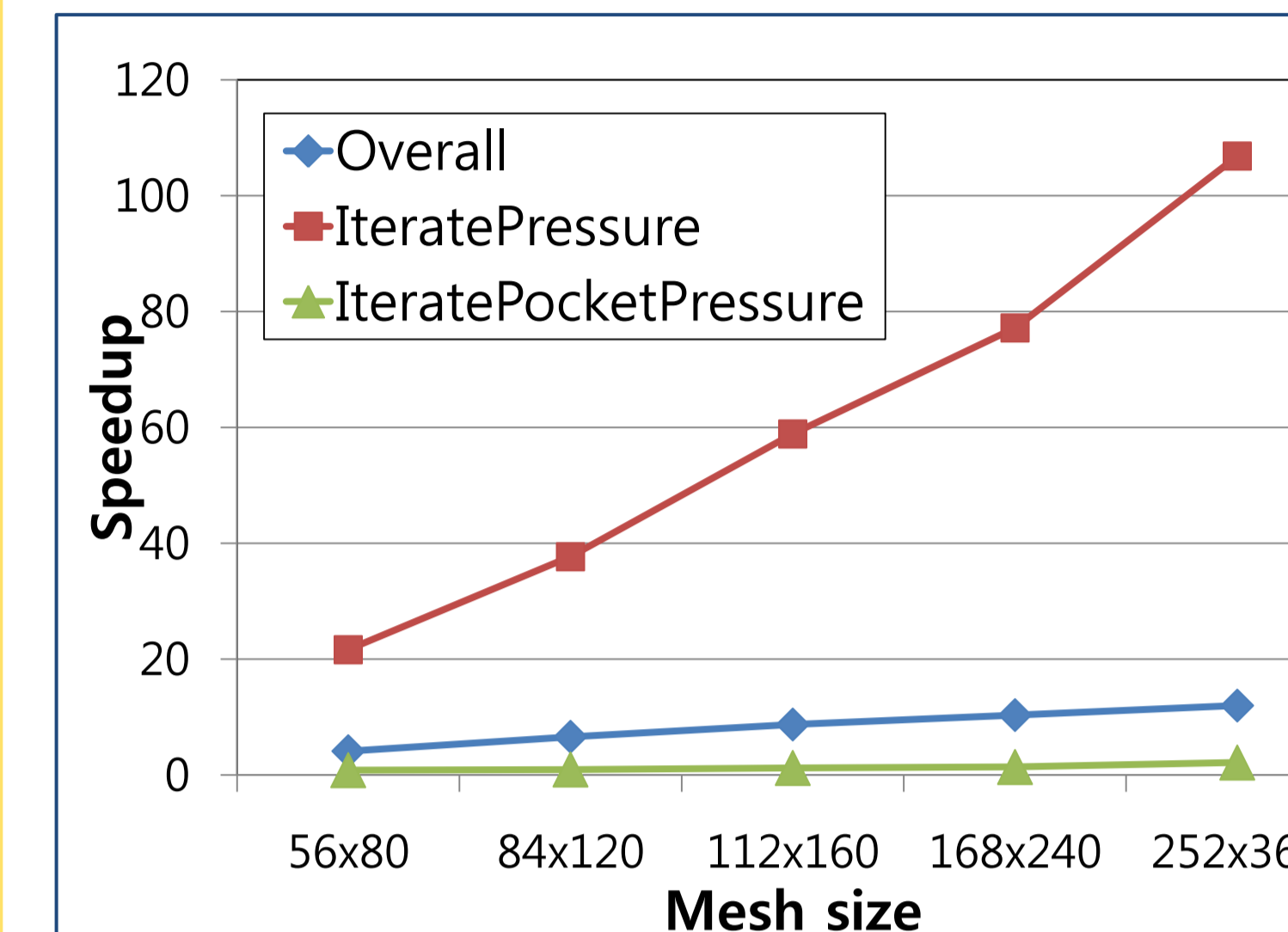
        redblack = 1; //2nd pass
        iteratePressure_kernel<<<blocks, threads, Mem_size>>>(d_MeshType,...,redblack);
        cutilSafeCall(cudaMemcpy(err,d_err, sizeof(double)*blocks, cudaMemcpyDeviceToHost));
        for(i=0;i<blocks;i++) { error+=err[i]; } // Error summation
    }while(error>criteria);
}
```

// Computational kernel structure

```
__global__ void iteratePressure_kernel(int *d_MeshType, ..., int redblack ) {
    int iidx = threadIdx.x;
    int jidx = blockIdx.x;
    if(((iidx+jidx)&1) == redblack && d_MeshType[jidx*const_NzNode+iidx]==-1) {
        // ... Coefficient calculation
        aP=aE+aW+aN+aS+Fe-Fw+b;
        d_dP[jidx*const_NzNode+iidx]=(aE*PE+aW*PW+aN*PN+aS*PS+b*oldPP)/aP-PP;
        d_P[jidx*const_NzNode+iidx] +=0.4*d_dP[jidx*const_NzNode+iidx];
        // ... Error calculation
    }
    double_reduction( error, d_err);
}
```

Results

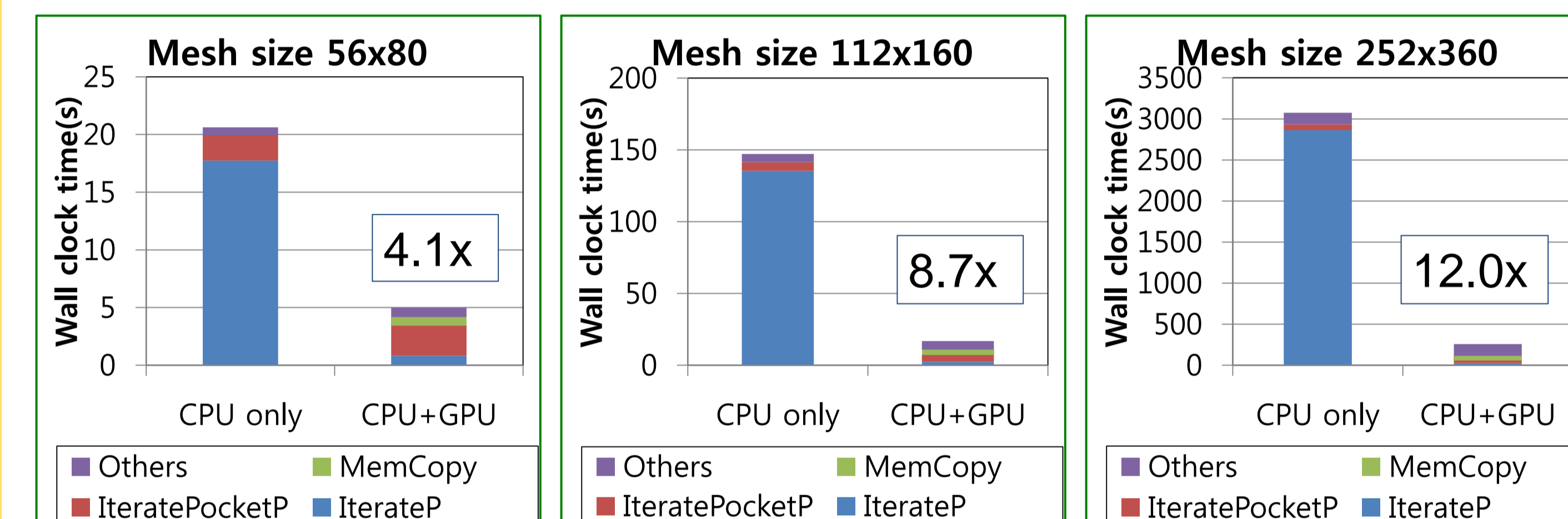
GPU speedup



- ❖ Overall speedup
 - ▶ Increase with mesh size
 - ▶ Achieved 12X at 252x360 (Limit: 21X by Amahl's law)
 - ▶ Org. code serial part: 3~4.5%
- ❖ IteratePressure
 - ▶ Excellent parallel speedup
 - ▶ Achieved 106X at 252x360 (Theoretical limit: 140X from clock speed))
- ❖ IteratePocketPressure
 - ▶ Poor parallel speedup
 - ▶ Small and fixed pocket mesh size

CPU : AMD Llano A8-3850, 2.9GHz
GPU : GTX 580, 795MHz, 512 threads

Wall clock time comparison



Mesh	CPU/GPU	Loop (s)	IterateP(s)	ItrPocketP(s)	MemCp(s)	Others(s)
56x80	CPU	20.6	17.7 (86%)	2.2 (11%)	-	0.7 (3%)
	CPU+GPU	5.0	0.8 (16%)	2.6 (52%)	0.8(15%)	0.8 (16%)
112x160	CPU	147.2	135.4 (92%)	6.0 (4%)	-	5.7 (4%)
	CPU+GPU	16.9	2.3 (14%)	4.9 (29%)	3.7(22%)	6.0 (36%)
252x360	CPU	3074.5	2861.6(93%)	72.2 (2%)	-	140.6 (5%)
	CPU+GPU	256.2	26.8 (10%)	33.4 (13%)	54.1(21%)	141.9 (55%)

- ▶ A small serial part becomes a critical bottleneck as the problem size gets bigger and GPU speedup increases.
- ▶ Not only core calculation part but also general calculation part needs to be parallelized for better speedup.

Conclusion & Future work

- Implemented a Reynolds equation solver on GPGPU for gas film lubrication problem.
- Achieved 106x speedup for core calculation part and overall 12x speedup (DP) using RBGS, relative to 1core of AMD Llano A8-3850.
- A tiny serial part can become a critical bottleneck as the problem size gets bigger and GPU efficiency increases.
- Future work will include the development of general gas film analysis solver and the development of parallelization scheme for remaining serial part, such as integration, error check, and et al.